

# ESPrtk 3.9.8.9

## Datasheet

### Ver 1.8.9 – BETA



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*Status release : Update release.*

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# Release and revision version

Rev	Date	Firmware	Detail
V1.0	4/2/2020	3.0.0	First Release
V1.2	8/3/2020	3.2.0	1. Add support Deep Sleep mode ( Hardware Control mode)
V1.2	2/4/2020	3.2.5	1. WiFi Radio Range up to 2Km
V1.3 + V1.4	11/7/2020 4/7/2020	3.8.0 3.9.0	<ol style="list-style-type: none"> <li>1. Change GPIO pin name.</li> <li>2. Support UART_Base_to_UART_Rover mode .</li> <li>3. New support GSM Cellular 2G 3G 4G LTE .</li> <li>4. New support Ethernet module.</li> <li>5. More support other action for Rover Repeater mode.</li> <li>6. Changed Read/Write configure of ACTION_PLANNING ,INTERNET , NTRIP_CLIENT , MQTT_RTK with more support.</li> <li>7. Add new Read/Write configure for INTERNET , ACTION_PLANNING ,GSM_CELLULAR , STREAM_MANAGER , POSITION_ANTENNA.</li> <li>8. Hardware Control : Support W5XX for ‘Control WIFI and Ethernet module connect to router’</li> </ol>
V1.5	31/7/2020	3.9.0 +3.9.2	1. Correct circuit diagram and power voltage for Neopixel LED.
V1.6 V1.7	16/7/2020 17/7/2020	3.9.5 3.9.5	<ol style="list-style-type: none"> <li>1. Changed Read/Write configure of YOUR_PROFILE (for support change CSS theme of WEB Configure interface).</li> <li>2. Support view NMEA/GGA for “No Main Action” mode.</li> <li>3. Hardware Control : Correct Command for Bluetooth Read String+Hex.</li> </ol>
V1.8	16/10/2020	3.9.8	<ol style="list-style-type: none"> <li>1. Changed Read/Write configure of ACTION_PLANNING with more support.</li> <li>2. Hardware Control mode: Support Auto calibrate magnetometer by command .</li> <li>3. Web Configure mode : Support Auto calibrate magnetometer using Sensor or Text field as input data.</li> <li>4. Main Action mode: Support send IMU data to Bluetooth device .</li> </ol>
V1.82	17/12/2020	3.9.82	<ol style="list-style-type: none"> <li>1. Changed Read/Write configure of ACTION_PLANNING and POSITION_ANTENNA with more support.</li> <li>2. Add new Read/Write configure for WIFI_TCP_UDP .</li> <li>3. Support Send IMU_1/IMU_2 Data to WiFi TCP/UDP device .</li> <li>4. Support Send RX-UART-RTK data to WiFi TCP/UDP device.</li> <li>5. Support Respond realtime command control on RX-Bluetooth device .</li> <li>6. Support Respond realtime command control on WiFi TCP/UDP device.</li> <li>7. Stable IMU data at high speed.</li> <li>8. WiFi TCP/UDP support : (TCP Server AP - TCP Server STA - TCP Client STA - UDP Server AP - UDP Server STA - UDP Client STA ).</li> </ol>



<b>Rev</b>	<b>Date</b>	<b>Firmware</b>	<b>Detail</b>
V1.87	1/2/2021	3.9.87	<ol style="list-style-type: none"><li>1. Fully Skytraq/Navspark PX1122R support Configure/Query</li><li>2. Add more support Navspark Configure/Query feature.</li><li>3. NTRIP CASTER support.</li><li>4. Changed Read/Write configure of ACTION_PLANNING.</li><li>5. Add new Read/Write configure for NTRIPCASTER_Admin and NTRIPCASTER_ACC .</li></ol>
V1.88	5/3/2021	3.9.88	<ol style="list-style-type: none"><li>1. Supports RTK stream insertion / injection of RTCM messages 1005,1006,1007,1008,1032,1033,1004,1012 .</li><li>2. Changed Read/Write configure of POSITION_ANTENNA.</li></ol>
V1.89	19/3/2021	3.9.89	<ol style="list-style-type: none"><li>1. Add new feature UART_to_WIFI_Bridge for Main Action.</li><li>2. Changed Read/Write configure of ACTION_PLANNING.</li></ol>

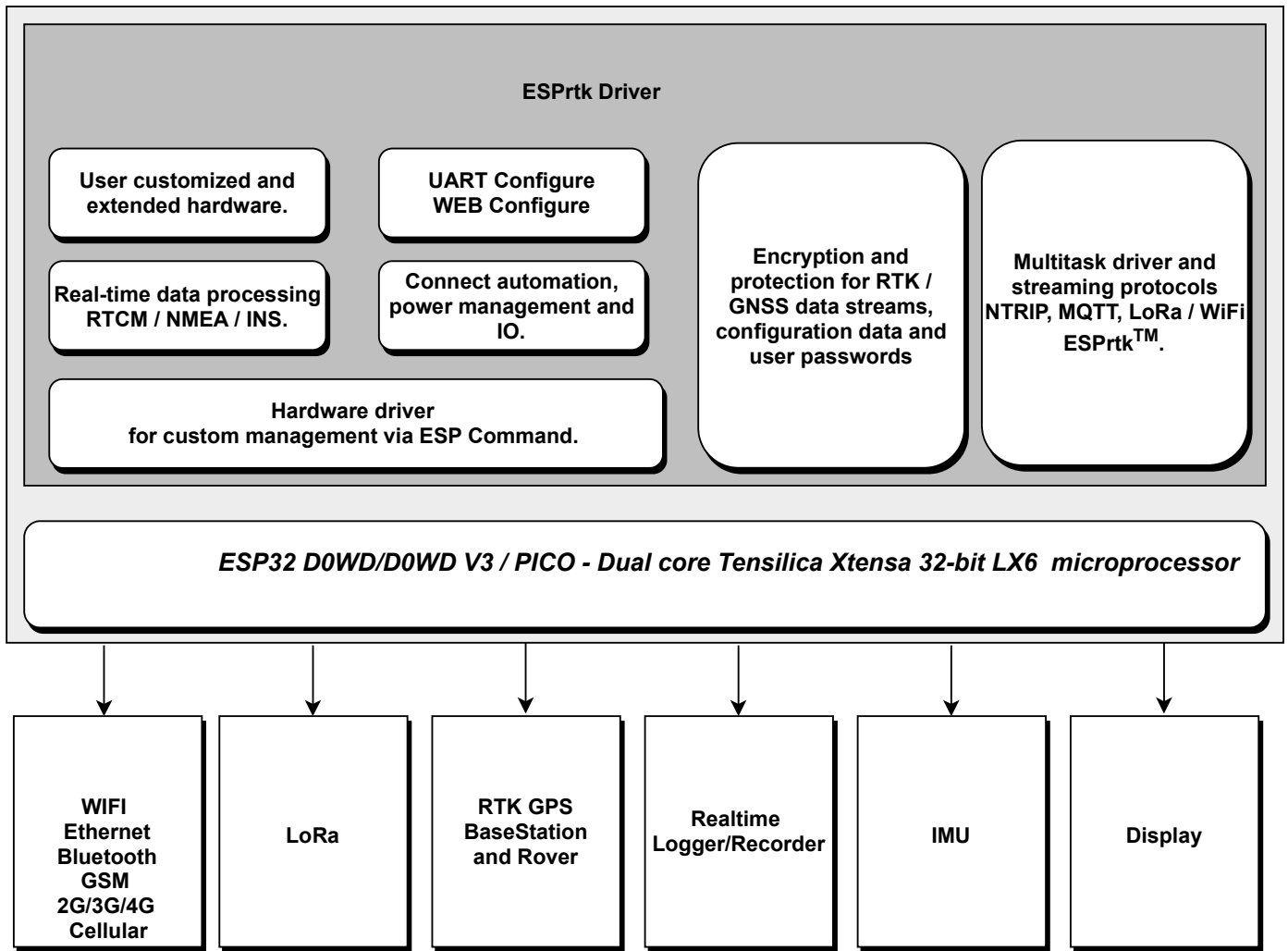


## GENERAL DESCRIPTION

- ESPrtk module used to transmit wireless GNSS data in high precision positioning applications.
- ESPrtk is geared towards the ability to use high quality, independent, wireless and low cost platforms.
- Users can access and control ESP32 chip internal hardware.
- User update firmware.
- Multi-connection.
- Control and high speed real-time data processing.
- Protect device - Encrypt data.
- Automation of connections .
- Energy / Power / Speed / Hardware / Device manager.

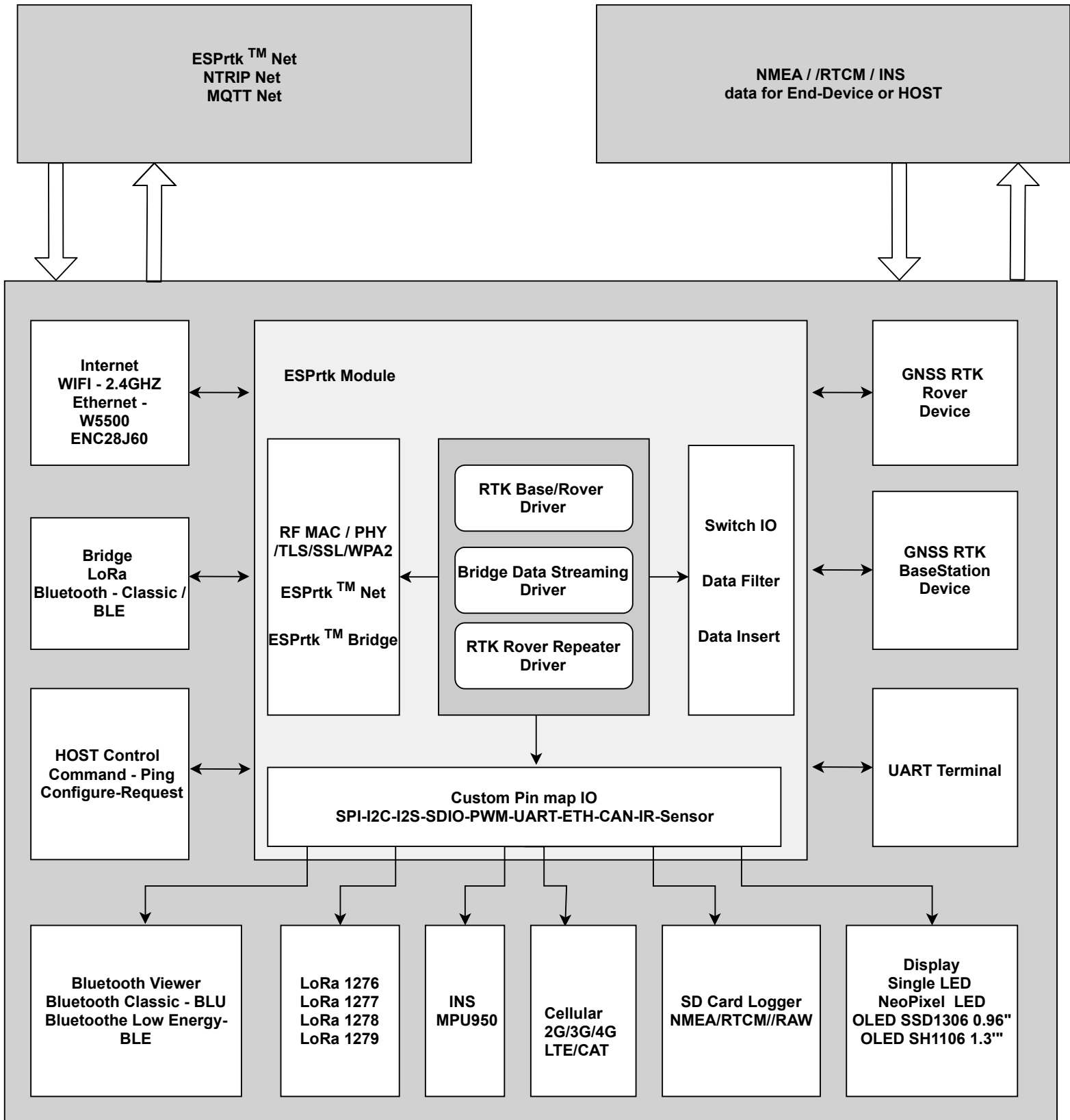
## KEY PRODUCT FEATURES

- MQTT™ - NTRIP CASTER™ - NTRIP™ - RADIO™ – TCP/UDP™ - bridge for RTK position.
- Basestation RTK, Rover RTK.
- RTCM data – NMEA data – UBX data- Skytraq data.
- WIFI - Bluetooth Classic - Bluetooth BLE.
- Ethernet ENC28J60 , W5500, W5xx.
- LoRa 1276/-7/-8/-9 .
- SD Card - OLED Display - IMU MPU9250 - NEOPIXEL led.
- UART Configure – ESPrtk command.
- GSM Cellular 2G/3G/4G LTE/CAT : Quectel ,SimCom, Ublox,Xbee.
- Support SIMCom 2G SIM800 + SIM900 series (SIM800A, SIM800C, SIM800L, SIM800H, SIM808, SIM868 , SIM900A, SIM900D, SIM908, SIM968) .
- Support SIMCom 3G SIMCom WCDMA/HSPA/HSPA+ Modules (SIM5360, SIM5320, SIM5300E, SIM5300E/A) SIMCom LTE Modules (SIM7100E, SIM7500E, SIM7500A, SIM7600C, SIM7600E) SIMCom SIM7000E/A/G CAT-M1/NB-IoT Module
- Support Quectel 3G Quectel BG96 Quectel M95 Quectel MC60
- Support U-blox 2G, 3G, 4G, and LTE Cat1 Cellular Modems (many modules including LEON-G100, LISA-U2xx, SARA-G3xx, SARA-U2xx, TOBY-L2xx, LARA-R2xx, MPC1-L2xx) u-blox LTE-M/NB-IoT Modems (SARA-R4xx, SARA-N4xx, but NOT SARA-N2xx)
- Digi Xbee 2G/3G/4G LTE.
- WEB Configure – UI WEB interface.
- Encrypt : Bitwise, AES , WAP, WAP2. SSL.
- Navspark : NS-HP-BD / -GL / -GN , PX1120R , PX1122R .
- Ublox : NEO , LEA, M8P, F9P, F9K,F9H.
- Hemisphere: Eclipse P307 .
- NVS Technologies:NV08C-RTK .
- Swift : Piksi Multi .





Categories	Items	Specifications
Certification	RF Certification	FCC/CE-RED/IC/TELECOM/KCC/SRRC/NCC
	Wi-Fi Certification	Wi-Fi Alliance
	Bluetooth certification	BQB
	Green Certification	REACH/RoHS
Test	Reliability	HTOL/HTSL/uHAST/TCT/ESD
Wi-Fi	Protocols	802.11 b/g/n (802.11n up to 150 Mbps)
		A-MPDU and A-MSDU aggregation and 0.4 $\mu$ s guard interval support
Bluetooth	Frequency range	2.4 GHz ~ 2.5 GHz
	Protocols	Bluetooth v4.2 BR/EDR and BLE specification
	Radio	NZIF receiver with -97 dBm sensitivity
		Class-1, class-2 and class-3 transmitter
		AFH
Audio	CVSD and SBC	
Hardware	Module interfaces	SD card, UART, SPI, SDIO, I2C, LED PWM, Motor PWM, I2S, IR, pulse counter, GPIO, capacitive touch sensor, ADC, DAC
	On-chip sensor	Hall sensor
	Integrated crista	40 MHz crista
	Integrated SPI flash 1	4 MB
	Operating voltage/Power supply	3.0 V ~ 3.6 V
	Operating current	Average: 80 mA
	Minimum current delivered by power supply	500 mA
	Recommended operating temperature range	-40 °C ~ +85 °C
	Moisture sensitivity level (MSL)	Level 3





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# Overview Introduction

## About ESPrtk

ESPrtk is an abbreviation for ESP32 RTK.

ESPrtk is a small circuit board used to transmit wireless GNSS data in high precision positioning applications.

ESPrtk is geared towards the ability to use high quality, independent, wireless and low cost platforms.

ESPrtk's heart is a powerful ESP32 processor .

ESPrtk is a data bridge, it provides many solutions to deploy network models focusing on GNSS data transmission (such as RAW / RTCM / NMEA) of RTK location applications. Along with that is the maximum exploitation of the hardware power of ESP32 to provide the most powerful and intelligent features..

## Control System

ESPrtk is designed to run Hierarchical Control System (HCS).

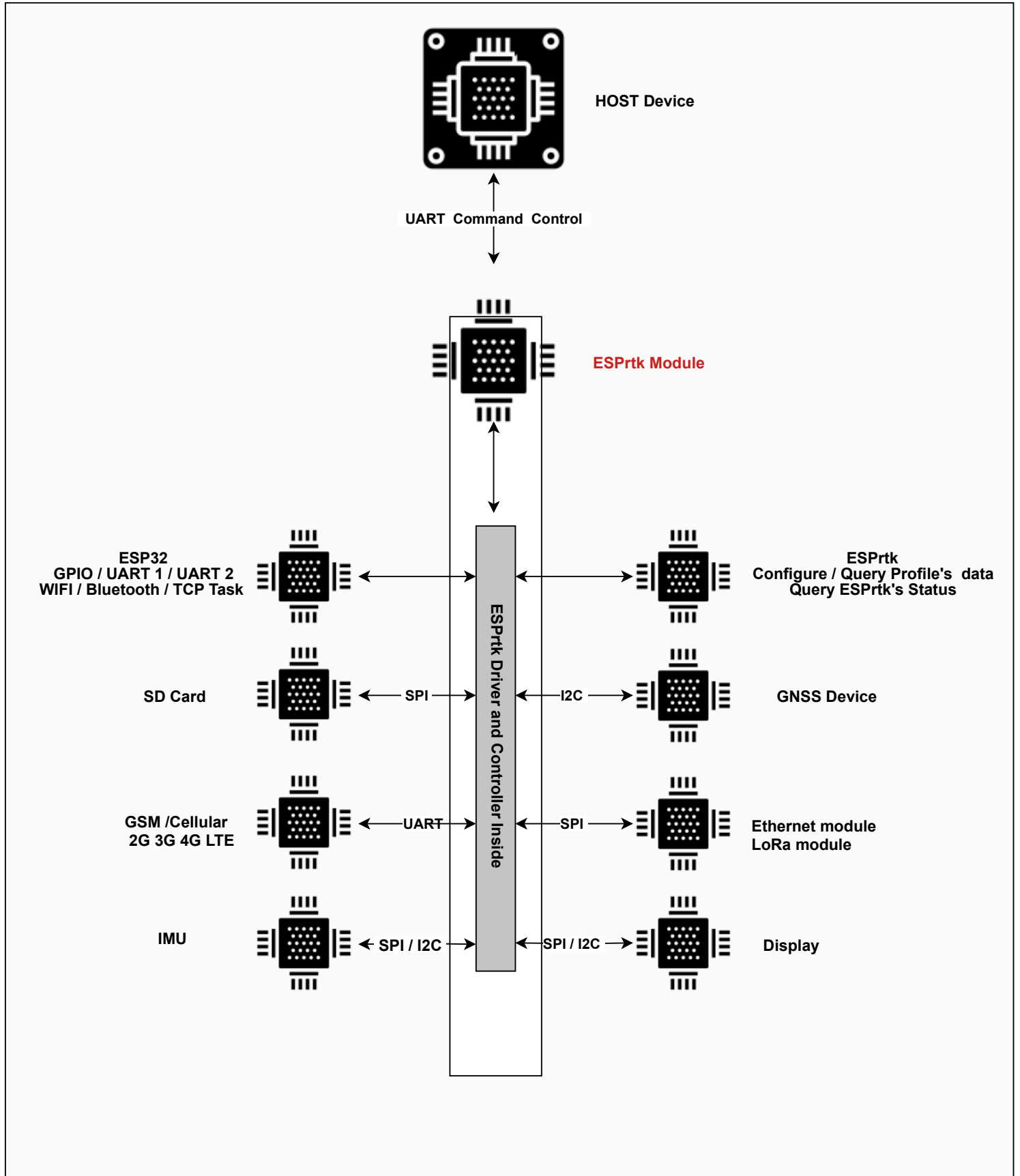
In particular, ESPrtk is a data bridge for GNSS / RTK message transmission, which integrates many programs running in parallel (Driver) to connect to many peripheral devices such as GNSS Receiver, IMU, SD Card, Display, Ethernet ...etc . ESPrtk now is an external controller.

Finally, ESPrtk is controlled, managed and monitored by a higher level control device called HOST . HOST can be a PC or maybe a microcontroller . ESPrtk is now the periphery of HOST.

A special feature of the ESPrtk design is that HOST not only controls ESPrtk, but HOST can also manage and control all peripherals devices connected to ESPrtk such as GNSS Receiver, IMU, SD Card, Display, Ethernet. ..

With this design, ESPrtk will reduce a huge amount of programs running on HOST, making the deployment of RTK systems easier.

The connection between HOST and ESPrtk is done on ESPrtk's UART\_0 port. HOST communicates, configures and controls with ESPrtk (or peripheral) through the exclusive ESPrtk Command (ESP Command).



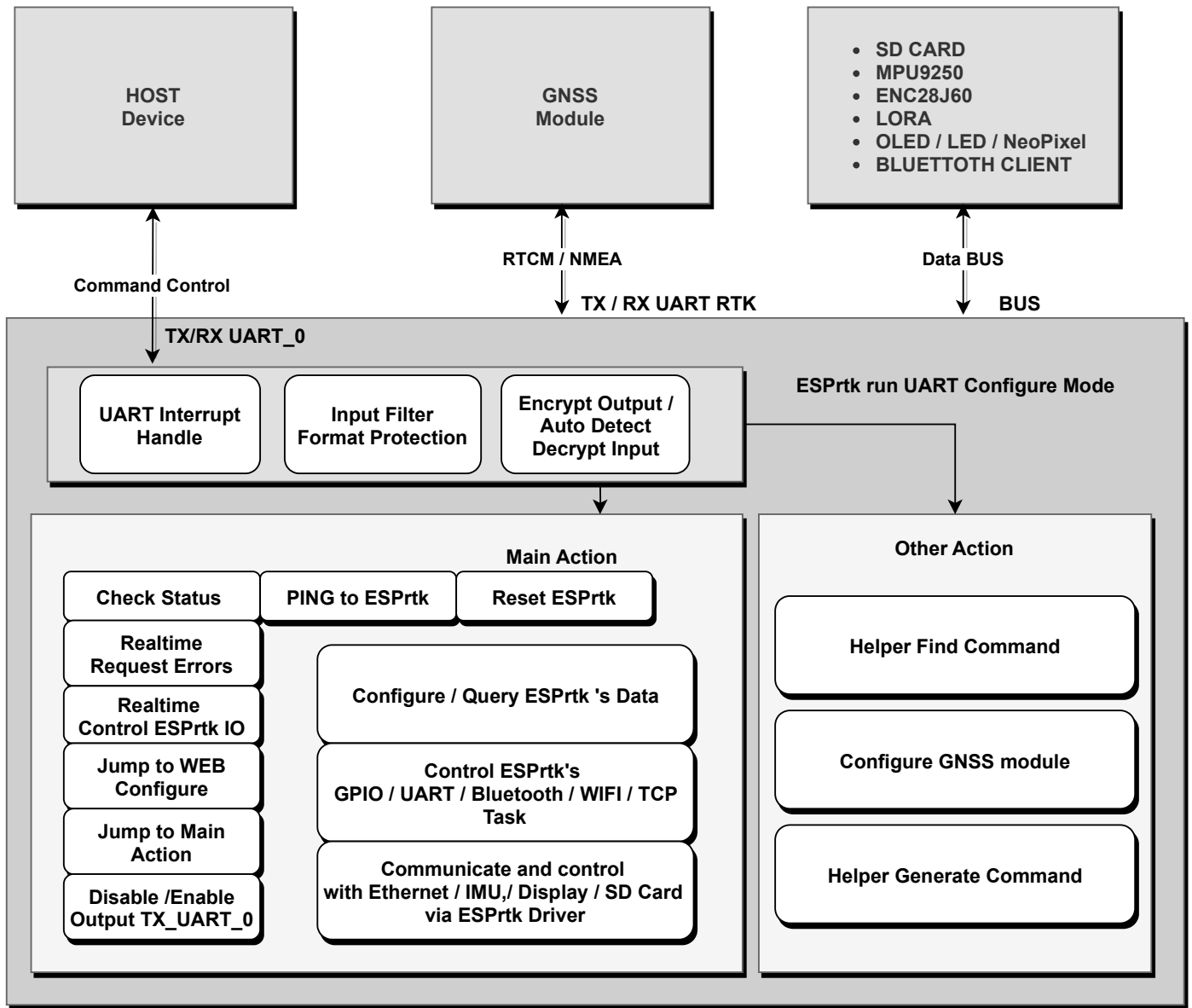


# Actions Mode

ESPrtk Designed around applications related to positioning and collecting RTK data

With 3 different independent operating modes,

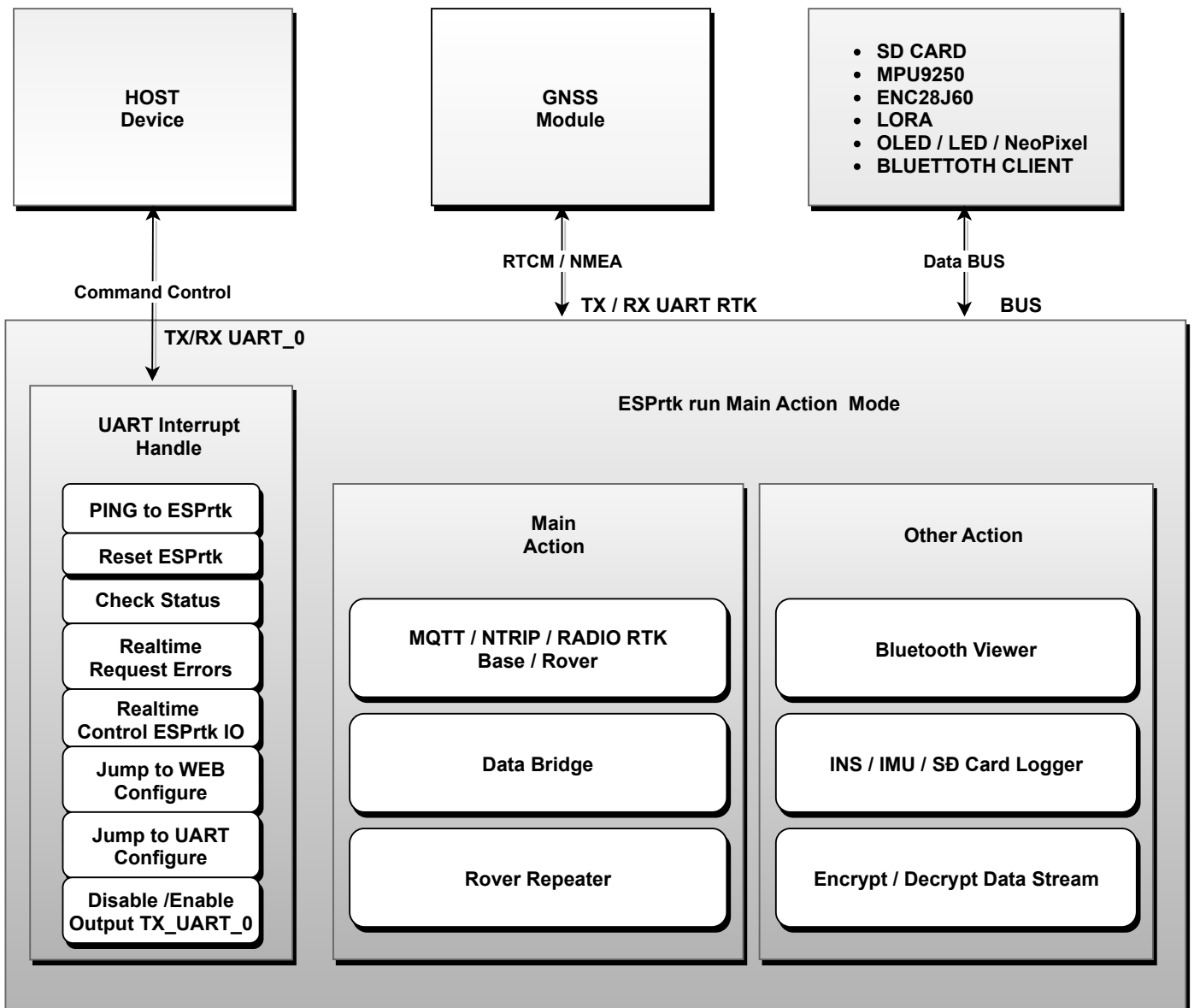
1. **UART Configure Mode** : In this mode, HOST communicates with ESPrtk via UART\_0 port to configure (change settings) on ESPrtk. HOST can also control ESPrtk's hardware features such as controlling IO pins, Bluetooth, WIFI, TCP Task, etc., or controlling other peripheral devices connected to ESPrtk.





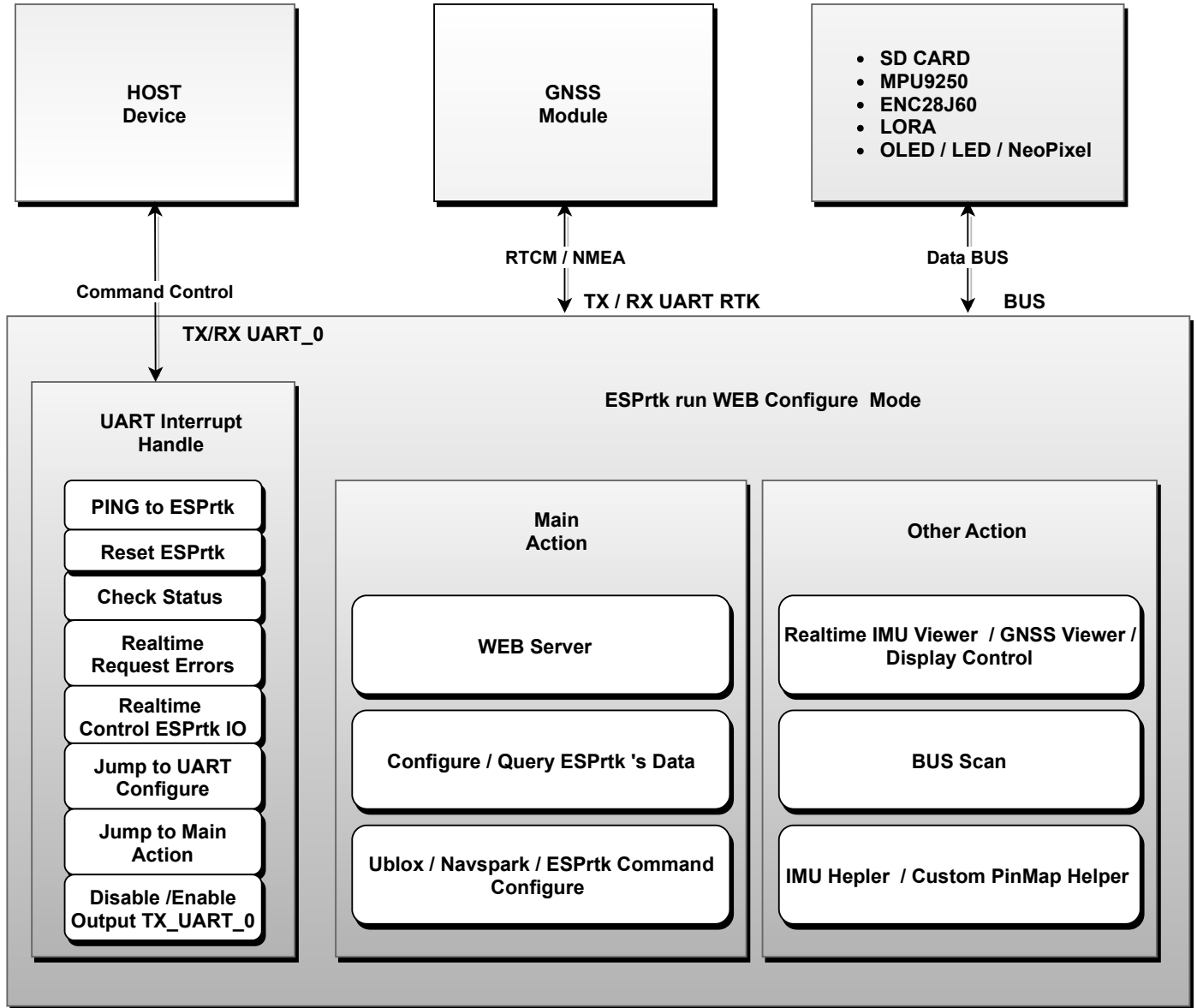
- Main Action Mode:** After configuring ESPrtk, the changed data will be stored in ESPrtk's FLASH memory and they will not be lost during power outages. Once in Main Action mode, ESPrtk reads the boot instructions and performs the main activities planned in advance by the user (via UART Configure or WEB Configure).

Main Action is central mode because most applications that use ESPrtk actually use it.



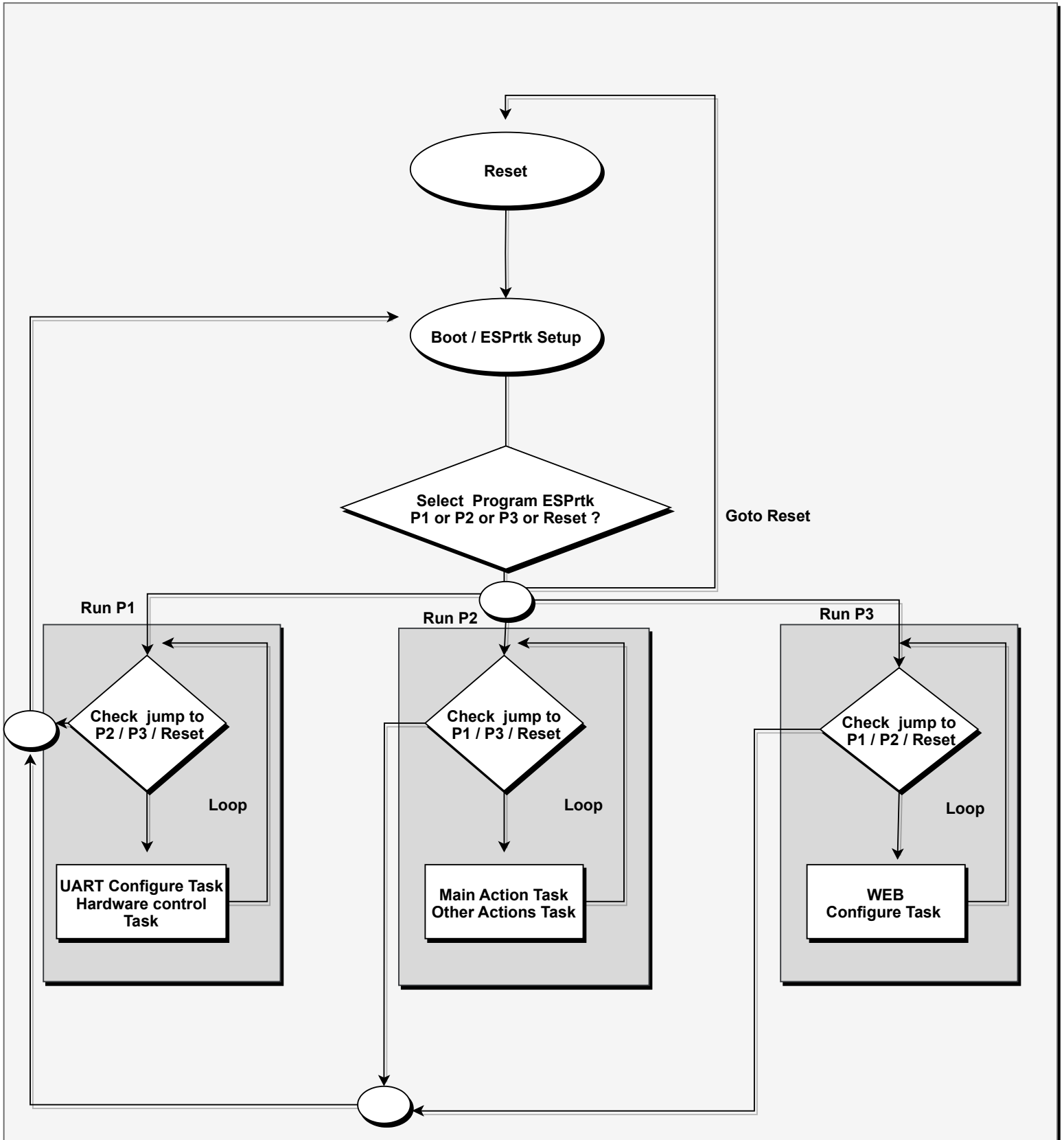


3. **WEB Configure Mode:** In addition to configuring ESPrtk via UART, users can perform ESPrtk configuration via an intuitive WEB UI interface using any WEB browser with a web server run by ESPrtk over a WIFI connection. Along with that are tools that help users connect to peripherals such as GNSS Receiver, IMU, SD, Display ..





The above three operating modes operate independently of each other and HOST can switch between them with a control command at any time while ESPrTk running the program.





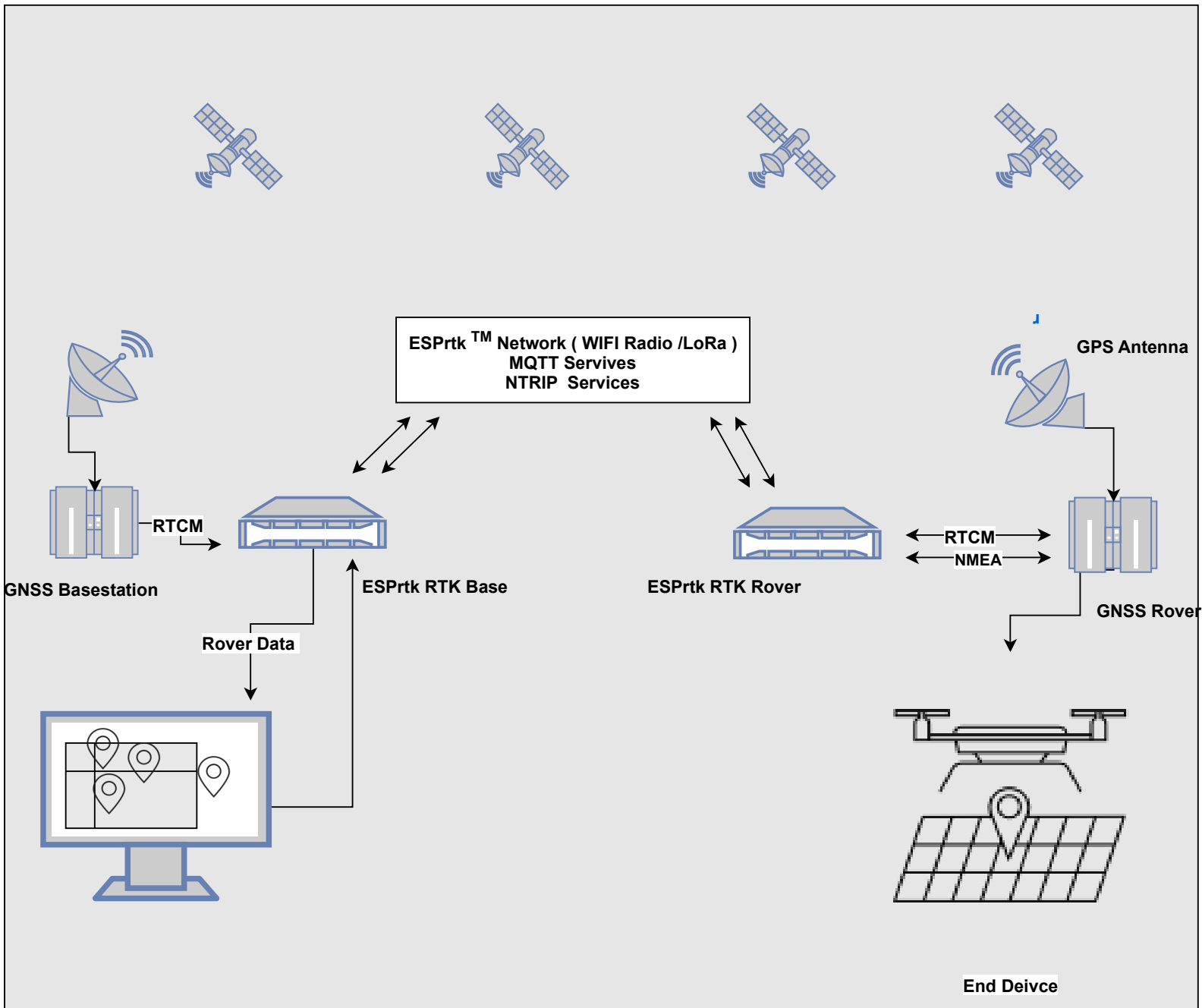
# **ESPrtk Run in Main Action Mode**



## ESPrtk with RTK Position Applications

In RTK positioning, GNSS (Rover) receivers need RAW / RTCM data from other GNSS receivers (BaseStation). In most practical applications, Rover is always on the move and the distance from Rover to BaseStation is large (in kilometers).

ESPrtk is used as a data link bridge between BaseStation and Rover.





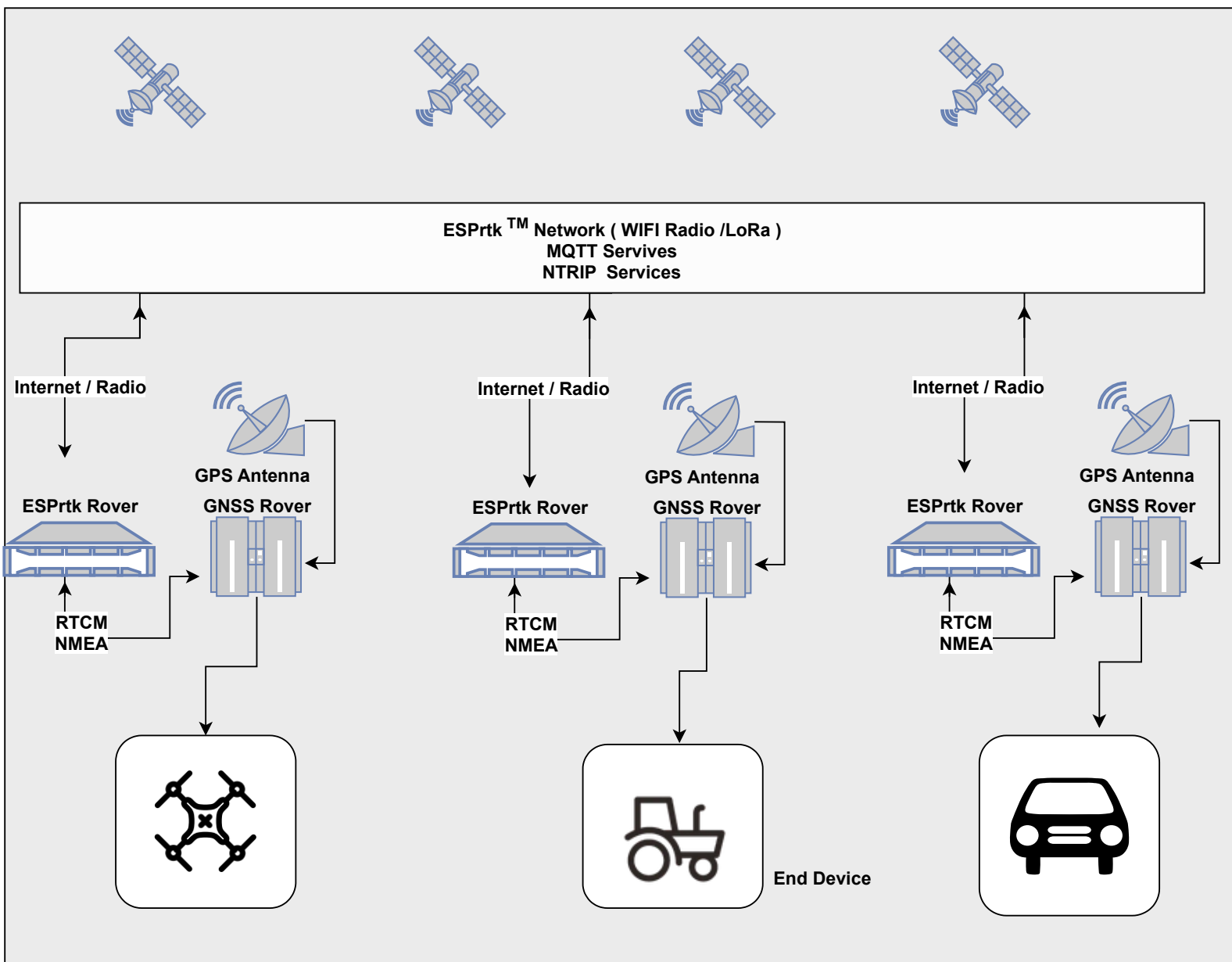
If set to a Base, ESPrtk will collect RTCM / RAW data from one of the UART ports and then send it over the wireless interface to one or more other devices (Rover).

If set to Rover, the data received from the Base will be streamed to the UART port to the RTK module.

There may be more than one Rover using RTCM / RAW data from Base at the same time.

At the same time, ESPrtk Rover can send back NMEA data (such as \$ GPGGA) containing positioning information for ESPrtk Base and will be exported on TX\_UART0 port. HOST devices can manage Rover's location through this feature.

When combined with ESPrtk, the cost of initial investment and system operation will be greatly saved.





ESPrtk applies both types of link: Internet and Radio.

With the Internet, ESPrtk supports two popular types of RTCM transmission protocols, MQTT and NTRIP via WiFi or Ethernet connection. With this type of link, the problem of distance has been solved.

With Radio, ESPrtk uses its own 2.4Ghz WIFI signal (for distances less than 3km) or frequency 443Mhz -> 998Mhz when combining ESPrtk with LoRa module (for distances less than 50km).

## Configure ESPrtk run for RTK Position Application

The full RTK model includes 1 ESPrtk Base and 1 (or more) ESPrtk Rover linked together by MQTT / NTRIP (online) or via Radio link (offline).

When configuring ESPrtk, they will be configured in pairs.

- **MQTT RTK Base** and **MQTT RTK Rover (or MQTT Rover Repeater)** for MQTT link.
- **NTRIP RTK Base** and **NTRIP RTK Rover (or NTRIP Rover Repeater)** for NTRIP link.
- **NTRIP CASTER Server** for NTRIP link.
- **Radio RTK Base** and **Radio RTK Rover** for Radio link.

On version 3.9.8.7, the features are supported as shown in the table below.

Main Action	Detail
<b>MQTT RTK Base</b>	<b>Send data (from RX-UART-RTK) to (MQTT Broker)</b>
<b>MQTT RTK Rover</b>	<b>Export data (from MQTT Broker) to TX-UART-RTK port</b>
<b>NTRIP RTK Base</b>	<b>Send data (from RX-UART-RTK) to (NTRIP Caster)</b>
<b>NTRIP RTK Rover</b>	<b>Export data (from NTRIP Caster) to TX-UART-RTK port</b>
<b>NTRIP CASTER Server</b>	<b>Get RTCM/RAW /.. data from RX-UART-RTK (RX1/RX2) then send to NTRIP Client (Rover).</b>
	<b>Get RTCM/RAW /.. data from NTRIP Server (BaseStation) then send to NTRIP Client (Rover).</b>
<b>Radio RTK Base</b>	<b>Send data (from RX-UART-RTK) to ( RTK Radio_Rover)</b>
<b>Radio RTK Rover</b>	<b>Export data (from RTK Radio_Base) to TX-UART-RTK port</b>



Other Action for RTK Base	MQTT RTK Base	NTRIP RTK Base	Radio RTK Base
Export IMU data to TX_UART_0 port	●	●	●
Send RTCM/RAW/.. data (from RX-UART-RTK) to Bluetooth Client	●	●	●
Save RTCM/RAW/.. data (from RX-UART-RTK) to SD Card	●	●	●
Base-Export NMEA data (from Rovers) to TX_UART_0 port	●	○	●
Base-Priority export NMEA Data from Rovers	●	○	●
Send IMU_1 Data to Bluetooth Client	●	●	●
Send IMU_2 Data to Bluetooth Client	●	●	●
Send Data (from RX-UART-RTK) to WiFi TCP/UDP device	●	●	●
Send IMU_1 Data to WiFi TCP/UDP device	●	●	●
Send IMU_2 Data to WiFi TCP/UDP device	●	●	●
Respond realtime command control on Bluetooth Client	●	●	●
Respond realtime command control on WiFi TCP/UDP	●	●	●

Other Action for RTK Rover	MQTT RTK Rover	NTRIP RTK Rover	Radio RTK Rover
Export IMU Data to TX_UART_0 port	●	●	●
Save NMEA/RTCM Data (from RX-UART-RTK) to SD Card	●	●	●
Send NMEA/RTCM data (from RX-UART-RTK) to Bluetooth Client	●	●	●
Save RTCM/RAW... data (from Server/RTK_Base) to SD Card	●	●	●



<b>Send GGA message (from RX-UART-RTK) to Server/Radio RTK Base + Export GGA to TX_UART0</b>	•	•	•
<b>Send all NMEA messages (from RX-UART-RTK) to Server / Radio RTK Base + Export NMEA to TX_UART0</b>	•	•	•
<b>Send IMU_1 Data to Bluetooth Client</b>	•	•	•
<b>Send IMU_2 Data to Bluetooth Client</b>	•	•	•
<b>Send Data (from RX-UART-RTK) to WiFi TCP/UDP device</b>	•	•	•
<b>Send IMU_1 Data to WiFi TCP/UDP device</b>	•	•	•
<b>Send IMU_2 Data to WiFi TCP/UDP device</b>	•	•	•
<b>Respond realtime command control on Bluetooth Client</b>	•	•	•
<b>Respond realtime command control on WiFi TCP/UDP</b>	•	•	•

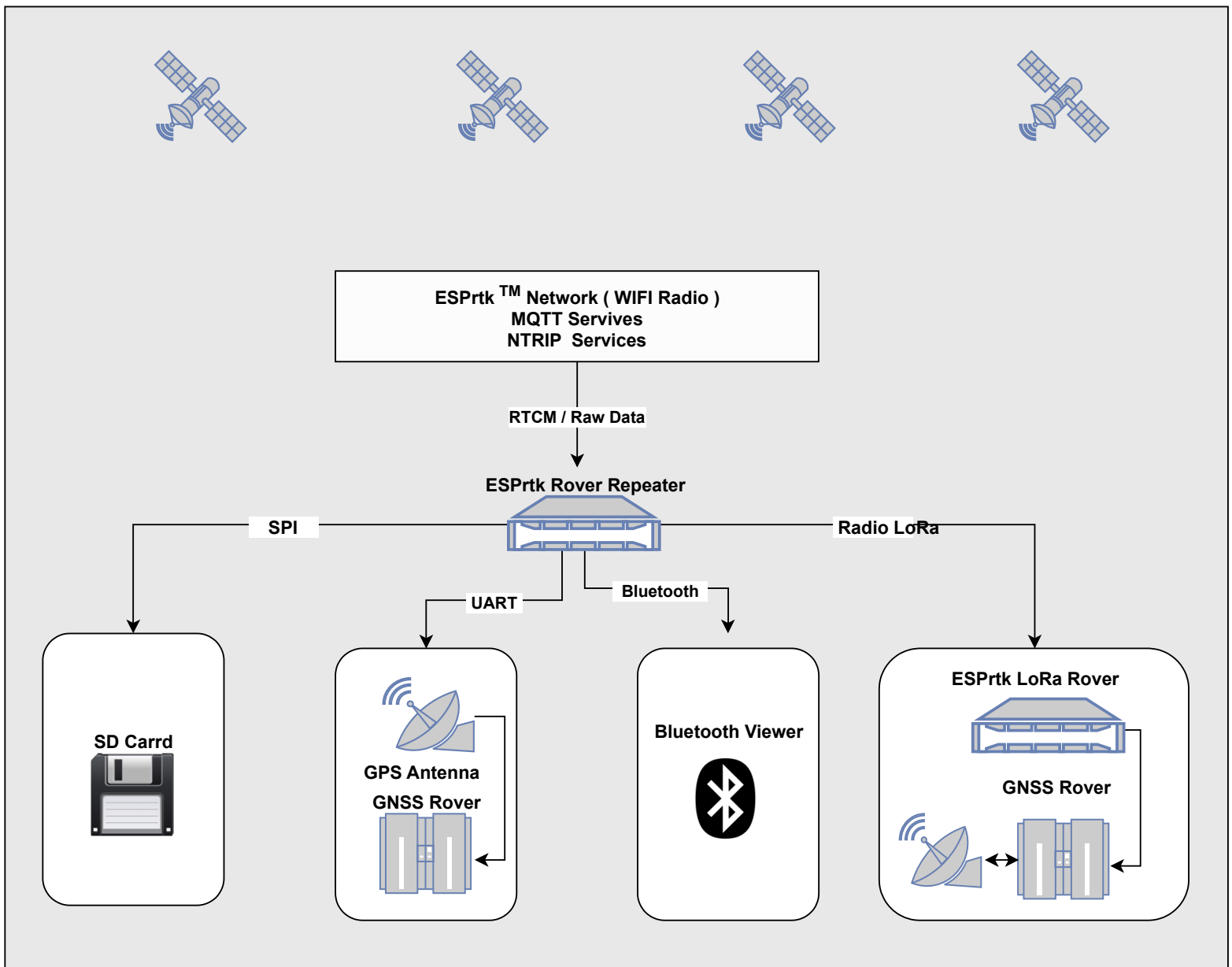


## Configure ESPrtk run as Rover Repeater for RTK Application

The RTK Rover Repeater has the same main function as the RTK Rover is to receive RAW / RTCM data from RTK Base and export to TX\_UART\_RTK port.

The RTK Rover Repeater adds a feature that repeats data from the Base. It is then a Rover (receiving data from Base) and a Base (sending data received to other Rover or to Bluetooth Client devices).

In ESPrtk 3.0.0 version, the repetition feature is applied to Rover when running as MQTT / NTRIP Rover, RAW / RTCM data received will be transmitted repeatedly to ESPrtk running as Radio RTK Rover.





The repetition feature is primarily exploited in applications that require the expansion of RTK networks in areas where Internet use is limited in distance.

The RTK model includes :

- 1 RTK Rover Repeater : Send RTCM/RAW ( from RTK MQTT/NTRIP Base ) to RTK Radio Rover .
- 1 (or more) RTK Radio Rover : Export RTCM/RAW data to GNSS Rover Receiver.

When configuring ESPrtk, they will be configured in pairs.

- **MQTT RTK Base** and **MQTT RTK Rover Repeater** for MQTT link.
- **NTRIP RTK Base** and **NTRIP RTK Rover Repeater** for NTRIP link.

And

- **MQTT RTK Rover Repeater** and **Radio RTK Rover** for Radio link.
- **NTRIP RTK Rover Repeater** and **Radio RTK Rover** for Radio link.

( When ESPrtk configure as **MQTT RTK Rover Repeater** or **NTRIP RTK Rover Repeater** that mean it will run as an **RTK MQTT / NTRIP Rover** and also run as an **RTK Radio Base** at the same time on one ESPrtk device )

On version 3.0.0, the features are supported as shown in the table below.

Main Action	Detail
<b>MQTT RTK Base</b>	<b>Send data (from RX-UART-RTK) to (MQTT Broker)</b>
<b>MQTT RTK Rover</b>	<b>Export data (from MQTT Broker) to TX-UART-RTK port</b>
<b>MQTT RTK Rover Repeater</b>	<b>Export data (from MQTT Broker) to TX-UART-RTK port</b>
<b>NTRIP RTK Base</b>	<b>Send data (from RX-UART-RTK) to (NTRIP Caster)</b>
<b>NTRIP RTK Rover</b>	<b>Export data (from NTRIP Caster) to TX-UART-RTK port</b>
<b>NTRIP RTK Rover Repeater</b>	<b>Export data (from NTRIP Caster) to TX-UART-RTK port</b>
<b>Radio RTK Rover</b>	<b>Export data (from RTK Radio_Base) to TX-UART-RTK port</b>



Other Action for RTK Rover Repeater	MQTT RTK Rover Repeate	NTRIP RTK Rover Repeate	Radio RTK Rover Repeate
Export IMU Data to TX_UART_0 port	●	●	●
Save NMEA / RTCM Data (from RX-UART-RTK) to SD Card	●	●	●
Rover-Save RTCM/RAW... data (from Server/RTK_Base) to SD Card	●	●	●
Send RTCM/RAW... data (from Server/RTK_Base) to Bluetooth Client	●	●	●
Send RTCM/RAW... data (from Server/RTK_Base) to LoRa_Radio_Rover	●	●	●
Base-Export NMEA/GGA data (from Rovers) to TX_UART_0 port	●	●	●
Base-Priority export NMEA Data from Rovers	●	●	●
Rover-Send GGA message (from RX-UART-RTK) to Server/RTK_Base + Export GGA to TX_UART0	●	●	●
Rover-Send all NMEA messages (from RX-UART-RTK) to Server/RTK_Base + Export NMEA to TX_UART0	●	●	●
Send IMU_1 Data to Bluetooth Client	●	●	●
Send IMU_2 Data to Bluetooth Client	●	●	●
Send Data (from RX-UART-RTK) to WiFi TCP/UDP device	●	●	●
Send IMU_1 Data to WiFi TCP/UDP device	●	●	●
Send IMU_2 Data to WiFi TCP/UDP device	●	●	●
Respond realtime command control on Bluetooth Client	●	●	●
Respond realtime command control on WiFi TCP/UDP	●	●	●



## Configure ESPrtk - UART\_Base\_to\_UART\_Rover mode

Main Action	Detail
UART_Base_to_UART_Rover	Get data (from RX-UART-RTK) as RTK Base and Export to TX-UART-RTK port as RTK Rover

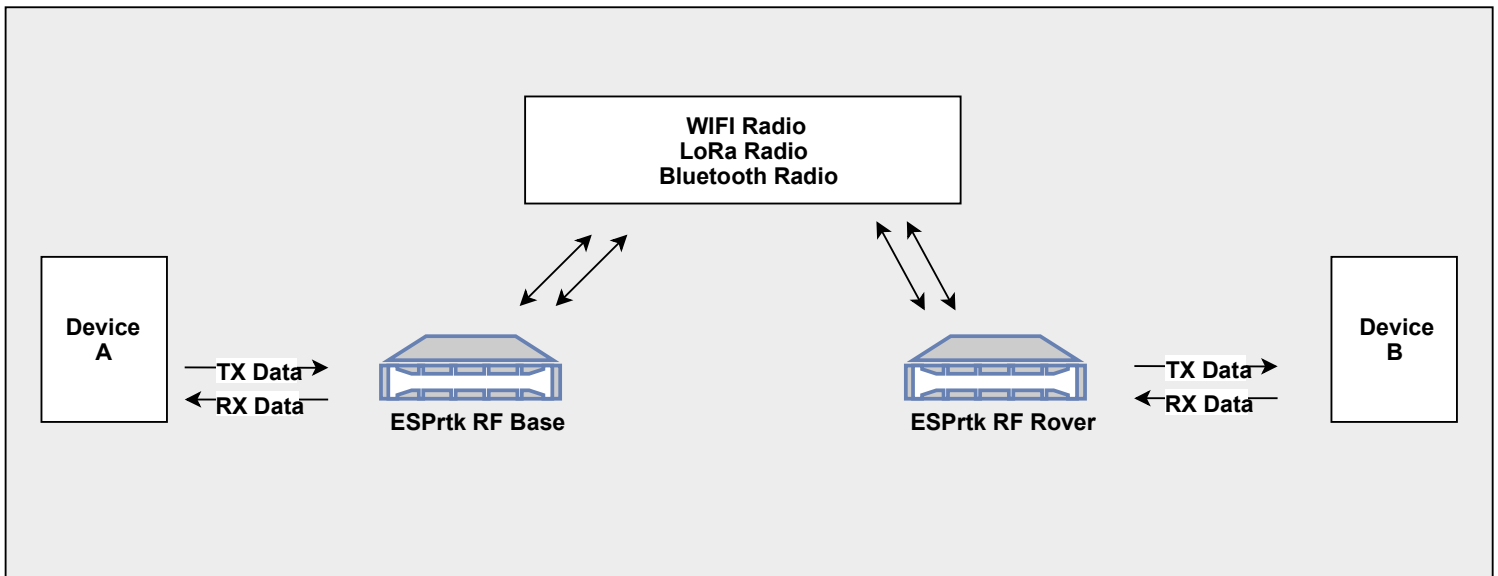
Other Action for RTK Rover Repeater	UART_Base_to_UART_Rover
Export IMU Data to TX_UART_0 port	•
Rover- Save RTCM/RAW... data (from Server/RTK_Base) to SD Card ( Save output TX-UART-RTK)	•
Send RTCM/RAW... data (from Server/RTK_Base) to Bluetooth Client	•
Send RTCM/RAW... data (from Server/RTK_Base) to Bluetooth Client	•
Send IMU_1 Data to Bluetooth Client	•
Send IMU_2 Data to Bluetooth Client	•
Send Data (from RX-UART-RTK) to WiFi TCP/UDP device	•
Send IMU_1 Data to WiFi TCP/UDP device	•
Send IMU_2 Data to WiFi TCP/UDP device	•
Respond realtime command control on Bluetooth Client	•
Respond realtime command control on WiFi TCP/UDP	•



## Configure ESPrtk run for Data Bridge

When using ESPrtk as RTK Base / Rover it will use Broadcast link (1 Base and Rover unlimited) and optimized for RTK applications.

When using ESPrtk as Data Bridge it will use Point To Point link (1 Base and 1 Rover with peer connection) optimized for 2-way data transmission between Base and Rover similar to UART Link Radio modules. .





RTK Base / Rover and Data Bridge Base / Rover modes use 2 different link models and they will not work when combining them.

Data Bridge Base / Rover only supports connection via Radio Link or Bluetooth.

'Bluetooth to Radio' mode is compatible with 'UART to Radio'.

When configuring ESPrtk, they will be configured in pairs.

- **UART\_to\_RF\_Base** and **UART\_to\_RF\_Rover** .
- **Bluetooth\_to\_RF\_Base** and **Bluetooth\_to\_RF\_Rover**.
- **Bluetooth\_to\_RF\_Base** and **UART\_to\_RF\_Rover** .
- **UART\_to\_RF\_Base** and **Bluetooth\_to\_RF\_Rover**.

Main Action	Detail
<b>UART_to_Bluetooth</b>	Send data (from RX-UART-RTK) to (Blueooth-Client) + Export data (from Blueooth-Client) to TX-UART-RTK port
<b>UART_to_RF_Base</b>	Send data (from RX-UART-RTK) to ( <b>UART_to_Radio_Rover</b> ) + Export data (from <b>UART_to_Radio_Rover</b> ) to TX-UART-RTK port
<b>UART_to_RF_Rover</b>	Send data (from RX-UART-RTK) to ( <b>UART_to_Radio_Base</b> ) + Export data (from <b>UART_to_Radio_Base</b> ) to TX-UART-RTK port
<b>Bluetooth_to_RF_Base</b>	Send data (from Blueooth-Client) to ( <b>UART_to_Radio_Rover</b> ) + Send data (from <b>UART_to_Radio_Rover</b> ) to (Blueooth-Client)
<b>Bluetooth_to_RF_Rover</b>	Send data (from Blueooth-Client) to ( <b>UART_to_Radio_Base</b> ) + Send data (from <b>UART_to_Radio_Base</b> ) to (Blueooth-Client)

- When using Bluetooth, the connection between the End Devices and ESPrtk is Bluetooth, the connection between ESPrtk Base and ESPrtk Rover will be Radio WIFI (or Radio LoRa).

- When using UART , the connection between the End Devices and ESPrtk is UART, the connection between ESPrtk Base and ESPrtk Rover will be Radio WIFI (or Radio LoRa).



Main Action	Communicate type	Wireless Link
UART_to_Bluetooth	UART	Bluetooth
UART_to_RF_Base	UART	Radio ( WiFi / LoRa)
UART_to_RF_Rover	UART	Radio ( WiFi / LoRa)
Bluetooth_to_RF_Base	Bluetooth	Radio ( WiFi / LoRa)
Bluetooth_to_RF_Rover	Bluetooth	Radio ( WiFi / LoRa)

Other Action Data Bridge	Save data send (TX-Wireless-Data) to SD Card	Save data receive (RX-Wireless-Data) to SD Card
UART_to_Bluetooth	•	•
UART_to_RF_Base	•	•
UART_to_RF_Rover	•	•
Bluetooth_to_RF_Base	•	•
Bluetooth_to_RF_Rover	•	•

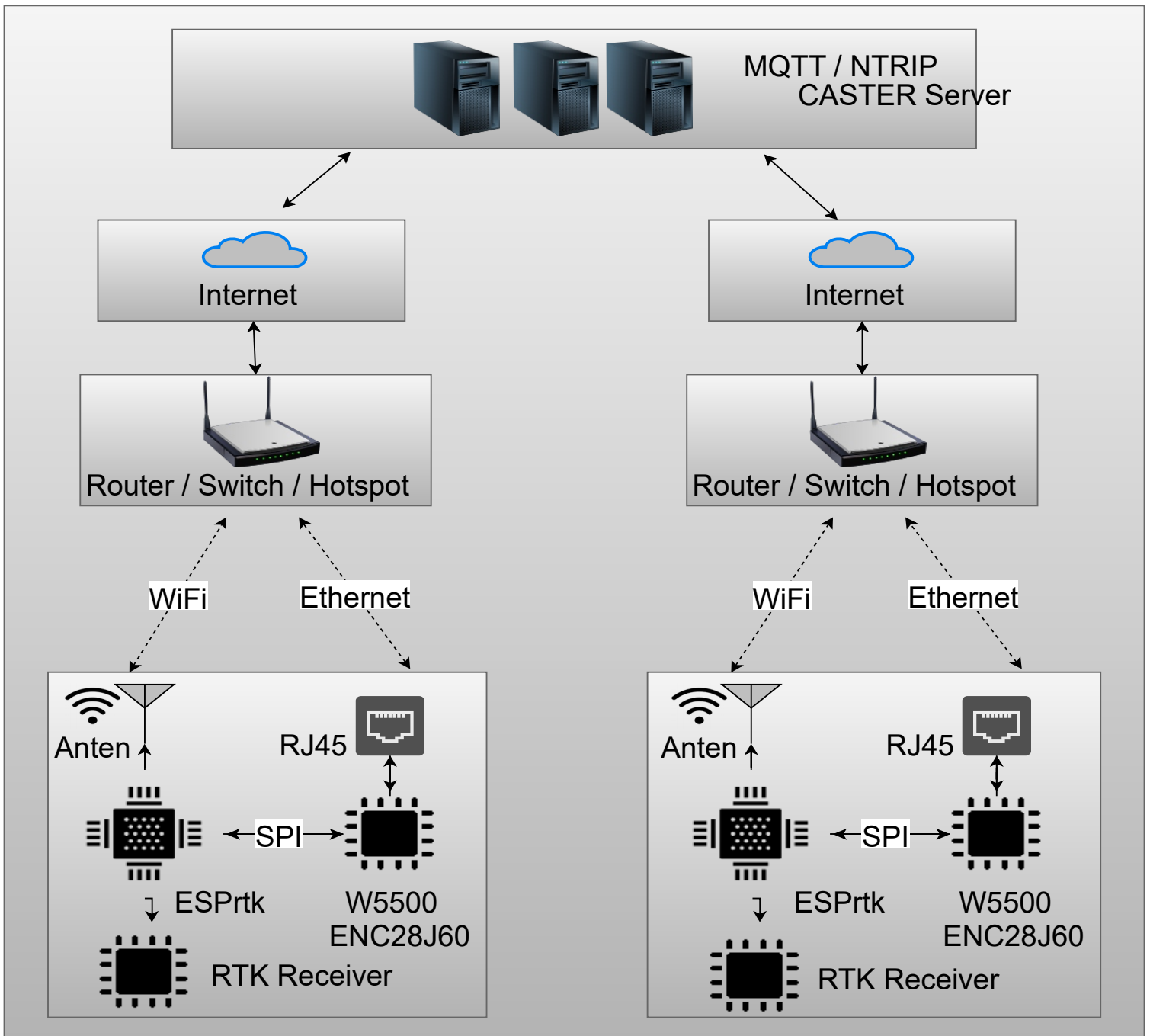


## Configure to access Internet for MQTT/NTRIP

ESPrtk supports Internet access with both connections:

**WiFi** : High-speed wireless WIFI connection on ESP32 helps mobile connections for flexible Rover devices.

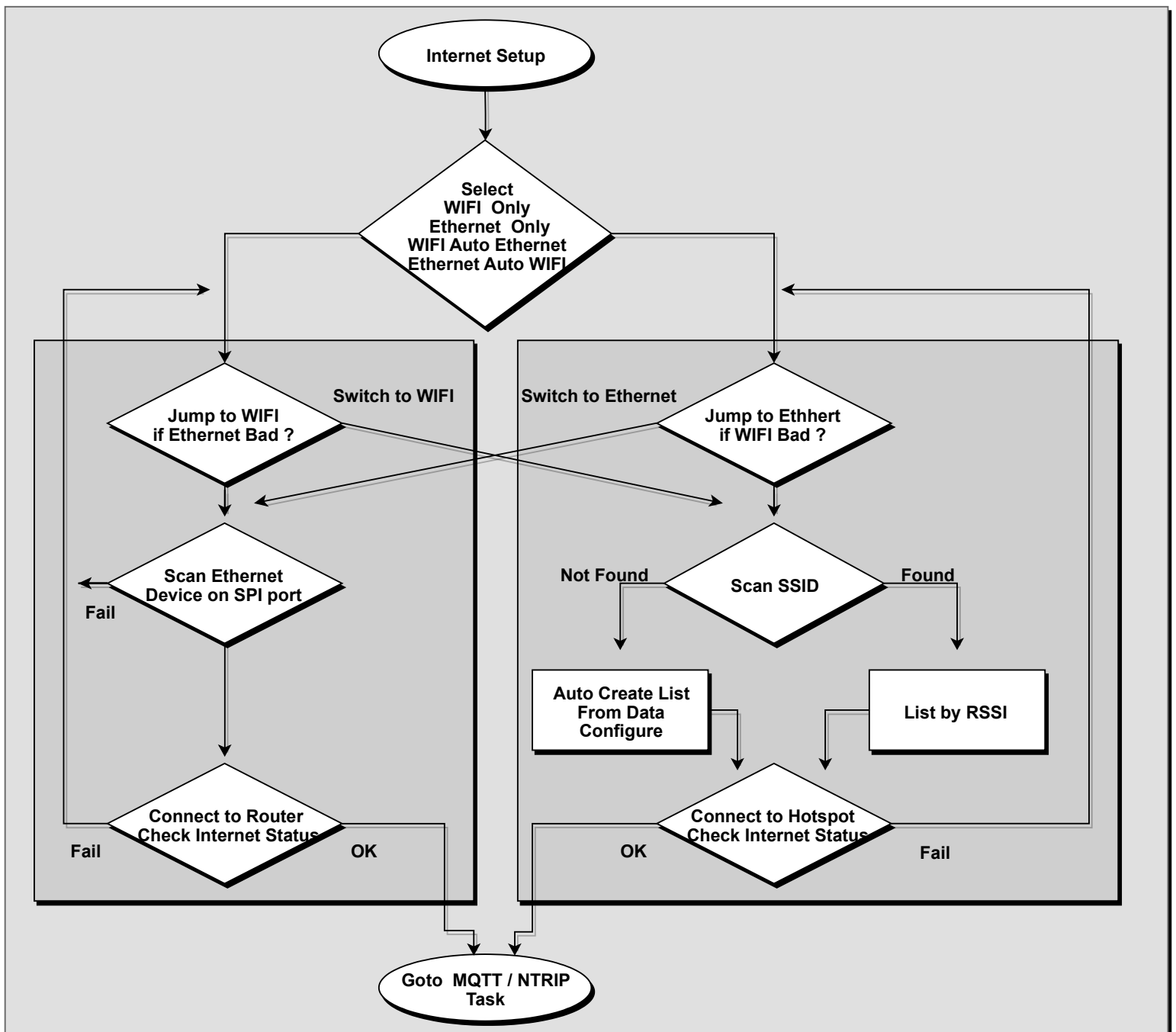
**Ethernet**: Internet connection will be suitable for Basestation with absolute stability. Ethernet module support are W5500 ( 100Mbps ), W5110 .., and ENC28J60 ( 10Mbps) communicate to ESPrtk via SPI port to access internet.

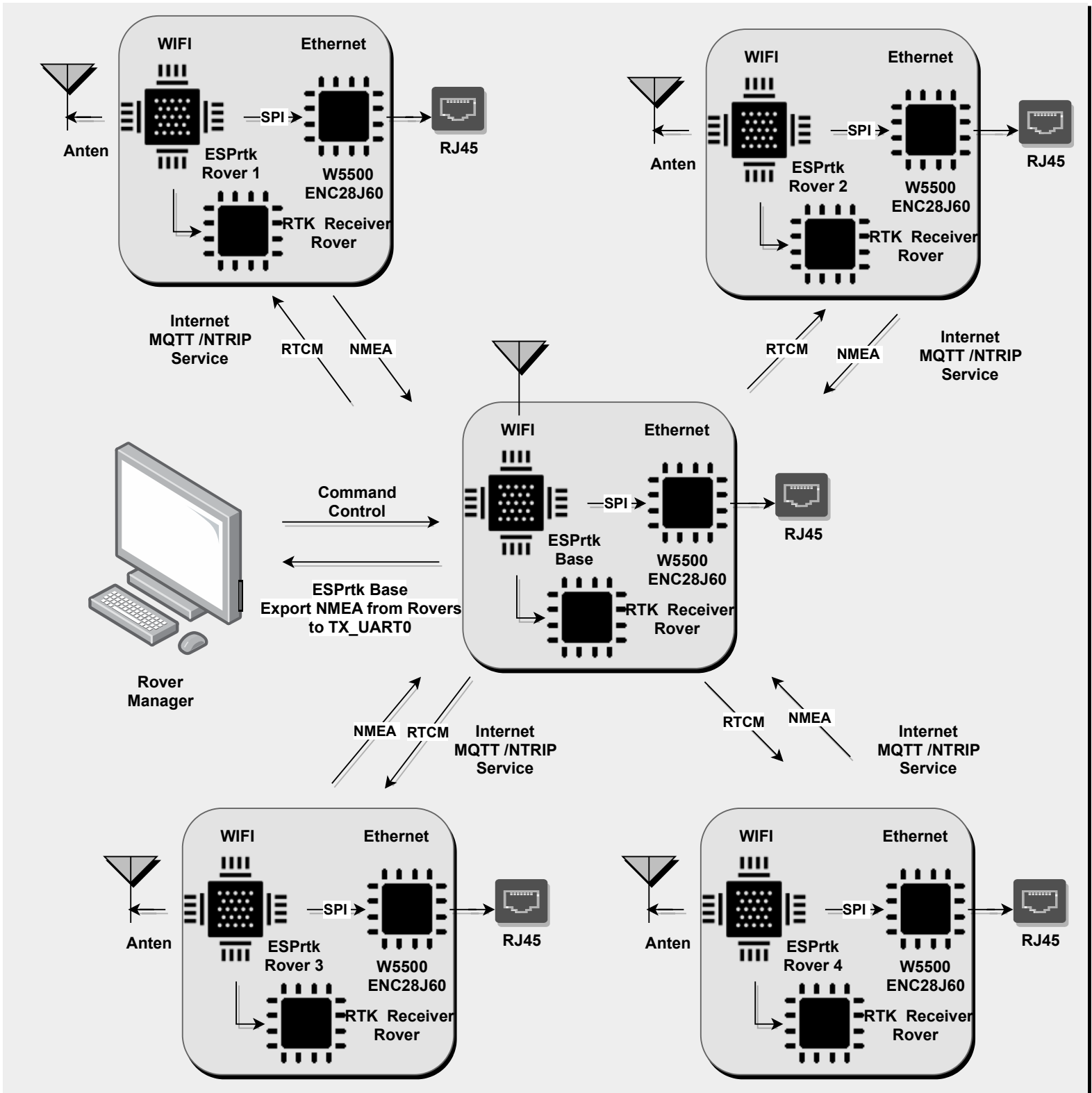




## There are 4 operating modes:

1. WiFi : WiFi only.
2. Ethernet : Ethernet only .
3. Auto WiFi: Select WIFI for the first connect, automatically switching to Ethernet (or back to WIFI) if Internet access is not available after 60 seconds.
4. Auto Ethernet: Select Ethernet for the first connect, automatically switching to WIFI (or back to Ethernet) if Internet access is not available after 60 seconds.







## Configure Radio Link.

When the internet connection is unavailable (the NTRIP / MQTT online service is not available), ESPrtk can use its WiFi signal to transmit GNSS data.

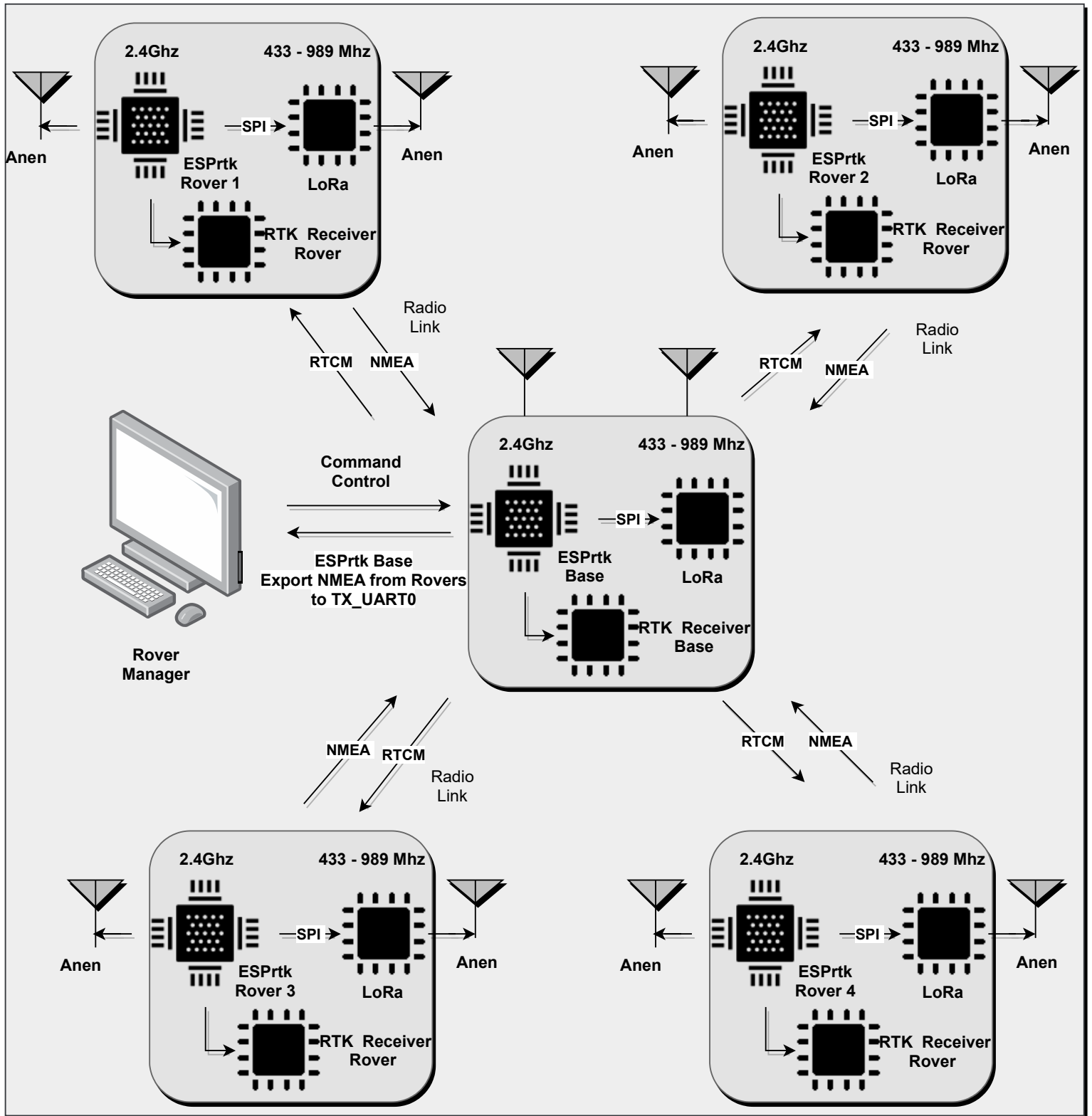
This is similar to the full MQTT functionality but is offline. The connections auto deployed in both protocols are TCP/UDP with the distance constrained to the WiFi transmit power.

ESPrtk will operate stably with a 2500-3000 meters baseline when using external antennas.

For LoRa link , ESPrtk 3.0.0 support communicate to external LoRa module (SX1276 , SX1277 , SX1278 , SX12769) via SPI port for km range stransmit.

Both support real-time data encryption / decryption using AES256.

	WIFI		LoRa		Unit
	Min	Max	Min	Max	
MAC /PHY	IEEE 80211		LoRa		-
Protocol	UDP/TCP-ESPrtk™		LoRa™ - ESPrtk™		-
AES256 Encrypt	Yes		Yes		
2 ways transmit	Yes		Yes		
Channel	1	14	1	14	-
Frequency	2.4 Ghz	2.5 Ghz	412 Mhz	915 Mhz	-
Transmit power	2	20	2	27	dBm
Transmit power	1.59	100	1.59	500	mW
Speed in the air	55	400	0.15	22	Kbps
Transmit Range	-	3	-	50	km
Bandwidth	20 Mhz	40 Mhz	56 Khz	500 Khz	-





## **ESPrtk - WIFI TCP/UDP .**

Act as a side action running with the main action at the same time.

This feature allows sending data get on RX\_UART\_RTK port (RX\_UART\_1 or RX\_UART\_2) to TCP / UDP device over WIFI connection.

Doesn't matter the format of the UART data (NMEA / RTCM / UBX / SKYTRAQ / RAW ...)

It also supports sending real-time IMU data to TCP / UDP device.

Besides, the TCP / UDP device can also act as a HOST and send control commands to ESPrtk in the same way as using on the RX / TX UART\_0 port.

(HOST can send command PING, GPIO control command, check ESPrtk current system error, send restart command or control ESPrtk switch to UART / WEB Configure mode, .....

ESPrtk will respond ACK data / NACK back to HOST over TCP / UDP connection).

Supports 6 different types of connection modes and protocols:

1. TCP Server AP.
2. TCP Server STA.
3. TCP Server Client.
4. UDP Server AP.
5. UDP Server STA.
6. UDP Server Client.

### **Note !**

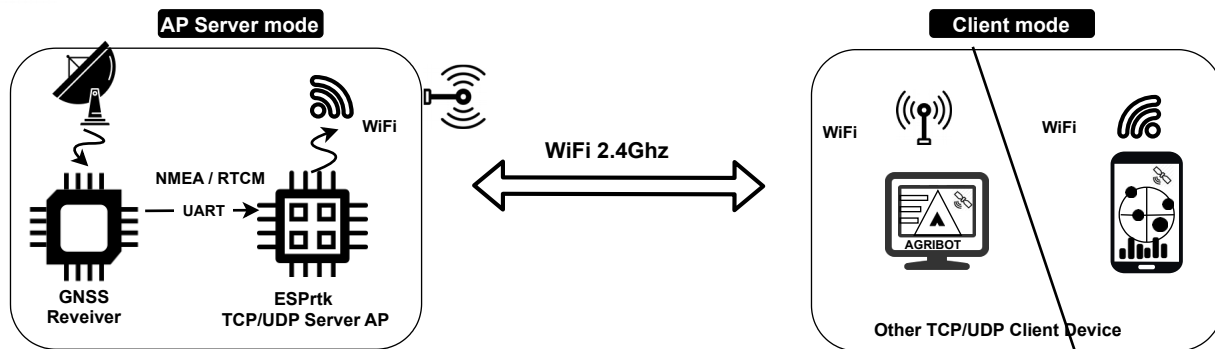
The connection mode and protocol may be different (see below), but it only serves as an intermediate data transmission channel. Usage and how ESPrtk works will be the same on all 6 connection types.

Below describes some common configurations in total of 12 different configurations.

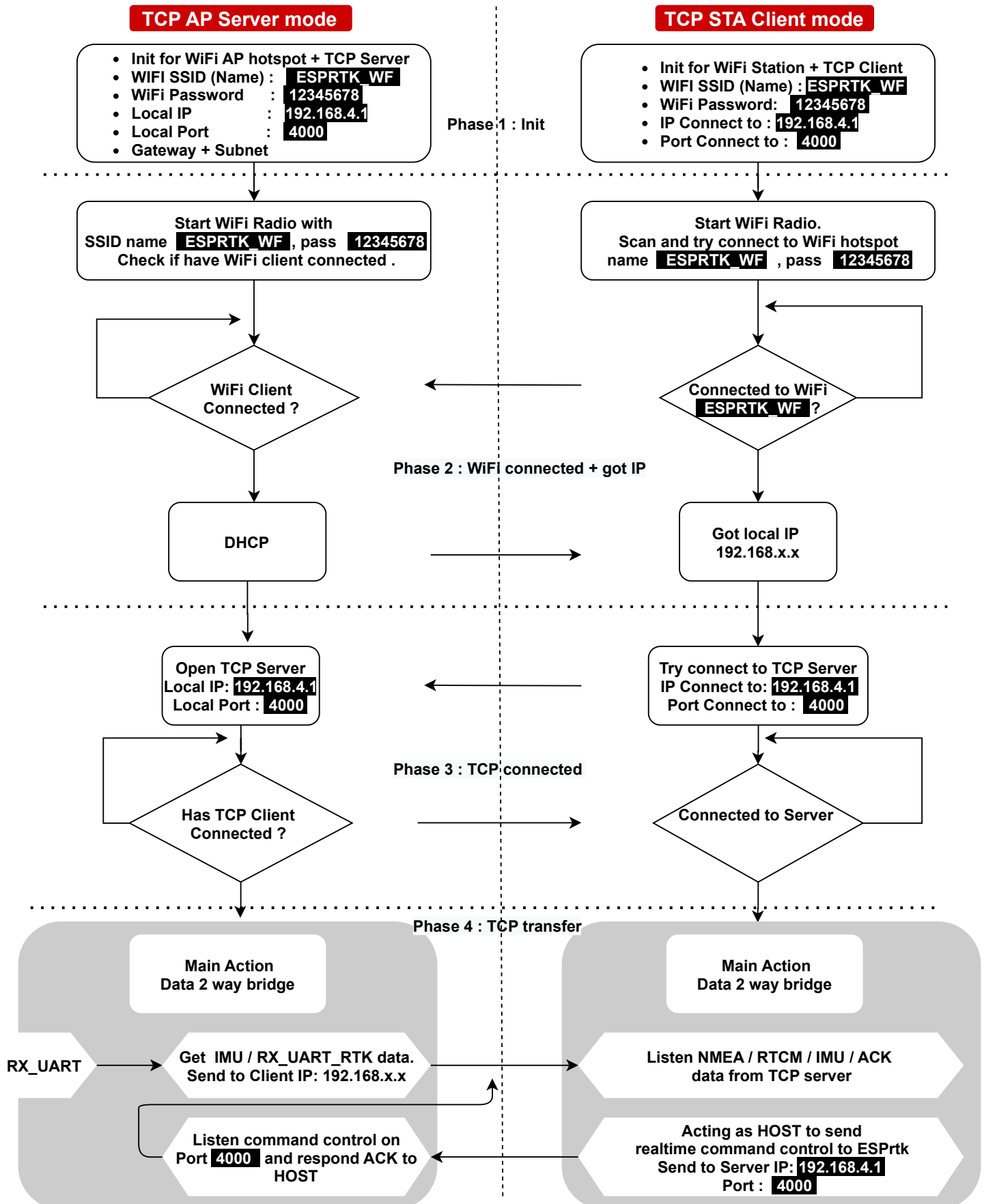


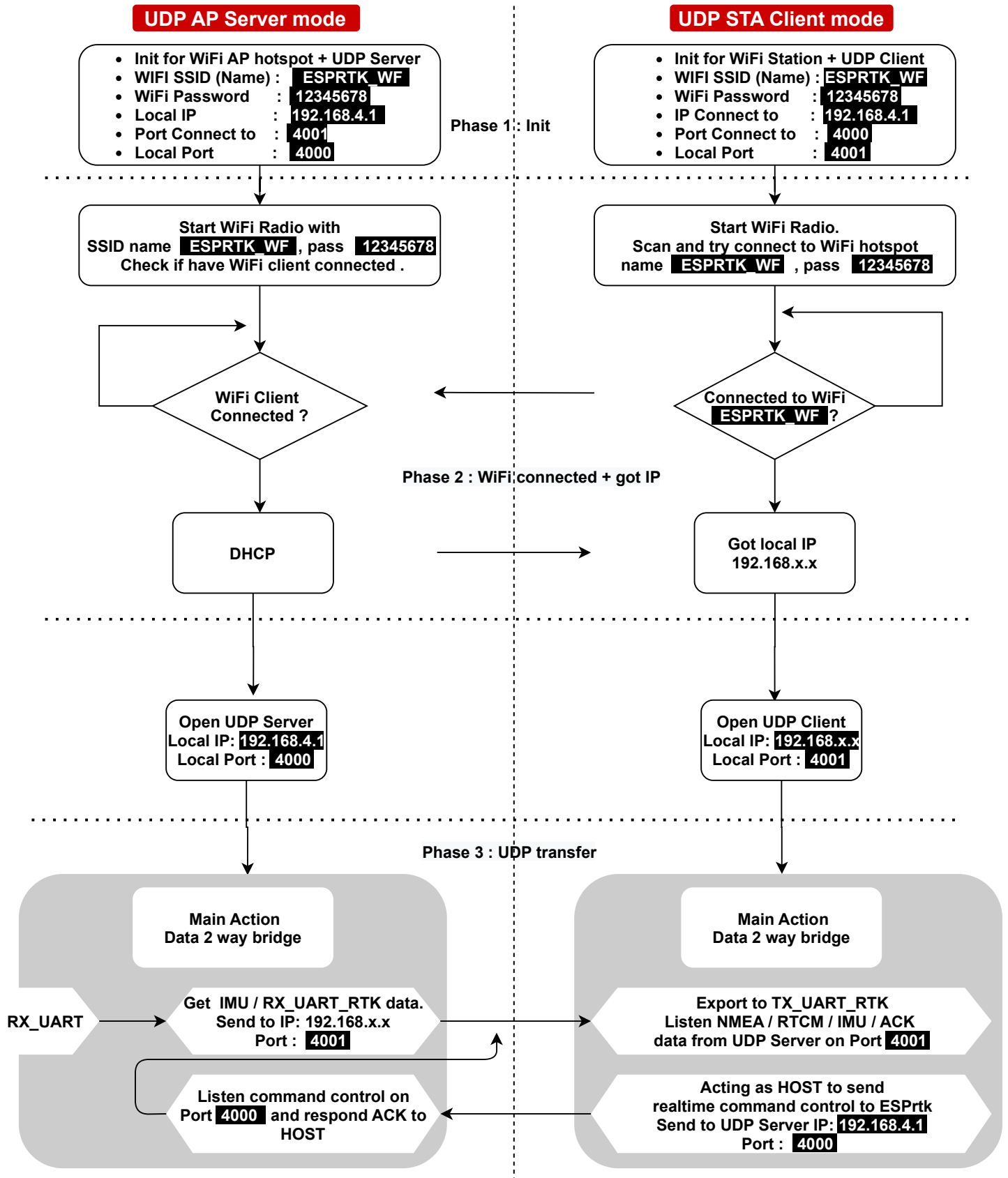
## Configure ESPrtk - TCP /UDP – Server AP + Client STA mode.

Type	Detail
WiFi mode	AP (Access Point) with STA ( Station)
Protocol	TCP /UDP .



Type	WiFi mode (PHY/MAC)	Package and data Transmission Protocol	Detail
TCP/UDP Server AP	Access Point	TCP/UDP Server	Configure ESPrtk’s WiFi mode as an Access Point (hotspot), wait for TCP / UDP Client device (AG monitor, Phone, ESPrtk Client ...) connect to it. Open TCP / UDP Server and listen on default IP and local port as configuration. Listens, maintains connections, and transmits data to TCP / UDP Client.
TCP/UDP Client STA	Station	TCP/UDP Client	Configure ESPrtk’s WiFi mode as a Station device, try to connect to the WiFi Access Point (WiFi Access Point can be Router acting as intermediate data relay or maybe ESPrtk TCP / UDP Server AP). Open TCP / UDP Client and connect to the IP / Port of TCP / UDP Server. Maintain connectivity and data transfer to TCP / UDP Server.

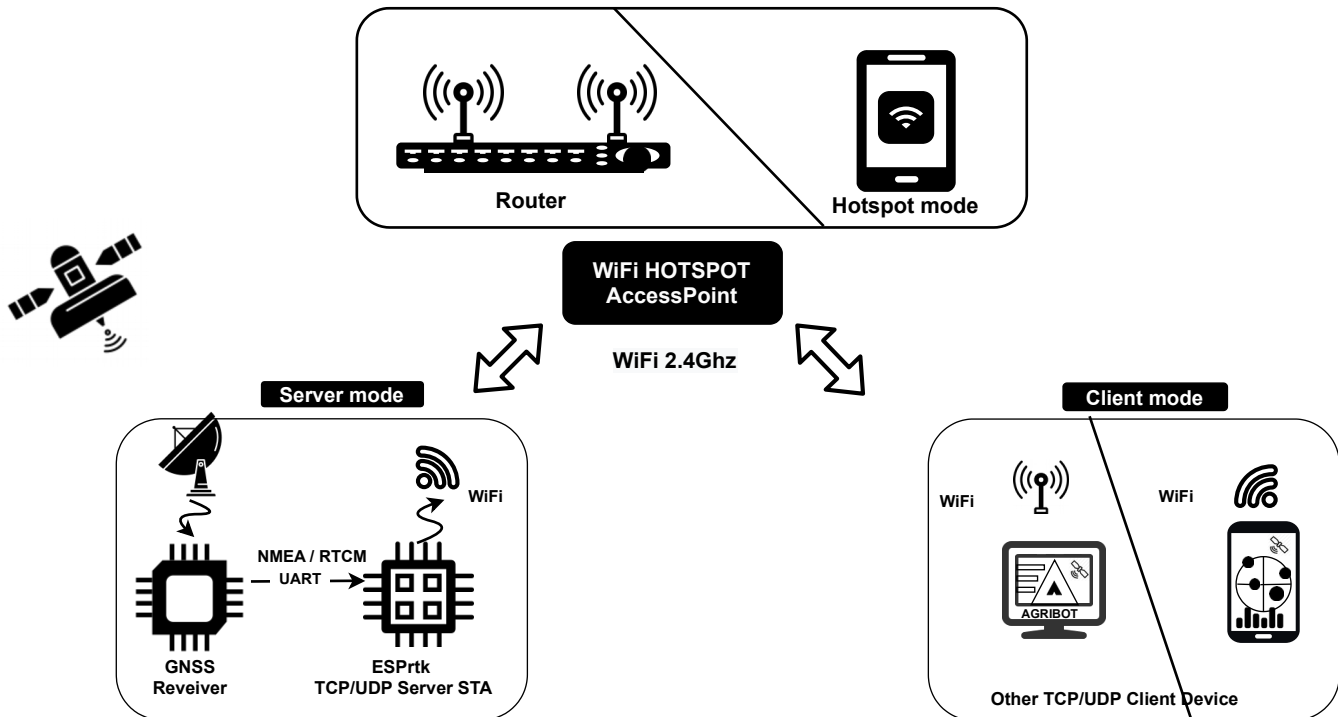


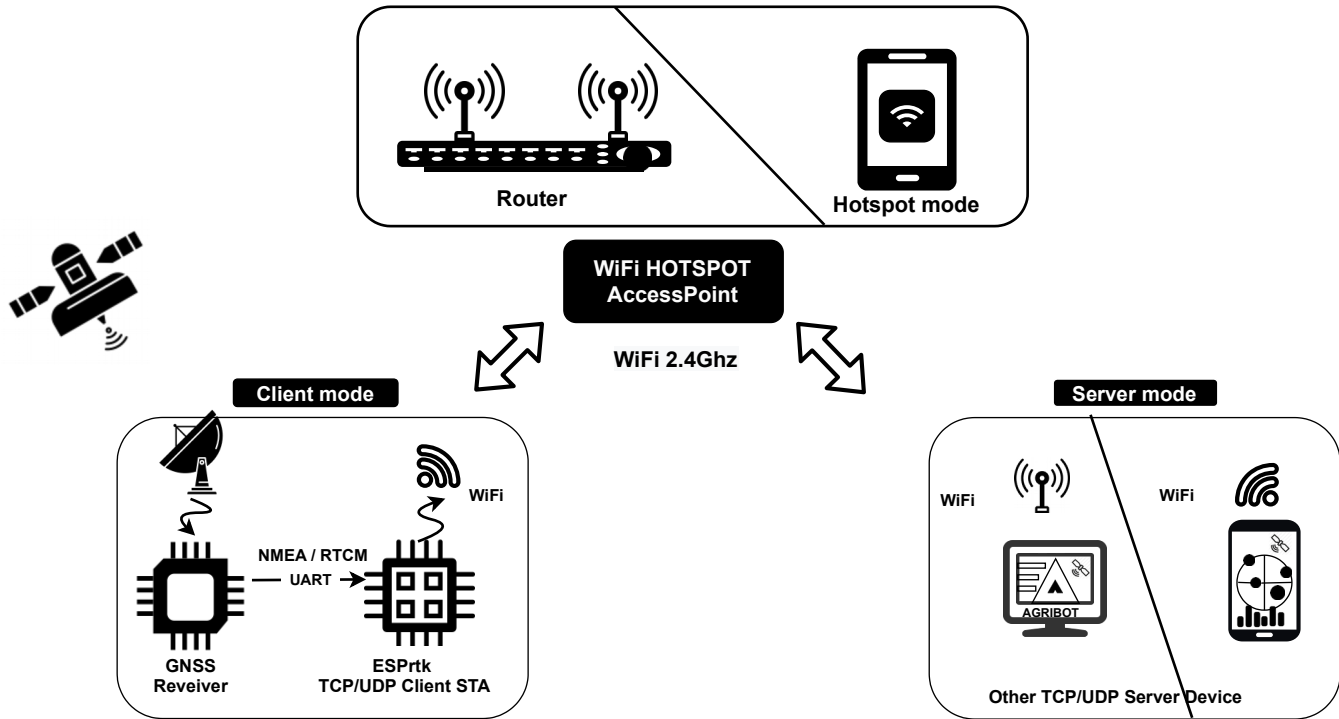




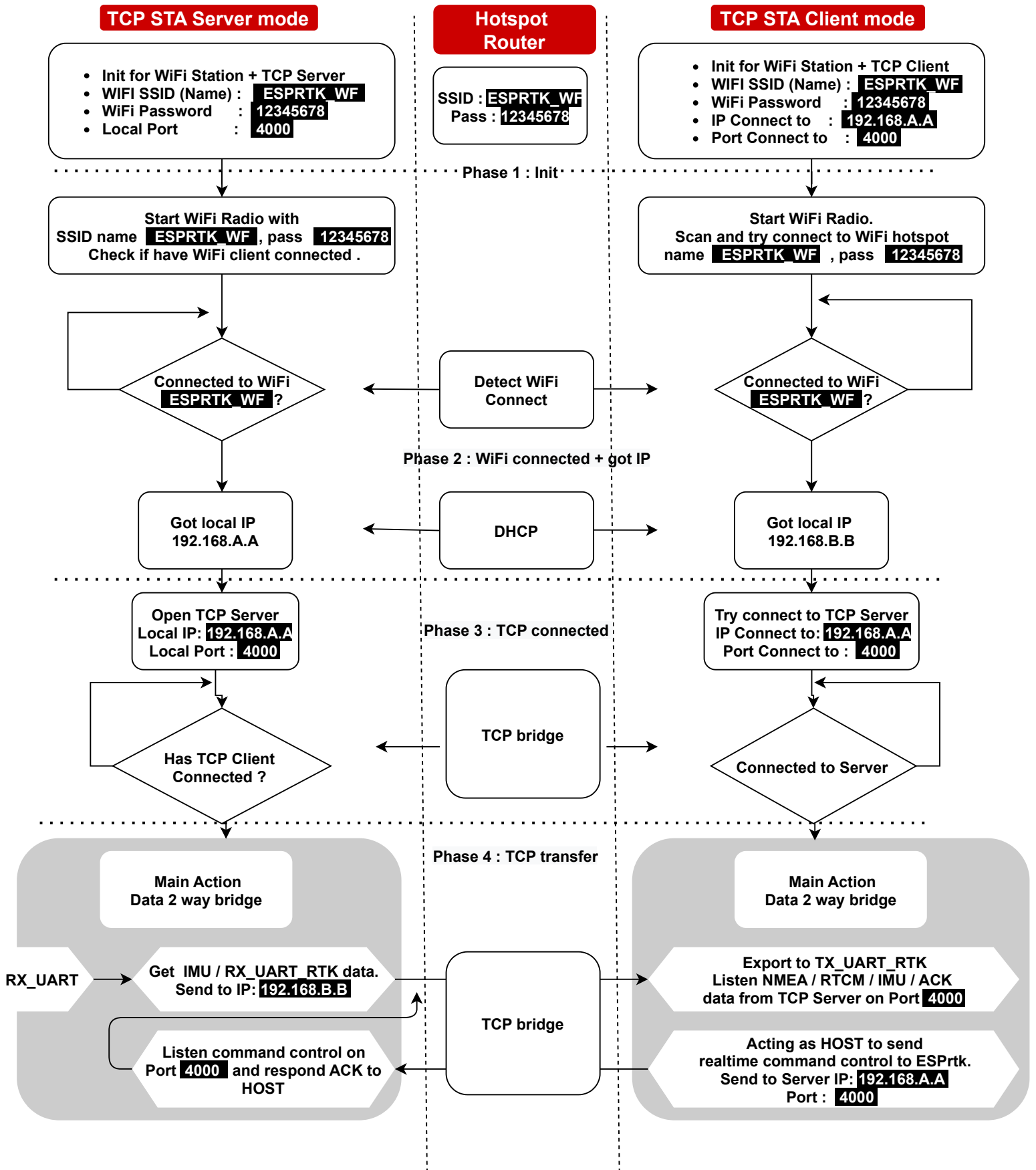
## Configure ESPrtk - TCP /UDP – Server STA + Client STA mode.

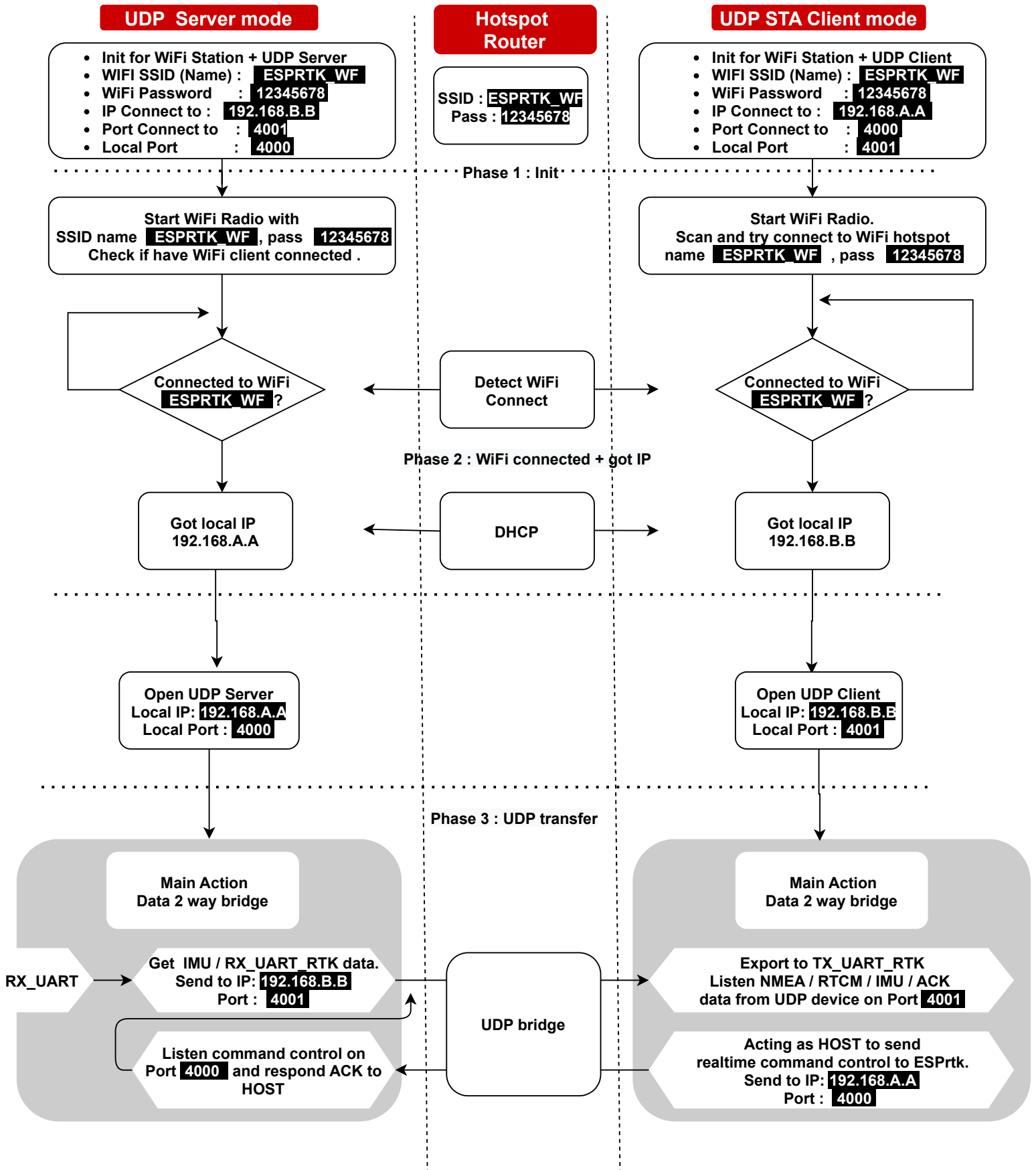
Type	Detail
WiFi mode	STA (Station) with STA ( Station)
Protocol	TCP/UDP ( Server / Client)





Type	WiFi mode (PHY/MAC)	Package and data Transmission Protocol	Detail
TCP/UDP Server STA	Station	TCP/UDP Server	Configure the ESPrtk's WiFi mode as a Station device, try to connect to the WiFi Access Point ( Router acting as intermediate data relay ). Open TCP / UDP Server and listen on default IP and Local port configuration. (Local IP is automatically assigned by the Router by DHCP). Listens, maintains connections and transmits data to TCP / UDP Client.
TCP/UDP Client STA	Station	TCP/UDP Client	Configure ESPrtk's WiFi mode as a Station device, try to connect to the WiFi Access Point (WiFi Access Point can be Router acting as intermediate data relay or maybe ESPrtk TCP / UDP Server AP). Open TCP / UDP Client and connect to the IP / Port of TCP / UDP Server. Maintain connectivity and data transfer to TCP / UDP Server.







## Configure ESPrtk - NTRIP CASTER mode.

Type	Detail
WiFi mode	STA (Server)
Protocol	TCP.
Main Action	Get RTCM/RAW /.. data from RX-UART-RTK (RX1/RX2) then send to NTRIP Client (Rover).
	Get RTCM/RAW /.. data from NTRIP Server (BaseStation) then send to NTRIP Client (Rover).

### NTRIP CASTER - Configure.

**Name/Pass Login WebAdmin** : For owners of NTRIP CASTER, used to login to Dashboard site to manage user accounts.

**Admin Email** : When NTRIP CASTER detected client error or abuse. CASTER will send an error message with the email address of the administrator (admin) via NTRIP Stream , so customers can contact them to resolve the issue.

**WebAdmin Port** : The port that NTRIP CASTER uses to run the Dashboard page. Usually 80.

Then , the Dashboard's address will be <http://x.x.x.x/admin> or <http://x.x.x.x:80/admin> ( With x.x.x.x is the local IP address of that NTRIP CASTER ) .

Setting this value to 0 will not activate the Dashboard and increase the number of sockets by 1 for the NTRIP Client / Server.

**Caster Port** : The port that NTRIP CASTER uses to listen to and respond to connections from the NTRIP Client (Rover / Base). Usually 2101.

Then , the Sourcetable Page's address will be <http://x.x.x.x:2101> or <http://x.x.x.x:80> ( With x.x.x.x is the local IP address of that NTRIP CASTER ) .



**Cycle Update Parse NMEA (s)** : NTRIP CASTER will collect the Rover's location via GGA / NMEA message. Setting the cycle as small will help show the location with a lower delay. Recommended value is above 60s. Setting this value to 0 disables this function.

**Basestation timeout data receive (s)** : NTRIP CASTER acts as a data bridge, it receives RTCM data from NTRIP Base and distributes it to all Rovers. If NTRIP Base stops sending RTCM data after a period of time, NTRIP CASTER will understand the NTRIP Base has lost connection (died or stopped working). The default value is 9 seconds.

**Cycle save record limit (s)** : All changes, user configuration data, bandwidth counter, etc. will be automatically saved to FLASH periodically after a period of time. The default value is 86400 seconds. ( 1 day ). Setting this value to 0 disables this function.

## Testing NTRIP CASTER with local network and dynamic IP.

Please make sure the configuration is saved correctly. Now press the “Reset” button on ESPrTk, it will start working.

## NTRIP CASTER - Find the local IP address of the NTRIP CASTER.

Before starting NTRIP CASTER, the ESP32 will try to connect to the WIFI hotspot to get the IP address.

If the connection is successful, you will receive a notification with the IP address for your CASTER on the TX\_UART\_0 port.

If you use an OLED display for your ESP32, you will also see a message similar.

Remember, this will be the IP address that the NTRIP Client / Server will use to connect to it.

**For example**, in my case, the ESP32 NTRIP CASTER server now has address **192.168.1.10**

Thus, the address that the NTRIP Client needs to connect to will be:

- IP: **192.168.1.10**
- Port: **2101**

One thing to know is that this IP will be changed in the event your wifi hotspot reboots.



## **NTRIP CASTER - Check the status of NTRIP CASTER.**

The NTRIP CASTER server is ready as soon as it connects successfully with WIFI hotspot.

Connect your computer to the same WIFI hotspot, then open the WEB browser and access the address <http://192.168.1.10:2010>

You will get a SourceTable page containing information about the active RTK Basestations (Mountpoint).

## **NTRIP CASTER - Connecting the F9P / PX1122R Base to the NTRIP CASTER.**

By default, you will see there is a station named Base\_0 in the SourceTable list, this station created by the NTRIP CASTER itself to act like an NTRIP Server / BaseStation by taking the RTCM data on its own RX\_UART\_RTK port and distributing it. directly to the NTRIP clients (instead of receiving the push RTCM from the NTRIP Server).

Connect TX1 pin of F9P / PX1122R Base to RX\_UART\_RTK (RX\_UART1 or RX\_UART\_2) pin of ESP32 NTRIP CASTER so that this mounpoint has available data.

To connect ESPrtk with RTK receiver, See ESPrtk Pin map more detail.

## **NTRIP CASTER - Connect the NTRIP Client to the NTRIP CASTER.**

You can use ESPrtk running in NTRIP Client mode to connect to NTRIP CASTER as an NTRIP Client / Rover.



I will use Lefeburre NTRIP CLient Adnroid app to test the connection to NTRIP CASTER. First, connect your phone to the same WIFI hotspot.

Open the application, in the NTRIP settings entry:

- Caster IP : **192.168.1.10**
- Caster Port : **2101**
- Username : **name\_0**
- Password : **pass\_0**
- Data Stream (Mountpoint) : **Base\_0**

**Tip :** Mountpoint can also be automatically suggested by the application by browsing the SourceTable panel.

Then, click the connect button.

The yellow speed bar moves to the right, so I have successfully connected to Base\_0 station.

Because this is NTRIP CASTER's own Base\_0 station, if the F9P / PX1122R Base is not connected to the RX\_UART\_RTK pin of the ESP32 NTRIP CASTER, the NTRIP CASTER will only send about 50 Byte / s of default messages with a string like this in the stream. : " ST: RX\_UART\_RTK CASTER Not receive data after 3s ".

## **NTRIP CASTER - Connect the NTRIP BaseStation to the NTRIP CASTER.**

You can use ESPrtk running in NTRIP Master mode to connect to NTRIP CASTER as an NTRIP Server / BaseStation.

I will use RTKLIB to test the connection to the NTRIP CASTER.



First, connect your computer to the same WIFI hotspot.

The input data is RTCM over Serial port in my case.

In NTRIP settings:

- NTRIP Caster Host : **192.168.1.10**
- Port : **2101**
- Mountpoint : **Base\_1**
- Password : **pass\_1**
- String : **Austin,Texas;RTCM  
3.2;1005(1),1074(1),1084(1),1124(1),1230(1);;GPS+GLO+BDS;SNIP;USA;30.30;-  
97.73;1;0;sNTRIP;none;N;N;2980;my\_misc**

Then press Start button.

The green data status bar starts moving to the right, the input data counter increases, it looks like it is working.

To be sure, I check it out again on the Sourcetable site.

And my Base\_1 station appeared. So it worked.

## **NTRIP CASTER - Add more connections for NTRIP Client / Rover and NTRIP Server / BaseStation.**

Multiple NTRIP Clients can connect and listen to RTCM data at the same time on a single mountpoint.

Multiple NTRIP Server (BaseStation) can be connected and send RTCM data to the NTRIP CASTER.

One thing to note is that the number will be limited and changed by the admin of that NTRIP CASTER.

One NTRIP account will allow up to 10 Rovers and 1 BaseStation to connect to.

An NTRIP account allows Rover to access any active Mountpoint of the NTRIP CASTER.

ESPrTk 3.9.87 supports :



- 10 different accounts
- 10 connection in the sametime
- 50000bps bandwidth for each connection

## **NTRIP CASTER - Admin / Dashboard page.**

When the NTRIP CASTER is running, all information about the connections and the speed for each socket will be printed out on the TX\_UART0 port of the ESP32.

To make it easier to manage and monitor the status of the NTRIP CASTER. ESPrtk supports an online WEB Server that works at the same time as NTRIP CASTER.

Information will be automatically updated in real time (every 1 second).

This feature is specific to Admin (manager / owner / technician) of that NTRIP CASTER.

It allows to make changes to user accounts, set bandwidth limits, uptime limits, ... Kick or ban IP on any connection, check status and location in realtime.

Can use computer, phone or any device that supports WEB browser to use with it.

### **NTRIP Caster Admin Dashboard - Access the Dashboard page.**

First, connect your computer to the same WIFI hotspot.

(In this article, the IP address of the NTRIP CASTER is 192.168.1.10 and the Admin Dashboard page is configured to run at port 80.)

Open a browser and access the address <http://192.168.1.10:80/admin> (or <http://192.168.1.10/admin>).

The homepage appears with server type options that the browser will use to load data for the WEB site.

There are 3 options:



- **Online Server S1 Only** : Load web resources from an online server.
- **Combination Server S1 + S2** : Load web resources from online server, if failed, automatically switch to offline mode and download resource directly from ESPrtk.
- **Direct Server S2 Only** : Load web resources directly from ESPrtk.

When loading resources directly from ESPrtk (Server S2), the connection for NTRIP Client will be reduced in maximum bandwidth to ensure page loading speed. This will cause some RTCM data to be lost in about 3 seconds when the browser loads the resource from ESPrtk.

(Therefore, we recommend using the first option (Online Server S1 Only) to load the page. The 2nd and 3rd options should only be used when you are offline.)

To continue, click on the 'GO!' Button and wait about 5 seconds, a login page will appear, it asks to enter a name and password to access as admin of NTRIP CASTER, the default value is:

- Name : **admin**
- Password : **acb123ABC**

( If you want to change NTRIP CASTER admin username and password, please use the WEB configuration interface or the UART configuration interface of ESPrtk.)

## **NTRIP Caster Admin Dashboard - Tab Tables .**

This tab provides information about the connection status for each Basestation and Rover.

### **General description sheet for Basestation .**

It's at the top of the tab, and it provides the following information:

- **Mountpoint** : The name of the mount point on which Basestation is logged.
- **Name** : The username of the user that is used for this Basestation.



- **Active** : Whether data is running through this socket or not.
- **IP** : The IP address of that Basestation.
- **Time Run** : Total continuous operation time (from the last reconnection time).
- **RTCM In bps** : The speed at which the data is sent (up) for the Basestation. (If it is Base\_0 of the NTRIP CASTER itself, it is the input data rate on RX\_UART\_RTK port).
- **Out bps** : Total sending speed to all rover.
- **Rovers** : Total Rover is listening to data on this mountpoint.

### **Detailed description sheet for Basestation.**

It is located at the bottom of the general description sheet, it provides additional information:

- **STR**: STR string currently used to display on the Sourcetable page for this mount point.  
Position: The position (Lat / Long) of the Basestation. Click the 'Redraw map' button to show it on the map. (Make sure to access the Map tab first.)
- **Control Kick** :Instantly disconnects to this Basestation. (Basestation can still be reconnected).
- **Control Board IP** : Disconnects immediately to this Basestation and permanently ban the current IP. (Basestation cannot be reconnected by an current IP).

### **Detailed description sheet for Rover.**

Directly below the Basestation Blueprint is a detailed description for each Rover listening to its RTCM data, which provides the following information:

- **Rover IP / Port** :The Rover IP address
- **Time Run** : Total time of continuous operation (from the last reconnection time).
- **Lasted GGA / RMC** : Complete NMEA GGA message string and Rover's Lat / Long location.
- **Position** : Rover's current position (parsed from GGA). Click the 'Redraw map' button to show it on the map. (Make sure to access the Map tab first.)
- **RTK State** : Rover's RTK FIX status (parsed from GGA).
- **NMEA In bps** : Rover's speed send NMEA/GGA to NTRIP CASTER .
- **User Account** :Username is used for this Rover.



- **Control Kick** :Instantly disconnects to this Rover. (Rover can still be reconnected).
- **Control Board IP** : Disconnects immediately to this Rover and permanently ban the current IP. (Rover cannot be reconnected by an current IP).

### **IP Banned.**

At the bottom of the tab is a list of banned IP addresses.

You can add, edit or remove any IP.

The number of IPs can stored on ESPrTk version 3.9.8.7 is 50 different IPs.

## **NTRIP Caster Admin Dashboard - Tab Home .**

### **CASTER PROFILE Window:**

- **NAME** : The owner name of this NTRIP CASTER. (Change this field using the UART Configure interface or WEB Configure in the Profile tab)
- **MAX SOCKET** : Maximum number of sockets (at the same time) that NTRIP CASTER supports
- **MAX BAN IP** : Maximum number of sockets (at the same time) that NTRIP CASTER supports
- **MAX ACCOUNT** : Number of accounts connected at the same time that NTRIP CASTER supports
- **MAX BANDWIDTH** : Maximum bandwidth NTRIP CASTER supports.
- **BASE EACH ACCOUNT** : Number of BaseStation that can share one account.
- **ROVER EACH ACCOUNT** : Number of rovers that can share one account.
- **FIRMWARE / WEB UI** :Current version of NTRIP CASTER and WEB Server interface version for Admin Dashboard site.

### **CURRENT TOTAL BANDWIDTH Window:**

Total push-up and push-down speed of all Rover and Basestation.



### **TOTAL SOCKET OPENNING Window:**

The total number of Rovers and Basestation is connected to.

### **SERVER UPTIME + STREAM COUNT BYTE Window:**

- **Line 1** : Total operating time of NTRIP CASTER (from the last restart time)
- **Line 2** : Count the total number of Bytes that the NTRIP CASTER received (from the last restart).
- **Line 3** : Count the total number of Bytes that the NTRIP CASTER sent (from the last reboot).

### **SERVER TEMPERATURE Window:**

ESP32 chip internal temperature.

**Note** : Please use the heatsink for the ESP32 when running in NTRIP CASTER mode for a long time.

### **MOST ACTIVE ACCOUNT 24 HOUR Window:**

- **Top total bandwidth** : The account has the highest total number of Bytes (sending and receiving) within 24 hours.
- **Highest bandwidth** : The account has the highest bandwidth usage (receive and send) within 24 hours.
- **Top time run** : The account has the highest total connection uptime within 24 hours.
- **Top sockets** :Accounts used for the most devices within 24 hours.
- **Top average** : An account that averages the highest metrics within 24 hours.

### **LAST 24 HOUR REVENUE Window:**

The chart depicts the highest bandwidth usage and the most connections within 24 hours.



#### **LAST 24 MINUTES REVENUE Window:**

The chart depicts the highest bandwidth usage and the most connections within 24 minutes.

#### **MOST ACTIVE ACCOUNT 1 MINUTE Window:**

- **Top total bandwidth** : The account has the highest total number of Bytes (sending and receiving) within 1 minute.
- **Highest bandwidth** : The account has the highest bandwidth usage (receive and send) within 1 minute.
- **Top time run** : The account has the highest total connection uptime within 1 minute.
- **Top sockets** :Accounts used for the most devices within 1 minute.
- **Top average** : An account that averages the highest metrics within 1 minute.

#### **SOCKET STATUS Window:**

Column chart showing the connection status and Send / Receive speed of each socket (NTRIP device).

Clicking on that column will prioritize displaying the details of that socket in the SOCKET DETAIL tab next to it.

#### **SOCKET DETAIL Window:**

Details of connection:

- **Socket** : Connection's socket ID.
- **Mode** : Connection mode ( Base / Rover).
- **IP** : IP and Port of Rover/Base.
- **Time** : Total time to maintain the connection (from the last reconnection time).
- **Print** : The speed of the input data on this socket.
- **Out** : The speed of the output data on this socket.



- **In + Out** : The total data rate of input and output on this socket.
- **Lat** : Rover/Base's latitude .
- **Long** : Rover/Base's longitude.
- **Account** :The account that this Rover/Base is using to log in for this connection.
- **Agent** : NTRIP user agent.

#### **BANDWIDTH Window:**

- **ALL** : Total input and output data rate of the NTRIP CASTER at the present time.
- **IN** : Total input rate of NTRIP CASTER at the present time.
- **OUT** : The total output rate of the NTRIP CASTER at the present time.

#### **SOCKET Window:**

- **ALL** : Total number of devices connected to NTRIP CASTER (Base + Rover) at the present time.
- **Base** : The total number of devices connected to the NTRIP CASTER as a Base at the present time.
- **Rover** : Total number of devices connected to the NTRIP CASTER as a Rover at the present time.

### **NTRIP Caster Admin Dashboard - Tab User.**

**User name/Login name** : Username for NTRIP Client account.

**Password** : Password for NTRIP Client / Server account

**Mountpoint** :Registered Mountpoint name for NTRIP Server (BaseStation) account.

**Rover Support** : Number of rovers sharing one account.

**VRS Support**: VRS support Flag . Tick select to enable it.

**STR** :

- STR editor displayed on Sourcetable for NTRIP Server (BaseStation) account.
- Setting the flag 'Enable use STR from Client' to TRUE will display the STR uploaded from the NTRIP Server (BaseStation) account set by the user.



- Setting the flag 'Enable use STR from Client' to FLASE will display the default STR set by the admin.

**Highest Bandwidth :**

- Set the highest speed limit for this account. If the speed counter exceeds this limit, the account will be permanently banned until the counter is cleared by the admin.
- Unit : bps (bit-per-second).
- If this account is used on more than one Rover at a time, the speed value will include the total speeds of all Rovers.
- Setting the value to 0 will disables this function.

**Max Total Bandwidth:**

- Set a limit for the total number of Bytes (In + Out) for this account.
- If the Byte count counter exceeds this limit, the account will be permanently banned until the counter is cleared by the admin.
- Unit : GB (Giga Byte).
- If this account is used on multiple Rovers at the same time, the Byte counter will include the total Bytes of all Rovers.
- Setting this value to 0 will disables this function.

**Max Total Time :**

- Set a time limit for this account.
- If the timer exceeds this limit, the account will be permanently banned until the timer is cleared by the admin.
- Unit : Second.
- If this account is used on multiple Rovers at the same time, the timer will include the total times of all Rovers.
- Setting this value to 0 will disables this function.



**Save the configure :**

- When doing any update, add new, edit, delete, ... any data field. All information will be stored in the RAM (temporary) of ESPrTk.
- A button will appear at the top of the Web page, clicking on it to save all changes to the ESPrTk FLASH memory.
- It may take more than 3 seconds to save to FLASH, which may cause the NTRIP connection to be interrupted, so be sure to only perform saving the configuration to FLASH when you are sure.

**NTRIP Caster Admin Dashboard - Tab Map.**

- Display all locations of NTRIP Rover and NTRIP Basestation on a single page.
- Clicking on the Marker will display a Pop-up detailing the NTRIP Rover / Basestation information.
- If a location cannot be found for that NTRIP account, the marker will be set to the default coordinate (0,0).

**NTRIP Caster Admin Dashboard - Tab Admin.**

- **Logout** : Log out of the Dashboard page.
- **Kick All Socket** : Disconnects all active NTRIP accounts.
- **Restart Caster** : Restart the NTRIP CASTER remotely.



## Configure ESPrtk - UART\_to\_WIFI\_Bridge mode

Main Action	Detail
UART_to_WIFI_Bridge	<ul style="list-style-type: none"><li>• Send data (from RX-UART-RTK) to (WIFI TCP/UDP Device)</li><li>• + Export data (from WIFI TCP/UDP Device) to TX-UART-RTK port as RTK Rover</li></ul>

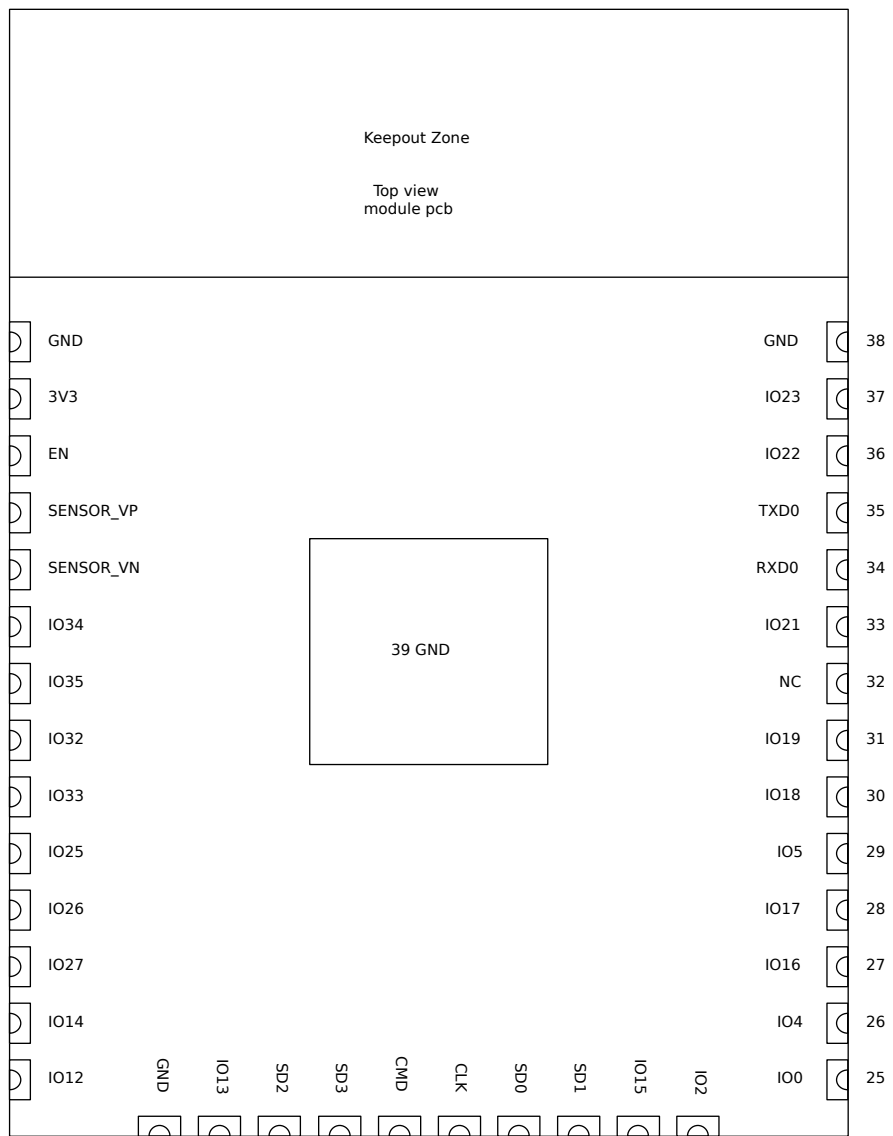
Other Action for UART_to_WIFI_Bridge	UART_to_WIFI_Bridge
Export IMU Data to TX_UART_0 port	•
Save NMEA/RTCM/RAW/.. Data (from RX-UART-RTK) to SD Card	•
Send NMEA/RTCM/RAW/.. Data (from RX-UART-RTK) to Bluetooth Client	•
Send IMU_1 Data to Bluetooth Client	•
Send IMU_2 Data to Bluetooth Client	•
Send Data (from RX-UART-RTK) to WiFi TCP/UDP device	•
Send IMU_1 Data to WiFi TCP/UDP device	•
Send IMU_2 Data to WiFi TCP/UDP device	•
Respond realtime command control on Bluetooth Client	•
Respond realtime command control on WiFi TCP/UDP	•



# ESP32 Pin Definitions

## ESP32 module

### Pin Layout





## Strapping Pins

ESP32 has five strapping pins, which can be seen in Chapter 6 Schematics:

- MTDI – GPIO12.
- GPIO0
- GPIO2
- MTDO - GPIO15.
- GPIO5

Software can read the values of these five bits from register "GPIO\_STRAPPING".

During the chip's system reset release (power-on-reset, RTC watchdog reset and brownout reset), the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down. The strapping bits configure the device's boot mode, the operating voltage of VDD\_SDIO and other initial system settings.

Each strapping pin is connected to its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impedance, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or use the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset release, the strapping pins work as normal-function pins.

Refer to Table 4 for a detailed boot-mode configuration by strapping pins.

Bootling Mode					
Pin	Default	SPI Boot		Download Boot	
GPIO0	Pull-up	1		0	
GPIO2	Pull-down	Don't-care		0	
Voltage of Internal LDO (VDD_SDIO)					
Pin	Default	3.3 V		1.8 V	
MTDI - GPIO12	Pull-down				
Enabling/Disabling Debugging Log Print over U0TXD During Bootling					
Pin	Default	U0TXD Active		U0TXD Silent	
MTDO - GPIO15	Pull-up	1		0	
Timing of SDIO Slave					
Pin	Default	Falling-edge Sampling Falling-edge Output	Falling-edge Sampling Rising-edge Output	Rising-edge Sampling Falling-edge Output	Rising-edge Sampling Rising-edge Output
MTDO - GPIO15	Pull-up	0	0	1	1



GPIO5	Pull-up	0	1	0	1
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Note :

- Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD\_SDIO)" and "Timing of SDIO Slave" after booting.
- Both ESP32-WROOM-32D and ESP32-WROOM-32U integrate a 3.3 V SPI flash, so the pin MTDI cannot be set to 1 when the modules are powered up.

## Electrical Characteristics

### Absolute Maximum Ratings

Stresses beyond the absolute maximum ratings listed in Table 5 below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device that should follow the recommended operating conditions.

Symbol	Parameter	Min	Max	Unit
VDD33	Power supply voltage	-0.3	3.6	V
$I_{\text{output}}^1$	Cumulative IO output current	-	[1,100 ]	mA
$T_{\text{store}}$	Storage temperature	-40	150	°C

1. The module worked properly after a 24-hour test in ambient temperature at 25 °C, and the IOs in three domains (VDD3P3\_RTC, VDD3P3\_CPU, VDD\_SDIO) output high logic level to ground. Please note that pins occupied by flash and/or PSRAM in the VDD\_SDIO power domain were excluded from the test.

2. Please see Appendix IO\_MUX of ESP32 Datasheet for IO's power domain.

### Recommended Operating Conditions

Symbol	Parameter	Min	Typical	Max	Unit
VDD33	Power supply voltage	3.0	3.3	3.6	V
$I_{\text{VDD}}$	Current delivered by external power supply	0.5	-	-	A
T	Operating temperature	-40	-	85	°C

### DC Characteristics (3.3 V, 25 °C)



Symbol	Parameter	Min	Typ	Max	Unit	
C_IN	Pin capacitance	-	2	-	pF	
V_IH	High-level input voltage	$0.75 \times V_{DD}$	-	$V_{DD1} + 0.3$	V	
V_IL	Low-level input voltage	-0.3	-	$0.25 \times V_{DD}$ <small>note1</small>	V	
I_IH	High-level input current	-	-	50	nA	
I_IL	Low-level input current	-	-	50	nA	
V_OH	High-level output voltage	$0.8 \times V_{DD1}$	-	-	V	
V_OL	Low-level output voltage	-	-	$0.1 \times V_{DD}$ <small>note1</small>	V	
I_OH	High-level source current ( $V_{DD1} = 3.3$ V, $V_{OH} \geq 2.64$ V output drive strength set to the maximum)	VDD3P3_CPU power domain <small>note2</small>	-	40	-	mA
		VDD3P3_RTC power domain <small>note2</small>	-	40	-	mA
		VDD_SDIO power domain <small>note3</small>	-	20	-	mA
I_OL	Low-level sink current ( $V_{DD1} = 3.3$ V, $V_{OL} = 0.495$ V, output drive strength set to the maximum)	-	28	-	mA	
R_PU	Resistance of internal pull-up resistor	-	45	-	k $\Omega$	
R_PD	Resistance of internal pull-down resistor	-	45	-	k $\Omega$	
V_IL_nRST	Low-level input voltage of CHIP_PU to power off the chip	-	-	0.6	V	

Notes:

1. Please see Appendix IO\_MUX of **ESP32 Datasheet** for IO's power domain. VDD is the I/O voltage for a particular power domain of pins.
2. For VDD3P3\_CPU and VDD3P3\_RTC power domain, per-pin current sourced in the same domain is gradually reduced from around 40 mA to around 29 mA,  $V_{OH} \geq 2.64$  V, as the number of current-source pins increases.
3. Pins occupied by flash and/or PSRAM in the VDD\_SDIO power domain were excluded from the test.

## Wi-Fi Radio

Parameter	Condition	Min	Typical	Max	Unit
Operating frequency range <small>note1</small>	-	2412		2484	MHz
Output impedance <small>note2</small>	-	-	note 2	-	$\Omega$



TX power <sup>note3</sup>	11n, MCS7	12	13	14	dBm
	11b mode	17.5	18.5	20	dBm
	11b, 1 Mbps	-	-98	-	dBm
	11b, 11 Mbps	-	-89	-	dBm
	11g, 6 Mbps	-	-92	-	dBm
	11g, 54 Mbps	-	-74	-	dBm
	11n, HT20, MCS0	-	-91	-	dBm
	11n, HT20, MCS7	-	-71	-	dBm
	11n, HT40, MCS0	-	-89	-	dBm
	11n, HT40, MCS7	-	-69	-	dBm
Adjacent channel rejection	11g, 6 Mbps	-	31	-	dB
	11g, 54 Mbps	-	14	-	dB
	11n, HT20, MCS0	-	31	-	dB
	11n, HT20, MCS7	-	13	-	dB

Note 1. Device should operate in the frequency range allocated by regional regulatory authorities.

Target operating frequency range is configurable by software.

Note 2. For the modules that use IPEX antennas, the output impedance is 50 Ω. For other modules without IPEX antennas,

users do not need to concern about the output impedance.

Note 3. Target TX power is configurable based on device or certification requirements.

## BLE Radio Receiver

Parameter	Conditions	Min	Typ	Max	Unit
Sensitivity @30.8% PER	-	-	-97		dBm
Maximum received signal @30.8% PER	-	0	-		dBm
Co-channel C/I	-	-	+10		dB
Adjacent channel selectivity C/I	F = F0 + 1 MHz	-	-5		dB
	F = F0 - 1 MHz	-	-5		dB
	F = F0 + 2 MHz	-	-25		dB
	F = F0 - 2 MHz	-	-35		dB
	F = F0 + 3 MHz	-	-25		dB



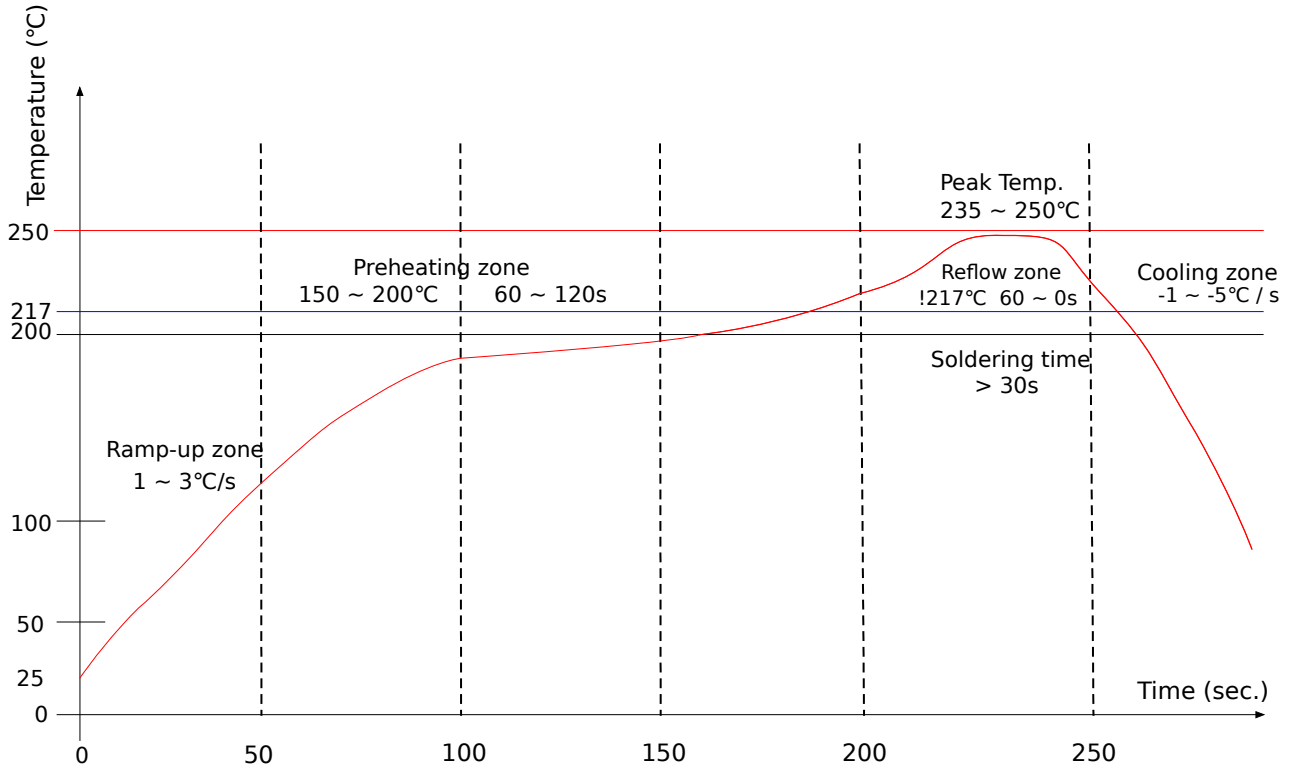
	F = F0 – 3 MHz	-	-45		dB
Out-of-band blocking performance	30 MHz ~ 2000 MHz	-10			dBm
	2000 MHz ~ 2400 MHz	-27			dBm
	2500 MHz ~ 3000 MHz	-27			dBm
	3000 MHz ~ 12.5 GHz	-10			dBm
	-	-36			dBm

## BLE Radio Transmitter .

Parameter	Conditions	Min	Typ	Max	Unit
RF transmit power	-	-	0		dBm
Gain control step	-	-	3		dBm
RF power control range	-	-12	-	+9	dBm
Adjacent channel transmit power	F = F0 ± 2 MHz	-	-52		dBm
	F = F0 ± 3 MHz	-	-58		dBm
	F = F0 ± > 3 MHz	-	-60		dBm
$\Delta f_{1_{avg}}$	-	-	-	265	kHz
$\Delta f_{2_{max}}$	-	247	-		kHz
$\Delta f_{1_{avg}} / \Delta f_{1_{avg}}$	-	-	-0.92		-
ICFT	-	-	-10		kHz
Drift rate	-	-	0.7		kHz/ 50 $\mu$ s
Drift	-	-	2		kHz



## Reflow Profile



Ramp-up zone — Temp.: <150°C Time: 60 ~ 90s Ramp-up rate: 1 ~ 3°C/s  
Preheating zone — Temp.: 150 ~ 200°C Time: 60 ~ 120s Ramp-up rate: 0.3 ~ 0.8°C/s  
Reflow zone — Temp.: >217°C 7LPH60 ~ 90s; Peak Temp.: 235 ~ 250°C (<245°C recommended) Time: 30 ~ 70s

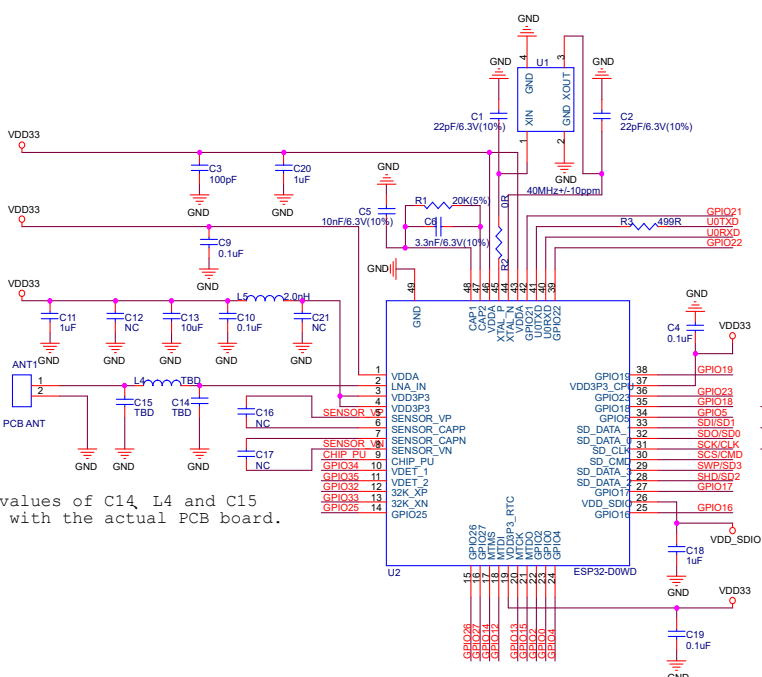


# ESP32-WROOM-32D/E Schematics

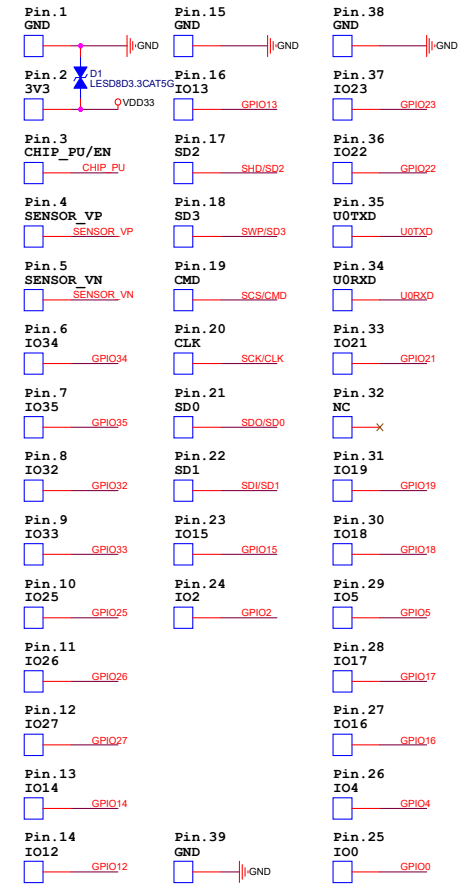
Note:

- Soldering Pad 39 to the Ground is not necessary for a satisfactory thermal performance. If users do want to solder it, they need to ensure that the correct quantity of soldering paste is applied.
- When ESP32 is powered on and off repeatedly by switching the power rails, and there is a large capacitor on the 3V3 rail, a discharge circuit can be added to the 3V3 rail to ensure proper power-on-reset. Please find the discharge circuit in Chapter Peripheral Schematics, in ESP32-WROOM-32 Datasheet.
- When battery is used as the power supply for ESP32 series of chips and modules, a supply voltage supervisor is recommended to avoid boot failure due to low voltage. Users are recommended to pull CHIP\_PU low if the power supply for ESP32 is below 2.3 V. For the reset circuit, please refer to Chapter Peripheral Schematics, in ESP32-WROOM-32 Datasheet.
- To ensure the power supply to the ESP32 chip during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually  $R = 10\text{ k}\Omega$  and  $C = 0.1\text{ }\mu\text{F}$ . However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32's power-up and reset sequence timing diagram, please refer to Section Power Scheme in ESP32 Datasheet.

The values of C1 and C2 vary with the selection of the crystal.



The values of C14, L4 and C15 vary with the actual PCB board.

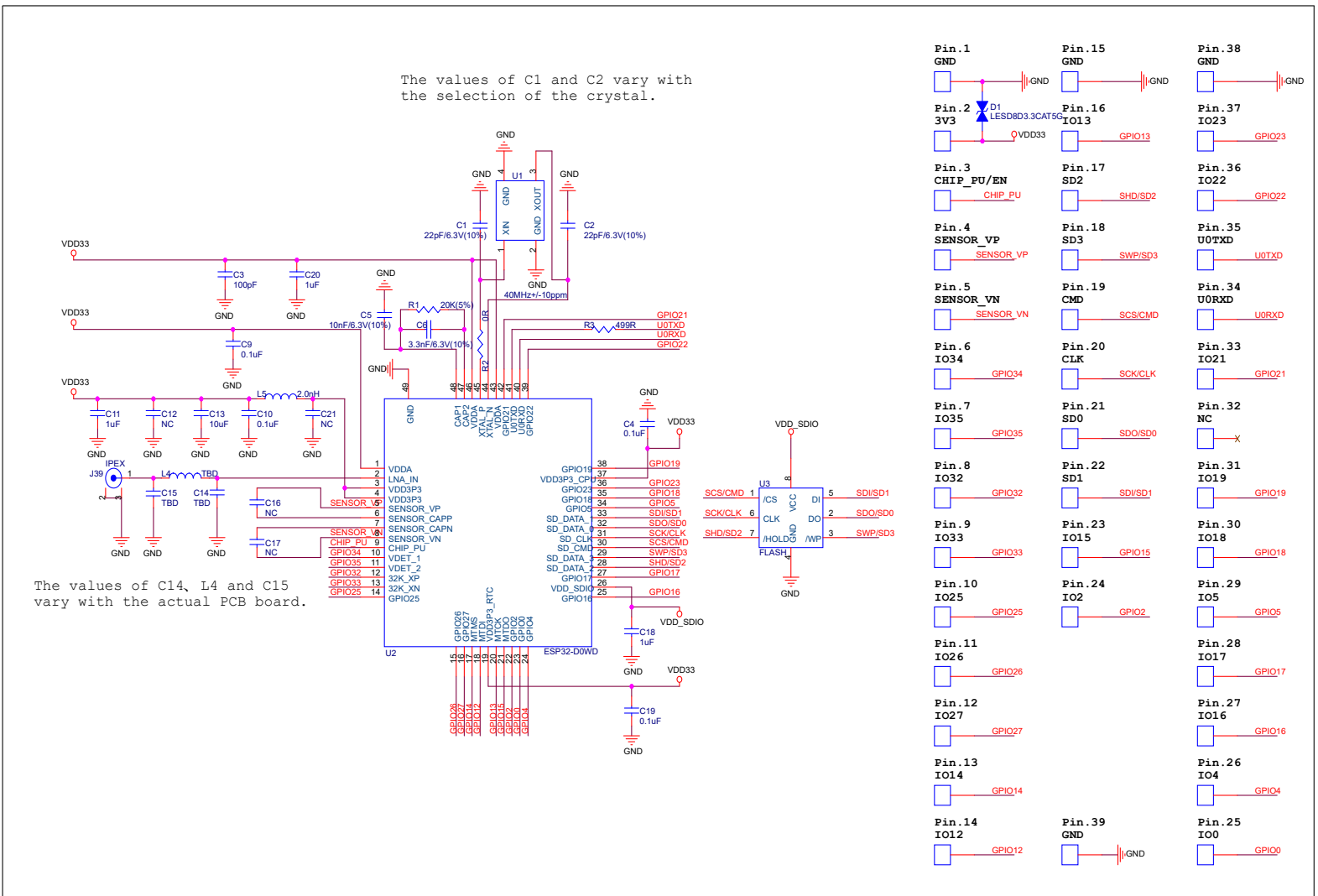




# ESP32-WROOM-32U/UE Schematics

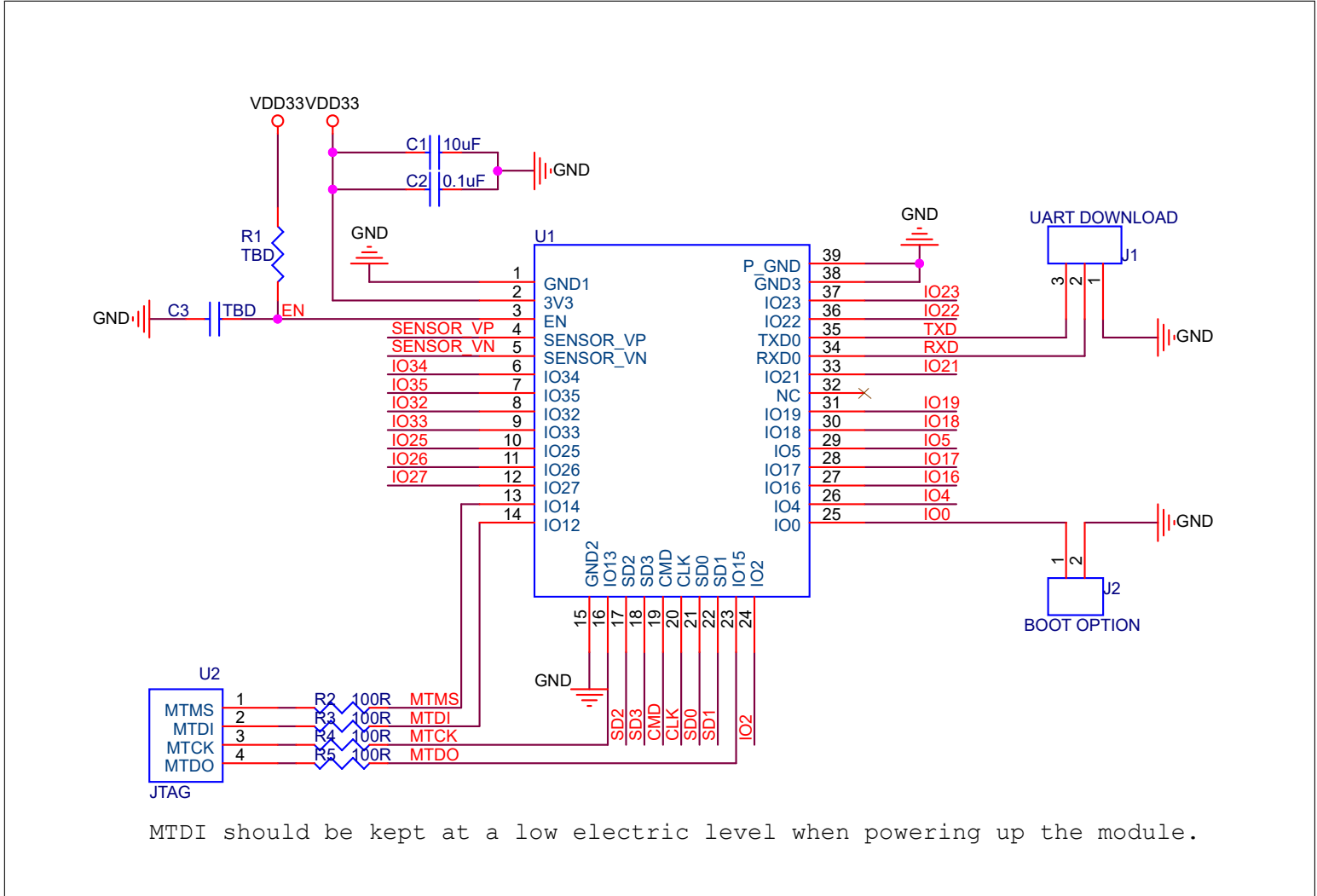
Note:

- Soldering Pad 39 to the Ground is not necessary for a satisfactory thermal performance. If users do want to solder it, they need to ensure that the correct quantity of soldering paste is applied.
- When ESP32 is powered on and off repeatedly by switching the power rails, and there is a large capacitor on the 3V3 rail, a discharge circuit can be added to the 3V3 rail to ensure proper power-on-reset. Please find the discharge circuit in Chapter Peripheral Schematics, in ESP32-WROOM-32 Datasheet.
- When battery is used as the power supply for ESP32 series of chips and modules, a supply voltage supervisor is recommended to avoid boot failure due to low voltage. Users are recommended to pull CHIP\_PU low if the power supply for ESP32 is below 2.3 V. For the reset circuit, please refer to Chapter Peripheral Schematics, in ESP32-WROOM-32 Datasheet.
- To ensure the power supply to the ESP32 chip during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually  $R = 10\text{ k}\Omega$  and  $C = 0.1\text{ }\mu\text{F}$ . However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32's power-up and reset sequence timing diagram, please refer to Section Power Scheme in ESP32 Datasheet.





## Peripheral Schematics



ESP32-WROOM-32D/E & ESP32-WROOM-32U/UE Peripheral Schematics



## ESPrtk PinMap

ESPrtk IO Name	GPIO	ESPrtk IO Name	GPIO	ESPrtk IO Name	GPIO
CWB_Button	13	RX_UART0	3	MOSI_SD_Card	23
MOSI_LoRa_Ethe	33	TX_UART0	1	MISO_SD_Card	39
MISO_LoRa_Ethe	35	RX_UART1	17	SCK_SD_Card	18
SCK_LoRa_Ethe	25	TX_UART1	5	CONNECT_LED	15
CS_SD_Card	19	RX_UART2	16	ERROR_LED	12
CS_LoRa	32	TX_UART2	4	TX_UART3	14
CS_Ethernet_PWR_GSM	0	SCL_I2C	22	SCL_OLED	27
RST_LoRa_Ethe	2	SDA_I2C	21	SDA_OLED	26
DI0_LoRa	34	RX_UART3	36		



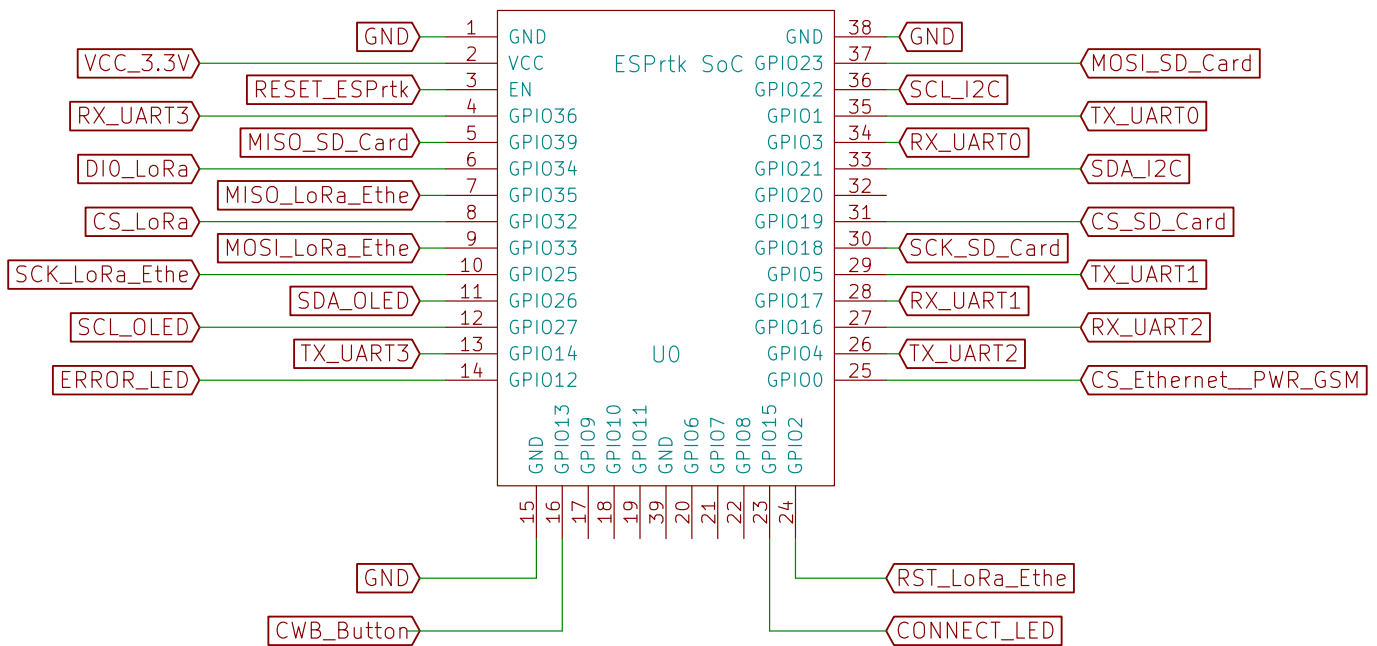
ESPrTk IO Name	GPIO	Input Pullup	Out	Type	Function
VCC_3.3V	VCC	●	○	○	Power input
GND	GND	○	●	○	Power ground
RESET_ESPrTk	EN	●	○	Inerrupt	Reset ESPrTk
ESPrTk IO Name	GPIO	Input Pullup	Out	Type	Function
CWB_Button	13	●	○	Inerrupt	Hold to Start WEB Configure
MOSI_LoRa_Ethe	33	○	●	SPI	Connect to MOSI pin on both LoRa and Ethernet module
MISO_LoRa_Ethe	35	●	○	SPI	Connect to MISO pin on both LoRa and Ethernet module
SCK_LoRa_Ethe	25	○	●	SPI	Connect to SCK pin on both LoRa and Ethernet module
CS_SD_Card	19	○	●	SPI	Connect to CS pin on SD /Micro SD Card module
CS_LoRa	32	○	●	SPI	Connect to CS pin on LoRa module
CS_Ethernet_PW R_GSM	0	○	●	SPI	Connect to CS pin on Ethernet module or Connect to PWR (Power KEY ON/OFF ) of GSM/Cellular module
RST_LoRa_Ethe	2	○	●	SPI	Connect to RESET pin on both LoRa and Ethernet module
DI0_LoRa	34	●	○	Inerrupt	Connect to DI0 pin on LoRa module
ESPrTk IO Name	GPIO	Input Pullup	Out	Type	Function
RX_UART0	3	●	○	UART	Flash/Update Firmware .- Command control – IMU Output Connect to TX_UART pin on HOST
TX_UART0	1	○	●	UART	Flash/Update Firmware .- Command control – IMU Output Connect to RX_UART pin on HOST
RX_UART1	17	●	○	UART	Connect to TX_A_UART GNSS RTK Receiver
TX_UART1	5	○	●	UART	Connect to RX_A_UART GNSS RTK Receiver



RX_UART2	16	●	○	UART	Connect to TX_B_UART GNSS RTK Receiver
TX_UART2	4	○	●	UART	Connect to RX_B_UART GNSS RTK Receiver
SCL_I2C	22	○	●	I <sup>2</sup> C / I2S	Connect to SCL pin on Other module ( IMU / Sensor / Clock ..) or Connect to NeoPixel Trips 4 LED
SDA_I2C	21	●	●	I <sup>2</sup> C	Connect to SDA pin on Other module ( IMU / Sensor / Clock ..)
RX_UART3	36	●	○	UART	Connect to TX-UART GSM/Cellular 2G/3G/4G/LTE module
<b>ESPrTk IO Name</b>	<b>GPIO</b>	<b>Input Pullup</b>	<b>Out</b>	<b>Type</b>	<b>Function</b>
MOSI_SD_Card	23	○	●	SPI	Connect to MOSI pin on SD /Micro SD Card module
MISO_SD_Card	39	●	○	SPI	Connect to MISO pin on SD /Micro SD Card module
SCK_SD_Card	18	○	●	SPI	Connect to SCK pin on SD /Micro SD Card module
CONNECT_LED	15	○	●	PWM	Connect to single LED (Pull Down) to show Connection Status
ERROR_LED	12	○	●	PWM	Connect to single LED (Pull Down) to show Error Status
TX_UART3	14	○	●	UART	Connect to RX-UART GSM/Cellular 2G/3G/4G/LTE module
SCL_OLED	27	○	●	I <sup>2</sup> C	Connect to SCL Pin on OLED SSD1306 /SH1106 Display
SDA_OLED	26	●	●	I <sup>2</sup> C	Connect to SDA Pin on OLED SSD1306 /SH1106 Display



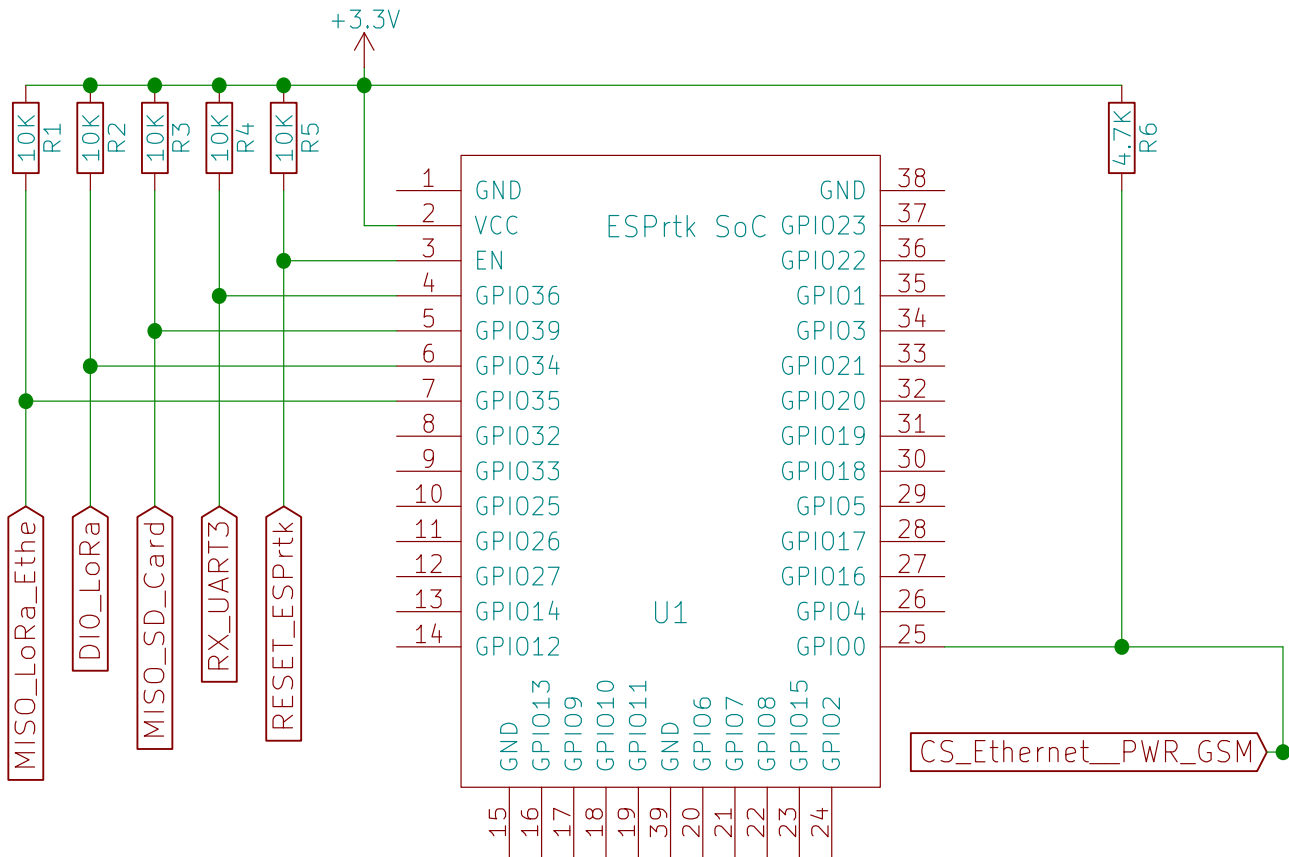
## ESPrtk Pin Out





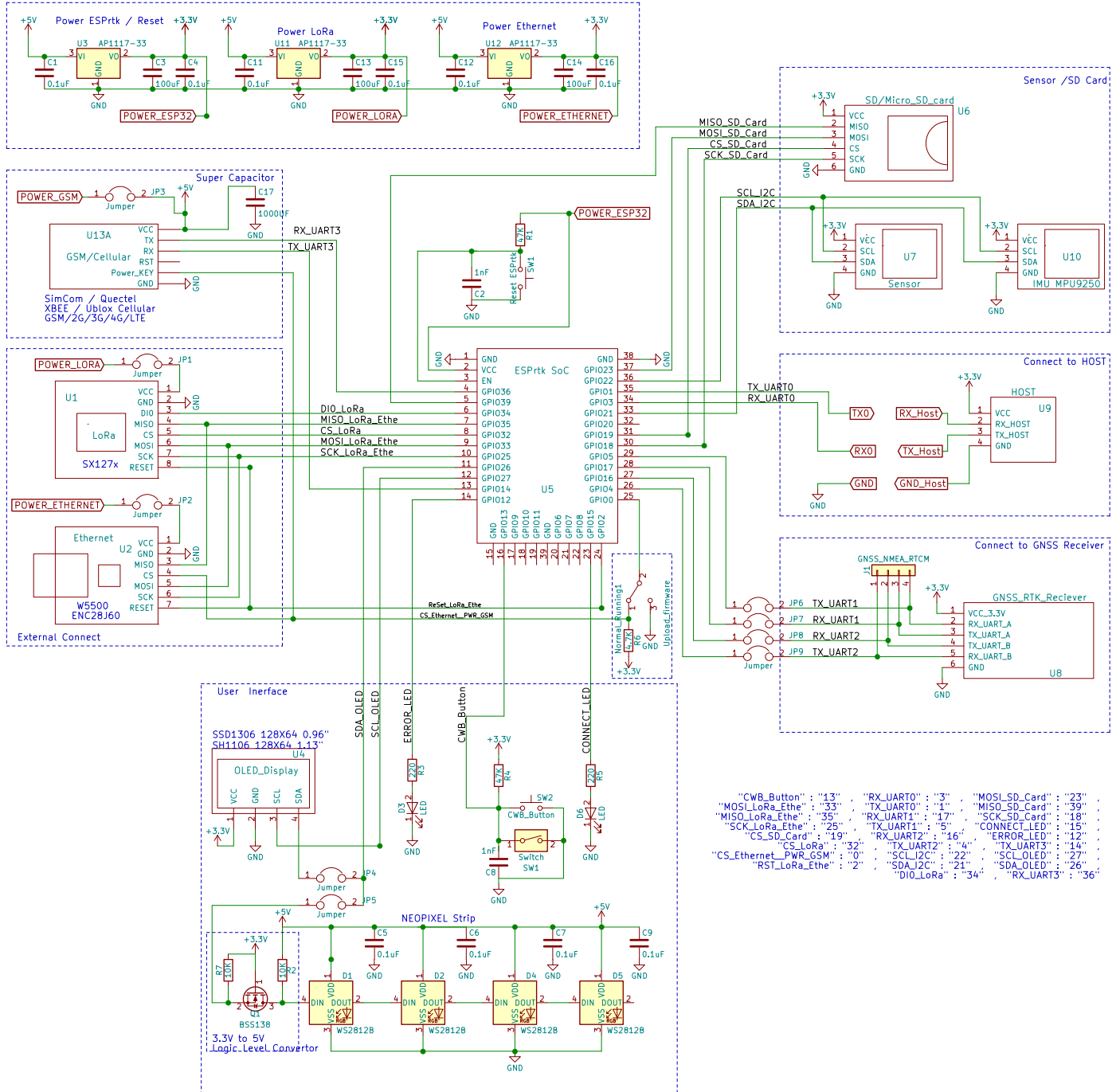
## Resistor Pull-Up Require.

The pins RESET, GPIO0, GPIO34, GPIO35, GPIO36, GPIO39 need to connect (always) with a pull-up resistor of 10K ohm (to 4.7K ohm).





# Suggest ESPrtk block diagram connection for mutil devices



```

"CWB_Button": "13", "RX_UART0": "3", "MISO_SD_Card": "23",
"MOSI_LoRa_Ethe": "33", "TX_UART0": "1", "MISO_SD_Card": "39",
"MISO_LoRa_Ethe": "35", "RX_UART1": "17", "SCK_SD_Card": "18",
"SCK_LoRa_Ethe": "25", "TX_UART1": "5", "CONNECT_LED": "15",
"CS_SD_Card": "19", "RX_UART2": "16", "ERROR_LED": "12",
"CS_LoRa": "32", "TX_UART2": "4", "TX_UART3": "14",
"CS_Ethernet_PWR_GSM": "0", "SCL_I2C": "22", "SCL_OLED": "27",
"RST_LoRa_Ethe": "2", "SDA_I2C": "21", "SDA_OLED": "26",
"DIO_LoRa": "34", "RX_UART3": "36"

```



## Custom Pin Map

This is an advanced feature that allows users to interfere into the output controller by pin mapping on ESP32 to ESPrtk ..

In this way, the selection and placement of the output pins on ESP32 will not depend on the default configuration, making it easier for users to redesign their own ESPrtk PCB board.

Besides helping make PCB design more flexible, this feature allows ESPrtk to be compatible on all hardware boards with different pinout designs.

Users can change the pinmap configuration of ESPrtk with UART Configure or WEB Configure.

Configure	JSON Configure
<b>Default from factory</b>	<pre>{   "CWB_Button" : "13" ,      "RX_UART0" : "3" ,  "MOSI_SD_Card" : "23" ,   "MOSI_LoRa_Ethe" : "33" ,  "TX_UART0" : "1" ,  "MISO_SD_Card" : "39" ,   "MISO_LoRa_Ethe" : "35" ,  "RX_UART1" : "17" , "SCK_SD_Card" : "18" ,   "SCK_LoRa_Ethe" : "25" ,   "TX_UART1" : "5" ,  "CONNECT_LED" : "15" ,   "CS_SD_Card" : "19" ,      "RX_UART2" : "16" , "ERROR_LED" : "12" ,   "CS_LoRa" : "32" ,         "TX_UART2" : "4" ,  "TX_UART3" : "14" ,   "CS_Ethernet_PWR_GSM" : "0" , "SCL_I2C" : "22" , "SCL_OLED" : "27" ,   "RST_LoRa_Ethe" : "2" ,    "SDA_I2C" : "21" ,  "SDA_OLED" : "26" ,   "DI0_LoRa" : "34" ,       "RX_UART3" : "36" }</pre>
<b>Example configure of User</b>	<pre>{   "CWB_Button" : "36" ,      "RX_UART0" : "3" ,  "MOSI_SD_Card" : "15" ,   "MOSI_LoRa_Ethe" : "27" ,  "TX_UART0" : "1" ,  "MISO_SD_Card" : "2" ,   "MISO_LoRa_Ethe" : "19" ,  "RX_UART1" : "34" , "SCK_SD_Card" : "14" ,   "SCK_LoRa_Ethe" : "5" ,    "TX_UART1" : "4" ,  "CONNECT_LED" : "17" ,   "CS_SD_Card" : "13" ,      "RX_UART2" : "35" , "ERROR_LED" : "16" ,   "CS_LoRa" : "18" ,         "TX_UART2" : "12" , "TX_UART3" : "25" ,   "CS_Ethernet_PWR_GSM" : "0" , "SCL_I2C" : "33" , "SCL_OLED" : "22" ,   "RST_LoRa_Ethe" : "23" ,   "SDA_I2C" : "32" ,  "SDA_OLED" : "21" ,   "DI0_LoRa" : "26" ,       "RX_UART3" : "39" }</pre>



## Exceptions .

ESPPrk supports changing all output pins. However, not all configurations are accepted.

-Some GPIO pins of ESP32 cannot be used for ESPPrk if it does not fully support. See table below

GPIO (ESP32)	...map to ESPPrk ( Input )	.. map to ESPPrk ( Output )
Input-Output	Yes	Yes
Input Only	Yes	No
Output Only	No	Yes

Sometime the configuration is successfully saved (passes the Logic test) but ESPPrk will fail or not work properly, this depends on how the user configures and how ESP32 work with that configuration.

So users need to know the limitations of output pin on ESP32. Below is a brief summary.

GPIO	Input	Output	Notes
0	●	●	Pulled up when start
1	●	●	Debug output at boot . Update firmware to ESPPrk.
2	●	●	
3	●	●	Debug output at boot Update firmware to ESPPrk. HIGH at boot
4	●	●	
5	●	●	
6	○	○	Connected to the integrated SPI flash
7	○	○	Connected to the integrated SPI flash
8	○	○	Connected to the integrated SPI flash
9	○	○	Connected to the integrated SPI flash
10	○	○	Connected to the integrated SPI flash
11	○	○	Connected to the integrated SPI flash
12	●	●	Boot fail if pulled high
13	●	●	
14	●	●	
15	●	●	



GPIO	Input	Output	Notes
16	•	•	
17	•	•	
18	•	•	
19	•	•	
21	•	•	
22	•	•	
23	•	•	
25	•	•	
26	•	•	
27	•	•	
32	•	•	
33	•	•	
34	•	○	input only
35	•	○	input only
36	•	○	input only
39	•	○	input only

ESPrTk IO Name	0	1	2	3	4	5	12	13	14	15	16	17	18	19	21	22	23	25	26	27	32	33	34	35	36	39	
CWB_Button (IN)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
MOSI_LoRa_Ethe	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	○	○	○	○	
MISO_LoRa_Ethe (IN)	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•
SCK_LoRa_Ethe	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	○	○	○	○	
CS_SD_Card	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	○	○	○	○	
CS_LoRa	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	○	○	○	○	
CS_Ethernet_PWR_GSM	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	○	○	○	○	



RST_LoRa_Ethe	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○		
DI0_LoRa (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
RX_UART0 (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
TX_UART0	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
RX_UART1 (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
TX_UART1	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
RX_UART2 (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
TX_UART2	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
SCL_I2C	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
SDA_I2C	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
RX_UART3 (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
MOSI_SD_Card	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
MISO_SD_Card (IN)	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●		
SCK_SD_Card	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
CONNECT_LED	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
ESPrTk IO Name	0	1	2	3	4	5	12	13	14	15	16	17	18	19	21	22	23	25	26	27	32	33	34	35	36	39
ERROR_LED	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
TX_UART3	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
SCL_OLED	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	
SDA_OLED	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	○	○	○	○	



## UART / SD Card Driver on ESPrtk .

Besides the ability to map input / output pins.

For UART connection, there is an additional secondary mapping function, UART-Soft-Switch, for faster communication switching.

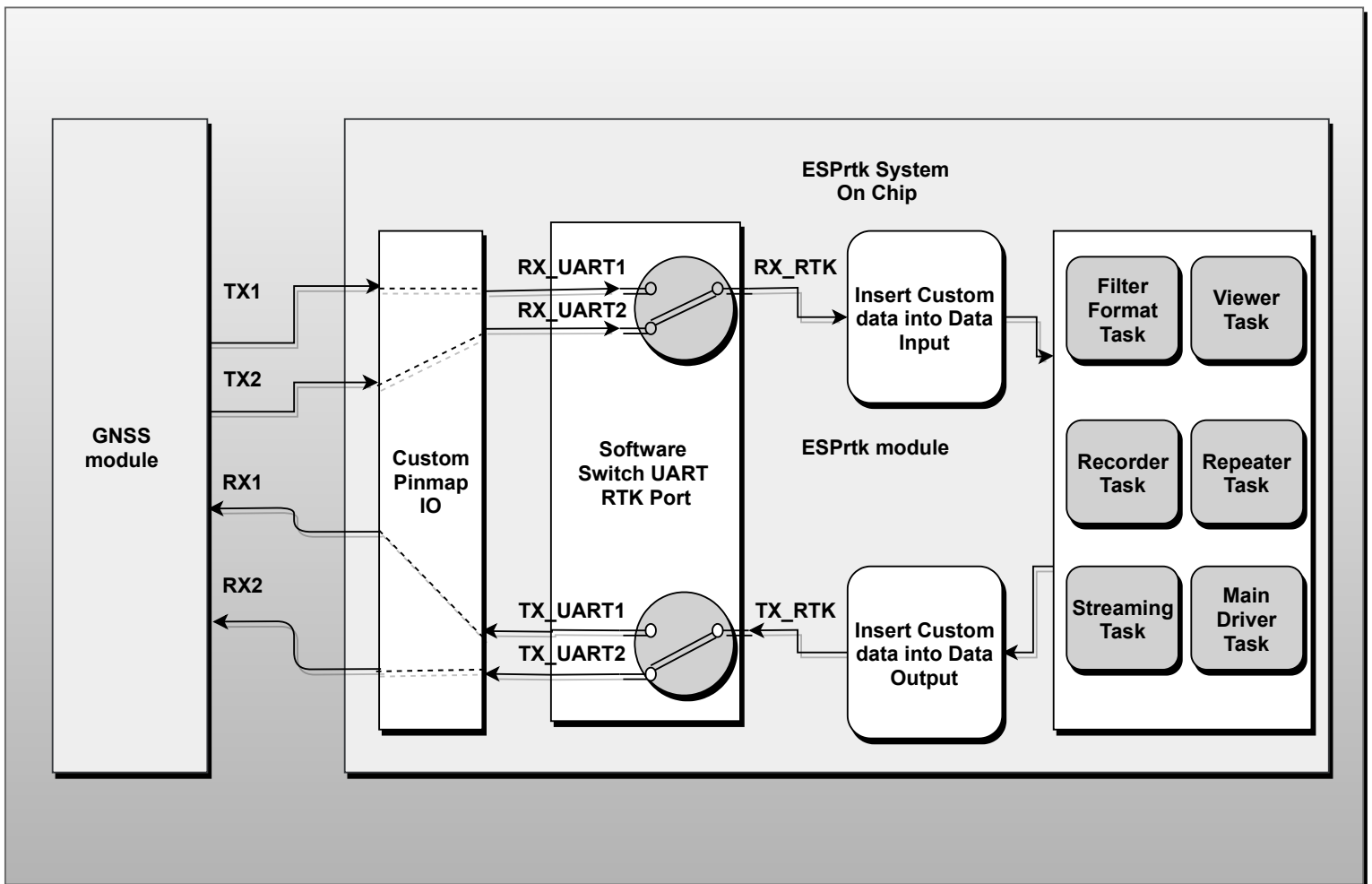
When running the application, the UART port with actual names are TX\_UART\_RTK and RX\_UART\_RTK will map to port TX\_UART1 (or TX\_UART2) and to port RX\_UART1 (or RX\_UART2).

For Base / Rover RTK applications, UART Driver also supports a lot of input data filters, supports inserting any data (default data) of users up to 500 Bytes on both TX / RX. The insert processing will be done automatically to ensure the main data stream will not be interrupted.

Data from filters and inserts will be forwarded to other processing tasks, including the Recorder Task.

Real-time capture and data storage will be performed by SD\_Card Driver. Here, NMEA / RTCM / RAW,... data continues to be processed before storing.

SD\_Card Driver on ESPrtk 3.0.0 supports many different recording types, file types, automation and card data protection.





## **Display for user communication and Sensor.**

When running Main Action mode, information about the status of ESPrtk such as Error, Thread Status, IMU Sensor Data, PING response, Control Command response, etc. will be exported to TX\_UART0 port as ASCII character. (can read and understand).

All outputs are assigned an ID to distinguish and in the proprietary format of ESPrtk TM.

In addition, information exported on the TX\_UART0 port can also be controlled (turned on / off) by default settings or turned on / off at run time via the Control Command from HOST.

For intuitive status display, ESPrtk supports display by 128x64 OLED display, NEOPIXEL LED strip and status LED.

ESPrtk also supports IMU peripheral sensor. (Accelerometer / Gyroscope / Magnetometer). High-precision IMU / INS data is processed in real time with low delay, sensor read-up frequency can up to 200Hz.

The CWB\_Button use to start WEB Configure mode by hold it in 3 second ( set to Low level).



## Symbol Type Value

Type value	Characters contain	Example	Notes
[0 → 9]	0123456789	0 , 123, 457	Number only
[a → z]	abcdefghijklmnopqrstuvwxyZ	esprtk	
[A → Z]	ABCDEFGHIJKLMNopqrstUVWX YZ	ESPRTK	
[INTEGER]	-0123456789	0 , -123, -457	Number only and ‘-’
[FLOAT]	-0123456789.	0.123 , -12.23 , 67.97	Number only and ‘-’ and ‘.’
[BIT]	01	011101, 1111001, 001	‘0’ and ‘1’ only
[HEX_Up]	0123456789ABCDEF	A0,B0, C045, AD7C, A8E4C0D2	1 byte of data must be represented by 2 characters.
[HEX]	0123456789acdbefABCDEF	A0,b7, a3ee, B3f5, A8E4c0d2	1 byte of data must be represented by 2 characters.
[<CR><LF>]	2 byte value are 0x0D , 0x0A		
[PRINT]	abcdefghijklmnopqrstuvwxyZ ABCDEFGHIJKLMNopqrstUVWX YZ0123456789 "#%&'()+,-./:;<=>@^`'{}~	Hello_ESPrtk_01 , Hello-ESPrtk-02 , Hello ESPrtk \$# ,	Not allow contain <CR><LF>, \$*
[STRING]	AbcdefghijklmnopqrstuvwxyZ ABCDEFGHIJKLMNopqrstUVWX YZ0123456789 -_+(.):,	Hello_ESPrtk_01 , Hello-ESPrtk-02 ,	Not allow contain <CR><LF>, <b>WhiteSpace</b> , ! =&"~</>? %#[]{}^\$*
[PASS_A]	[STRING]		Not allow contain <CR><LF>, , !=&"~</>?  %#[]{}^\$*
[PASS_B]	[PASS_A]		Not allow contain WhiteSpace
[PASS_C]	[PASS_A]		Must contain atleast 1 Upper Case and 1 Lower Case and 1 Number Min length 8 chars
[PASS_D]	[PASS_C]		Not allow contain WhiteSpace
[AT_Code]	[PRINT]	[AT+CMT=0]	Not allow contain !&~? %



## Format the message frame communicating on the port UART0.

### Message Frame:

<Header> + <Length\_Payload> + <Payload> + <\*CRC> + <CR> <LF>

Example : \$ESPLOG|25|2|INFO|GO to MAIN ACTION|\*6360

Label	Characters allowed to contain.
<Header>	[0 → 9] [a → z] [A → Z]
<Length_Payload>	[0 → 9]
<Payload>	[ASC]
<*CRC>	[HEX_Up]
<CR><LF>	[<CR><LF>]

Label	Sub	Min Bytes	Max Bytes	Describe
<Header>	'\$' + 'Header_Name' + ' '	3	10	Start Message
<Length_Payload>	'Length_Payload' + ' '	2	10	Numbers Bytes of Payload
<Payload>	'Payload'	1	Length_Payload	Payload data
<*CRC>	'*' + 'CRC_16'	5	5	Checksum of Message
<CR><LF>	0x0D + 0x0A	2	2	End Message

	<Header>	<Length_Payload>	<Payload>	<*CRC>	<CR><LF>
Ex 1	\$ESPLOG	25	2 INFO GO to MAIN ACTION	*6360	\r\n
Ex 2	\$ESPLOG	34	1 ERROR 0,0,G-G-G-G,  No ERROR	*7A58	\r\n



Ex 3	\$ESP_OK	5	X _	*5309	\r\n
Ex 4	\$ESP_OK	14	W m 3 0 0 0 0	*6D76	\r\n

## Length\_Payload calculate.

- Example message : \$ESP\_OK|14|W|m|3|0|0|0|0|\*6D76
- Then Payload range is : **W|m|3|0|0|0|0|** and Total of characters (Length) is **14**

## CRC calculate.

CRC\_Range calculate from after '\$' to begin '\*' ( not contain '\$' and '\*')

'Header\_Name' + '|' + <Length\_Payload> + <Payload>

- Example message : \$ESP\_OK|14|W|m|3|0|0|0|0|\*6D76
- Then CRC Range is: **ESP\_OK|14|W|m|3|0|0|0|0|**

## CRC16 Algorithm calculate in C/C++ for ESPrtk frame:

```

const char MSG[] = "$ESP_OK|14|W|m|3|0|0|0|0|*????\r\n";

// Calculate CRC
uint8_t FIRST_CRC = 0;
uint8_t SECOND_CRC = 0;
uint16_t i = 0;

while ( MSG [i] != '*' ){
    // CRC_Range calculate from after '$' to begin '*' ( not contain '$' and '*')
    if ( MSG [i] != '$' ){
        FIRST_CRC ^= ( uint8_t ) MSG [i];
        SECOND_CRC ^= ( uint8_t ) FIRST_CRC;
    }
    i++;
}

//Format CRC to [HEX_Up] string and store to buffer
char CRC16_OUT [4+1];
sprintf ( CRC16_OUT , "%02X%02X" , FIRST_CRC , SECOND_CRC );

//Print out result
printf ( "\n Your CRC16 is %s \n", CRC16_OUT);

```



//Result should be [ Your CRC16 is 6D76 ]

## ESPrTk support suggestions for fixing errors.

When ESPrTk receives an incorrectly structured message frame, it returns a NACK message.

If the message is valid and corrupted, ESPrTk will give an error and suggest correction.

A valid structured message (minimum) must include <Header> <Length\_Payload> <Payload> <\*CRC>, for example: \$ESP\_OK|??|?|?\*????

**Note :** The error correction suggestion function is only fully supported when running in UART Configure mode.

Examples:

HOST Send	\$ESP_OK ?? ? ?*????
Respond	NACK : [?] LENGTH_MESSAGE invalid (not a number) - [?] Do you mean LENGTH_MESSAGE = 4

HOST Send	\$ESP_OK 4 ? ? ?*????
Respond	NACK : Your_CRC = [????]: [?] Do you mean Checksum_CRC = 295A

HOST Send	\$ESP_OK ? P _ ?*????
Respond	NACK : [?] LENGTH_MESSAGE invalid (not a number) - [?] Do you mean LENGTH_MESSAGE = 5

HOST Send	\$ESP_OK 5 P _ ?*????
Respond	NACK : Your_CRC = [????]: [?] Do you mean Checksum_CRC = 5B01

HOST Send	\$ESP_OK 5 P _ *5B01
-----------	----------------------



Respond	\$ESP_OK 5 P _*5B01
---------	---------------------



## Types of message frame

Type frame	<Header>	Describe
LOG_FRAME	\$ESPLOG	Output status, information of ESPrtk
IMU_FRAME	\$ESPIM1	IMU / INS data output type 1
	\$ESPIM2	IMU / INS data output type 2
COMMAND_FRAME	\$ESP_OK	Respond to HOST with ACK status (non encrypt Payload) . *
	\$ESS_OK	Respond to HOST with ACK status (BitWise encrypt Payload).*
	\$AES_OK	Respond to HOST with ACK status (AES256 encrypt Payload).*
	\$ESP_ER	Respond to HOST with NACK status (non encrypt Payload) . *
	\$ESS_ER	Respond to HOST with NACK status (BitWise encrypt Payload).*
	\$AES_ER	Respond to HOST with NACK status (AES256 encrypt Payload).*

\* Tip :

ACK status : ESPrtk accept command message from HOST.

NACK status: ESPrtk receive a wrong format command message from HOST, so ESPrtk will ignore this command (not accept).

BitWise/AES256 encrypt payload : Payload data will be encrypt before export , please read more to learn about this feature.

## \$ESPLOG Message

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESPLOG xx	Type Log in Number	Type Log in String	Infor 1	Infor 2	Infor 3	Infor 4	...

PL0	Describe	Example
0	ESPrtk System	\$ESPLOG xx 0 SYSTEM ...
1	Error status	\$ESPLOG xx 1 ERROR ...
2	Text , Log, Information...	\$ESPLOG xx 2 INFO ...
3	Go to function status	\$ESPLOG xx 3 GOIN ...
4	Wifi Scan Result	\$ESPLOG xx 4 WFSCAN ..
5	Broker MQTT Status	\$ESPLOG xx 5  BROKER ...
6	Before print NMEA from Rover	\$ESPLOG xx 6  RVNMEA ...
7	Configure information detail	\$ESPLOG xx 7 CONFIG ...



## \$ESPIM1 Message

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL0	[FLOAT]			0.00	0	15	Raw Gyroscope X Axis	deg/s
PL1	[FLOAT]			0.00	0	15	Raw Gyroscope Y Axis	deg/s
PL2	[FLOAT]			0.00	0	15	Raw Gyroscope Z Axis	deg/s
PL3	[FLOAT]			0.00	0	15	Raw Magnetometer X Axis (micro-Tesla)	uT
PL4	[FLOAT]			0.00	0	15	Raw Magnetometer Y Axis (micro-Tesla)	uT
PL5	[FLOAT]			0.00	0	15	Raw Magnetometer Z Axis (micro-Tesla)	uT
PL6	[FLOAT]			0.00	0	15	Raw Accelerometer X Axis ( scale 0.1 m/s^2)	-
PL7	[FLOAT]			0.00	0	15	Raw Accelerometer Y Axis ( scale 0.1 m/s^2)	-
PL8	[FLOAT]			0.00	0	15	Raw Accelerometer Z Axis ( scale 0.1 m/s^2)	-
PL9	[FLOAT]			0.00	0	15	Temperature sensor	°C
PL10	[FLOAT]			0.00	0	15	Magnetometer X Axis + Calibrated	-
PL11	[FLOAT]			0.00	0	15	Magnetometer Y Axis + Calibrated	-
PL12	[FLOAT]			0.00	0	15	Magnetometer Z Axis + Calibrated	-

Example:

```

$ESPIM2|81|0.16|-0.09|-0.98|0.04|168.72|-172.96|-18.37|39.75|||||166.81|-163.44|19.96|53.70|*5172
$ESPIM1|81|82.32|199.63|172.13|-2.40|-7.20|-50.41|0.54|-0.52|-0.57|29.17|-2.40|-7.20|-50.41|*186D
$ESPIM2|82|0.35|-0.25|-0.88|0.20|136.90|-141.23|-31.31|21.44|||||139.56|-141.49|-30.51|22.45|*750C
$ESPIM1|84|178.90|116.04|202.62|17.55|-21.91|-30.16|0.57|-0.76|-0.12|29.16|17.55|-21.91|-30.16|
*2071
$ESPIM2|82|0.57|-0.51|-0.57|0.30|79.64|-100.98|-20.24|334.15|||||83.66|-106.79|-20.59|315.65|*7D05
$ESPIM1|82|117.38|127.38|185.91|37.51|-10.50|-8.85|-0.09|-0.79|0.14|29.16|37.51|-10.50|-8.85|*2211
$ESPIM2|77|0.66|-0.60|-0.20|0.40|51.81|-78.48|12.85|316.72|||||52.77|-79.97|6.36|316.71|*4774
$ESPIM1|76|-12.68|51.89|19.82|39.61|10.80|2.55|-0.66|-0.60|0.13|29.16|39.61|10.80|2.55|*3F7F
$ESPIM2|77|0.63|-0.64|0.03|0.45|41.11|-76.36|38.07|295.72|||||41.76|-76.70|35.26|303.99|*5E7E
$ESPIM1|79|-170.67|-256.16|-166.71|41.41|8.25|0.60|-0.30|-0.80|0.21|29.16|41.41|8.25|0.60|*004B
$ESPIM2|78|0.59|-0.60|-0.19|0.50|62.77|-77.32|21.63|314.30|||||54.44|-77.11|23.91|309.77|*7C09
$ESPIM1|86|-160.12|-91.22|-182.01|30.01|-17.70|-25.81|0.61|-0.86|-0.59|29.17|30.01|-17.70|-25.81|
*3C50
$ESPIM2|81|0.45|-0.47|-0.71|0.25|99.49|-120.54|-23.98|344.87|||||93.43|-97.15|-19.13|336.54|*433B

```



## \$ESPIM2 Message

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL0	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion - QW	-
PL1	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion - QX	-
PL2	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion - QY	-
PL3	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion - QZ	-
PL4	[FLOAT]	0.00	360.0	0.00	0	15	DMP-Euler YAW	deg
PL5	[FLOAT]	-180.0	180.0	0.00	0	15	DMP-Euler PITCH	deg
PL6	[FLOAT]	-90.0	90.0	0.00	0	15	DMP-Euler ROLL	deg
PL7	[FLOAT]	0.00	360.0	0.00	0	15	Compass Heading (using magnetometer calibrated) + Tilt compensation	deg
PL8	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion -QW+ Extended Kalman Filter	-
PL9	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion -QX+ Extended Kalman Filter	-
PL10	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion -QY+ Extended Kalman Filter	-
PL11	[FLOAT]	-1.00	1.00	0.00	0	15	DMP-Quaternion -QZ+ Extended Kalman Filter	-
PL12	[FLOAT]	0.00	360.0	0.00	0	15	DMP-Euler YAW + Extended Kalman Filter	deg
PL13	[FLOAT]	-180.0	180.0	0.00	0	15	DMP-Euler PITCH + Extended Kalman Filter	deg
PL14	[FLOAT]	-90.0	90.0	0.00	0	15	DMP-Euler ROLL + Extended Kalman Filter	deg
PL15	[FLOAT]	0.00	360.0	0.00	0	15	Compass Heading (using magnetometer calibrated) + Tilt compensation +Extended Kalman Filter	deg

### Example:

```

$ESPIM2|81|0.16|-0.09|-0.98|0.04|168.72|-172.96|-18.37|39.75|||||166.81|-163.44|19.96|53.70|*5172
$ESPIM2|82|0.35|-0.25|-0.88|0.20|136.90|-141.23|-31.31|21.44|||||139.56|-141.49|-30.51|22.45|*750C
$ESPIM2|82|0.57|-0.51|-0.57|0.30|79.64|-100.98|-20.24|334.15|||||83.66|-106.79|-20.59|315.65|*7D05
$ESPIM2|77|0.66|-0.60|-0.20|0.40|51.81|-78.48|12.85|316.72|||||52.77|-79.97|6.36|316.71|*4774
$ESPIM2|77|0.63|-0.64|0.03|0.45|41.11|-76.36|38.07|295.72|||||41.76|-76.70|35.26|303.99|*5E7E
$ESPIM2|78|0.59|-0.60|-0.19|0.50|62.77|-77.32|21.63|314.30|||||54.44|-77.11|23.91|309.77|*7C09

```



## \$ESP\_xx - \$ESS\_xx - \$AES\_xx Message

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	Type Command	ID Command	Infor 1	Infor 2	Infor 3	Infor 4	...

PL0	Describe Type Command	Command
'N'	Start WEB Configure mode	\$ESP_OK 5 N _*451F
'O'	Start UART Configure mode	\$ESP_OK 5 O _*441E
'X'	Start Main Action mode	\$ESP_OK 5 X _*5309
'P'	PING to ESPrtk	\$ESP_OK 5 P _*5B01
'Q'	Quit UART Configure mode	\$ESP_OK 5 Q _*5A00
'R'	Read data configure on ESPrtk	\$ESP_OK xx R ....
'W'	Write configure to ESPrtk	\$ESP_OK xx W ....
'E'	Export configure as example	\$ESP_OK 5 E _*4E14
'T'	Hardware control	\$ESP_OK xx T ....



PL0	Type Command	UART Configure Mode support this command ?	Main Action Mode support this command ?	WEB Configure Mode support this command ?	WEB Configure Mode Support ?- Command Tester Tool
'N'	Start WEB Configure mode	●	●	●	●
'O'	Start UART Configure mode	●	●	●	●
'X'	Start Main Action mode	●	●	●	●
'P'	PING to ESPrTk	●	●	●	●
'Q'	Quit UART Configure mode and jump to Main Action mode	●	○	○	○
'R'	Read data configure on ESPrTk	●	○	○	●
'W'	Write configure to ESPrTk	●	○	○	●
'E'	Export configure as example	●	○	○	●
'T'	Hardware control	●	○	○	○
<b>Exception support</b>					
'T'	Hardware control (Control type PRINT output on TX_UART0 )	●	●	●	●
'T'	Hardware control (Control GPIO ESPrTk )	●	●	●	●
'R'	Request ERROR_SYSTEM	●	●	●	●



PL0	HOST send command Start WEB Configure mode	ESPrtk respond		
		ACK	NACK	Max delay
'N'	\$ESP_OK 5 N _ *451F	\$ESP_OK 5 N _ *451F	\$ESP_ER xx N ..	8 Second

PL0	HOST send command Start UART Configure mode	ESPrtk respond		
		ACK	NACK	Max delay
'O'	\$ESP_OK 5 O _ *441E	\$ESP_OK 5 O _ *441E	\$ESP_ER xx O ..	4 Second

PL0	HOST send command Start Main Action mode	ESPrtk respond		
		ACK	NACK	Max delay
'X'	\$ESP_OK 5 X _ *5309	\$ESP_OK 5 X _ *5309	\$ESP_ER xx X ..	4 Second

PL0	HOST send command PING to ESPrtk	ESPrtk respond		
		ACK	NACK	Max delay
'P'	\$ESP_OK 5 P _ *5B01	\$ESP_OK 5 P _ *5B01	\$ESP_ER xx P ..	2 Second

PL0	HOST send command Quit UART Configure mode	ESPrtk respond		
		ACK	NACK	Max delay
'Q'	\$ESP_OK 5 Q _ *5A00	\$ESP_OK 5 Q _ *5A00	\$ESP_ER xx Q ..	1 Second



## Start Main Action mode.

By default, ESPrtk after supplying power (or RESET ) will enter Main Action mode.

## Use ESPrtk command to start Main Action mode

Use ESPrtk command control	
Step 0	ESPrtk after supplying power.
Step 2	HOST send command : <b>\$ESP_OK 5 X _ *5309</b>
Done	ESPrtk will start go to Main Action mode.
Success	The CONNECT_LED blink slow. ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 X _ *5309</b>

## Use the RESET button to start Main Action mode

Method 2: Use only the CWB button	
Step 0	ESPrtk after supplying power.
Done	Press RESET button (set EN pin to Low level) , then release. → ESPrtk will start go to Main Action mode.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 X _ *5309</b>



## Start UART Configure mode for Write configure data.

### Use ESPrtk command to start UART configure

Use ESPrtk command control	
Step 0	ESPrtk after supplying power.
Step 2	HOST send command : <b>\$ESP_OK 5 O _ *441E</b>
Done	ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 O _ *441E</b>

## Command Write Configure ESPrtk

**Tip :** To use these command , ESPrtk need running at UART Configure mode !

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	ID Command	Infor 1	Infor 2	Infor 3	Infor 4	...

PL0	PL1	Describe Type Command	Example
'W'	'c'	Write YOUR_PROFILE 's configure data	
'W'	'd'	Write ACTION_PLANNING 's configure data	
'W'	'e'	Write INTNERNET 's configure data	
'W'	'f'	Write RADIO_RTK 's configure data	
'W'	'g'	Write MQTT_RTK 's configure data	
'W'	'h'	Write NTRIP_CLIENT 's configure data	
'W'	'i'	Write NTRIP_MASTER 's configure data	
'W'	'j'	Write UART_CONFIGURE 's configure data	
'W'	'k'	Write BLUETOOTH 's configure data	
'W'	'l'	Write DISPLAY_VIEWER 's configure data	



'W'	'm'	Write EVENT_LOG 's configure data	
'W'	'n'	Write SIMPLE_DEBUG 's configure data	
'W'	'o'	Write SD_CARD 's configure data	
'W'	'p'	Write IMU_MPU9250 's configure data	
'W'	'q'	Write GPIO_PIN_MAP 's configure data	
'W'	'r'	Write SYSTEM_Other_Mode 's configure data	
'W'	's'	Write GSM_CELLULAR 's configure data	
'W'	't'	Write STREAM_MANAGER's configure data	
'W'	'u'	Write POSITION_ANTENNA's configure data	
'W'	'v'	Write WIFI_TCP_UDP's configure data	
'W'	'w'	Write NTRIPCASTER_Admin's configure data	
'W'	'x'	Write NTRIPCASTER_ACC's configure data	





PL0	PL1	PL2	Enable Hotspot Security
'W'	'c'	'0'	Disable Hotspot Security
		'1'	Enable Hotspot Security

PL0	PL1	PL9	Allow create new Profile
'W'	'c'	'0'	Not allow create new Profile
		'1'	Allow create new Profile

PL0	PL1	PL10	Type CSS theme WEB Configure's interface
'W'	'c'	'0'	Default – BGW theme
		'1'	BWR theme
		'2'	BGG theme
		'3'	Other theme
		'4'	Other theme

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'c'	STRING	-	-	1	1	ID Configure : YOUR_PROFILE	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

**Note:** This configure only work on WEB Configure interface !



**Message :**

HOST Send	\$ESP_OK 80 W c ESPrTk : IHGG4 def123DEF 0 admin abc123ABC ESPrTk new user Hello member 1 0 *134C
ACK Respond	\$ESP_OK 46 W c 1 ( ID : YOUR_PROFILE ) : Saved Success . *3B1B
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - ACTION\_PLANNING

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'd'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : ACTION\_PLANNING

Number of field values : 9

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	1	10000	10	-	-	Max Rover	
PL3	INTEGER	1	10000	1	-	-	ID Rover	
PL4	INTEGER	0	14	8	-	-	Type Baudrate UART_0	
PL5	INTEGER	0	14	6	-	-	Type Baudrate UART_1	
PL6	INTEGER	0	14	6	-	-	Type Baudrate UART_2	
PL7	INTEGER	0	1	1	-	-	Map TX-UART-RTK	
PL8	INTEGER	0	1	0	-	-	Map RX-UART-RTK	
PL9	INTEGER	0	17	0	-	-	Main Action	
PL10	BIT	-	-	00000000000000000000	19	19	Other action	



**TIP:** Note, when Internet method using GSM/Cellular module, the UART2 baudrate must equal to UART1 baudrate.

PL0	PL1	PL4	Type Baudrate UART_0	Unit
		PL5	Type Baudrate UART_1	
		PL6	Type Baudrate UART_2	
'W'	'd'	0	1200	bps
		1	2400	bps
		2	4800	bps
		3	9600	bps
		4	19200	bps
		5	38400	bps
		6	57600	bps
		7	115200	bps
		8	230400	bps
		9	250000	bps
		10	460800	bps
		11	500000	bps
		12	921600	bps
		13	1000000	bps
		14	2000000	bps

**TIP:** Note, when Internet method using GSM/Cellular module, the UART2 baudrate must equal to UART1 baudrate.

PL0	PL1	PL7	Map TX-UART-RTK	Unit
'W'	'd'	0	Map TX-UART-RTK to TX_UART_1 port	
		1	Map TX-UART-RTK to TX_UART_2 port	



PL0	PL1	PL8	Map RX-UART-RTK	Unit
'W'	'd'	0	Map RX-UART-RTK to RX_UART_1 port	
		1	Map RX-UART-RTK to RX_UART_2 port	

PL0	PL1	PL9	Main Action	Unit
'W'	'd'	0	No Main Action	
		1	MQTT_Base	
		2	NTRIP_Base	
		3	Radio_Base	
		4	MQTT_Rover	
		5	NTRIP_Rover	
		6	Radio_Rover	
		7	UART_to_Bluetooth	
		8	UART_to_RF_Base	
		9	UART_to_RF_Rover	
		10	Bluetooth_to_RF_Base	
		11	Bluetooth_to_RF_Rover	
		12	MQTT_Rover_Repeater	
		13	NTRIP_Rover_Repeater	
		14	Radio_Rover_Repeater	
		15	UART_Base_to_UART_Rover	
		16	NTRIP_CASTER	
		17	UART_to_WIFI_Bridge	





PL0	PL1	PL10	Other action
'W'	'd'	BIT1	Export IMU Data to TX_UART_0 port
		BIT2	Save NMEA/RTCM/RAW/.. Data (from RX-UART-RTK) to SD Card
		BIT3	Send NMEA/RTCM/RAW/.. Data (from RX-UART-RTK) to Bluetooth Client
		BIT4	Base-Export NMEA/GGA data (from Rovers) to TX_UART_0 port
		BIT5	Base-Priority export NMEA Data from Rovers
		BIT6	Rover-Save RTCM/RAW... data (from Server/Radio_Base) to SD Card
		BIT7	Rover-Send GGA message (from RX-UART-RTK) to Server/RTK_Base + Export GGA to TX_UART0
		BIT8	Rover-Send all NMEA messages (from RX-UART-RTK) to Server/RTK_Base + Export NMEA to TX_UART0
		BIT9	Wireless Bridge: Save data send (TX-Wireless-Data) to SD Card
		BIT10	Wireless Bridge: Save data receive (RX-Wireless-Data) to SD Card
		BIT11	Rover Repeat: Send RTCM/RAW... data (from Server/Server/RTK_Base) to Bluetooth Client
		BIT12	Rover Repeat: Send RTCM/RAW... data (from Server/RTK_Base) to RTK_Radio_Rover
		BIT13	Send IMU_1 Data to Bluetooth Client
		BIT14	Send IMU_2 Data to Bluetooth Client
		BIT15	Send Data (from RX-UART-RTK) to WiFi TCP/UDP device
		BIT16	Send IMU_1 Data to WiFi TCP/UDP device
		BIT17	Send IMU_2 Data to WiFi TCP/UDP device
		BIT18	Respond realtime command control on Bluetooth Client
		BIT19	Respond realtime command control on WiFi TCP/UDP



PL0	PL1	PL9	PL10 – BIT Support (1 → 19)																		
			1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
'W'	'd'	0	●	●	●	○	○	○	●	●	○	○	○	○	●	●	●	●	●	●	●
		1	●	●	●	●	●	○	○	○	○	○	○	○	●	●	●	●	●	●	●
		2	●	●	●	●	●	○	○	○	○	○	○	○	●	●	●	●	●	●	●
		3	●	●	●	●	●	○	○	○	○	○	○	○	●	●	●	●	●	●	●
		4	●	●	●	○	○	●	●	●	○	○	○	○	●	●	●	●	●	●	●
		5	●	●	●	○	○	●	●	●	○	○	○	○	●	●	●	●	●	●	●
		6	●	●	●	○	○	●	●	●	○	○	○	○	●	●	●	●	●	●	●
		7	●	○	○	○	○	○	○	○	●	●	○	○	○	○	●	●	●	●	●
		8	●	○	○	○	○	○	○	○	●	●	○	○	○	○	●	●	●	●	●
		9	●	○	○	○	○	○	○	○	●	●	○	○	○	○	●	●	●	●	●
		10	●	○	○	○	○	○	○	○	●	●	○	○	○	○	●	●	●	●	●
		11	●	○	○	○	○	○	○	○	●	●	○	○	○	○	●	●	●	●	●
		12	●	●	○	●	●	●	●	●	○	○	●	●	●	●	●	●	●	●	●
		13	●	●	○	●	●	●	●	●	○	○	●	●	●	●	●	●	●	●	●
		14	●	●	○	●	●	●	●	●	○	○	●	●	●	●	●	●	●	●	●
		15	●	○	○	○	○	●	○	○	○	○	○	○	●	●	●	●	●	●	●
		16	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○	○
		17	●	●	●	○	○	●	○	○	○	○	○	○	●	●	●	●	●	●	●

## ESPrTk Respond

Payload Index	Type	value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'd'	STRING	-	-	1	1	ID Configure : ACTION_PLANNING	
	PL3	INTEGER	0	1	-	-	Status Configure	
							0 Error: Failed to save , please try again	
							1 OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	



## Example

Message :	
HOST Send	\$ESP_OK 41 W d 10 1 8 6 6 1 0 0 00000000000000000000 *5E59
ACK Respond	\$ESP_OK 49 W d 1 ( ID : ACTION_PLANNING ) : Saved Success . *6A14
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - INTERNET

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'e'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : INTERNET

Number of field values : 8

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	24	0	-	-	Type Internet	
PL3	INTEGER	1	3	1	-	-	Number WiFi in List	
PL4	PRINT	-	-	TEWM_B31B6B	1	30	SSID1	
PL5	PASS_A	-	-	884744F797	0	30	Pass1	
PL6	PRINT	-	-	Tran Trong Toan	1	30	SSID2	
PL7	PASS_A	-	-	12121975	0	30	Pass2	
PL8	PRINT	-	-	My Router	1	30	SSID3	
PL9	PASS_A	-	-		0	30	Pass3	

PL0	PL1	PL2	Type Internet	Unit
'W'	'e'	0	WIFI	
		1	Ethernet ENC28J60	
		2	Ethernet W5500	
		3	Ethernet W5110	
		4	SIM800	
		5	SIM808-SIM868	
		6	SIM900-SIM968-SIM968	
		7	SIM7000	
		8	SIM5320-SIM5360	
		9	SIM7100	
		10	SIM7600	



	11	Ublox LEON-G100	
	12	Ublox LISA-U2xx	
	13	Ublox SARA-G3xx	
	14	Ublox TOBY-L2xx	
	15	Ublox LARA-R2xx	
	16	Ublox MPC1-L2xx	
	17	Ublox SARA-U2xx	
	18	Ublox SARA-R4xx	
	19	Ublox SARA-N4xx	
	20	Quectel BG96	
	21	Quectel M95	
	22	Quectel MC60	
	23	Digi XBee	
	24	SequansMonarch	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'e'	STRING	-	-	1	1	ID Configure : INTERNET	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 67 W e 0 1 TEWM_B31B6B 884744F797 Tran Trong Toan 12121975 My Router *190B
ACK Respond	\$ESP_OK 42 W e 1 ( ID : INTERNET ) : Saved Success . *271A
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...





PL0	PL1	PL3	RF Type	Unit
'W'	'f'	0	WiFi-to-WiFi	
		1	LoRa-to-LoRa	

PL0	PL1	PL4	WiFi Channel	Unit
PL0	PL1	PL8	LoRa Channel	
'W'	'f'	0	Channel 1	
		1	Channel 2	
		2	Channel 3	
		3	Channel 4	
		4	Channel 5	
		5	Channel 6	
		6	Channel 7	
		7	Channel 8	
		8	Channel 9	
		9	Channel 10	
		10	Channel 11	
		11	Channel 12	
		12	Channel 13	
		13	Channel 14	

PL0	PL1	PL5	WiFi Type Power	Unit
PL0	PL1	PL9	LoRa Type Power	



'W'	'f'	0	2 dBm - 1.59 mW	
		1	4 dBm - 2.51 mW	
		2	6 dBm - 3.98 mW	
		3	8 dBm - 6.31 mW	
		4	10 dBm - 10 mW	
		5	12 dBm - 15.9 mW	
		6	14 dBm - 25.1 mW	
		7	16 dBm - 39.8 mW	
		8	18 dBm - 63.1 mW	
		9	20 dBm - 100 mW	
		10	27 dBm - 500 mW	

PL0	PL1	PL6	WiFi Type Speed	Unit
'W'	'f'		55 Kbps	
			90 Kbps	
			160 Kbps	
			240 Kbps	
			320 Kbps	
			400 Kbps	

PL0	PL1	PL10	LoRa Type Speed	Unit
'W'	'f'		0.15 Kbps	
			0.3 Kbps	



			0.6 Kbps	
			1.2 Kbps	
			2.2 Kbps	
			3.9 Kbps	
			7 Kbps	
			12.5 Kbps	
			22 Kbps	

## ESPrtk Respond

Payload Index	Type	value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'f'	STRING	-	-	1	1	ID Configure : RADIO_RTK	
PL3	INTEGER	0	1	-	-	Status Configure		
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
PL4	STRING	-	-	-	-	Describe Status Configure in text string format		

## Example

Message :	
HOST Send	\$ESP_OK 52 W f abc_LoRa_WiFi_012345 0 0 9 0 433000000 0 9 8 10 *1906
ACK Respond	\$ESP_OK 43 W f 1 ( ID : RADIO_RTK ) : Saved Success . *7D4A
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - MQTT\_RTK

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'g'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : MQTT\_RTK  
Number of field values : 10

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	STRING	-	-	broker.hivemq.com	1	50	IP	
PL3	INTEGER	0	65535	1883	-	-	Port	
PL4	PASS_A	-	-	rkdpcppo	1	30	User Name	
PL5	PASS_B	-	-	nvZv101KE_SX	1	30	User Password	
PL6	STRING	-	-	ESPRTK_[ID]	1	30	MQTT Client ID	
PL7	STRING	-	-	RTCM	1	50	RTCM Topic	
PL8	STRING	-	-	NMEA	1	50	NMEA topic	
PL9	STRING	-	-	FAST_NMEA	1	50	Fast NMEA topic	
PL10	INTEGER	0	1	1	-	-	Enable encrypt data send	
PL11	PASS_D	-	-	abc_MQTT_RTK_01 2345	1	32	MQTT KEY Encrypt	
PL12								
PL13								
PL14								
PL15								
PL16								

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'g'	STRING	-	-	1	1	ID Configure : MQTT_RTK	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	





PL0	PL1	PL7	Enable check Mountpoint exist	Unit
'W'	'h'	0	Disable check Mountpoint exist	
		1	Enable check Mountpoint exist	

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'h'	STRING	-	-	1	1	ID Configure : NTRIP_CLIENT	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 31 W h rtk2go.com 2101 no no no 1 *0A78
ACK Respond	\$ESP_OK 46 W h 1 ( ID : NTRIP_CLIENT ) : Saved Success . *2218
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Write Configure - NTRIP\_MASTER

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'i'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : NTRIP\_MASTER

Number of field values : 31

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
---------------	------------	-----------	-----------	---------------	------------	------------	----------	------



PL2	STRING	-	-	rtk2go.com	1	50	IP	
PL3	INTEGER	0	65535	2101	-	-	Port	
PL4	STRING	-	-	A00__[ID]	1	100	Mountpoint	
PL5	PASS_B	-	-	BETATEST2	1	50	Password	
PL6	INTEGER	0	1	1	-	-	Enable check Mountpoint exist	
PL7	INTEGER	0	1	0	-	-	Enable Use Custom ENTRY	
PL8	PRINT	-	-	San_Jose-Calif	1	30	City	
PL9	INTEGER	0	46	13	-	-	Data Format ID	
PL10	STRING	-	-	1005(1),1077(1),1107(1),1117(1)	1	200	Message type detail	
PL11	INTEGER	0	5	1	-	-	Carrier Phase ID	
PL12	INTEGER	0	1	1	-	-	Flag Beidou	
PL13	INTEGER	0	1	1	-	-	Flag GPS	
PL14	INTEGER	0	1	1	-	-	Flag Glonass	
PL15	INTEGER	0	1	0	-	-	Flag Galileo	
PL16	INTEGER	0	1	1	-	-	Flag QZSS	
PL17	INTEGER	0	1	0	-	-	Flag IRNSS	
PL18	INTEGER	0	1	1	-	-	Flag SBAS	
PL19	INTEGER	0	1	0	-	-	Flag Navic	
PL20	INTEGER	0	1	0	-	-	Flag GNSS	
PL21	INTEGER	0	1	0	-	-	Flag GFZ	
PL22	PRINT	-	-	SNIP	1	20	Network	
PL23	STRING	-	-	USA	1	3	Country (max 3 digit)	
PL24	FLOAT	-90.0	90.0	37.388	-	-	Latitude	deg
PL25	FLOAT	-180.0	180.0	-121.9	-	-	Longitude	deg
PL26	INTEGER	0	1	1	-	-	Request GGA	
PL27	INTEGER	0	1	0	-	-	Solution	
PL28	INTEGER	0	1	0	-	-	Compression/Encryption	
PL29	INTEGER	0	2	1	-	-	Authentication	
PL30	INTEGER	0	1	0	-	-	User Fee	
PL31	INTEGER	0	1000000000	8600	-	-	Speed (Bitrate)	bps
PL32	STRING	-	-	ESPrTk-Base	1	50	Misc	



PL0	PL1	PL6	Enable check Mountpoint exist	Unit
'W'	'i'	0	Dissable check Mountpoint exist	
		1	Enable check Mountpoint exist	

PL0	PL1	PL7	Enable Use Custom ENTRY	Unit
'W'	'i'	0	Disable Use Custom ENTRY	
		1	Enable Use Custom ENTRY	

PL0	PL1	PL9	Data Format ID	PL0	PL1	PL9	Data Format ID
'W'	'i'	0	Auto Detec Format	24			SAE J2735 DSRC
		1	ADV	25			Trimble RMC
		2	AOA	26			Trimble RMC+
		3	BINEX	27			Trimble RMCx
		4	DGPS	28			Trimble sRMCx
		5	RAW	29			Trimble R17
		6	RTCM 2.0	30			Trimble R27
		7	RTCM 2.1	31			Septentrio SBF
		8	RTCM 2.2	32			SAPOS
		9	RTCM 2.3	33			RINEX
		10	RTCM 2.x	34			SP3
		11	RTCM 3.0	35			RTCA
		12	RTCM 3.1	36			FKP
		13	RTCM 3.2	37			COP
		14	RTCM 3.3	38			LB2
		15	RTCM 3.4	39			ZERO
		16	RTCM 3.5	40			POS_ASCII
		17	RTCM 3.x	41			JDNCT
		18	UBlox RAW	42			SP3-ASC
		19	Hermisphere Eclipse	43			UPD-ASC
		20	Skytraq Navspark RAW	44			UPD-RTCM
		21	NMEA	45			ION-ASC



		22	NCT	46			Other Format
		23	Novatel OEM				

PL0	PL1	PL26	Request GGA				Unit
'W'	'i'	0	None				
		1	Yes				

PL0	PL1	PL27	Solution				Unit
'W'	'i'	0	Single reference station				
		1	Networked reference stations				

PL0	PL1	PL28	Compression/Encryption				Unit
'W'	'i'	0	None				
		1	Yes				

PL0	PL1	PL29	Authentication				Unit
'W'	'i'	0	None				
		1	Basic				
		2	Digest				

PL0	PL1	PL30	User Fee				Unit
'W'	'i'	0	No user fee				
		1	Usage is charged				



## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'i'	STRING	-	-	1	1	ID Configure : NTRIP_MASTER	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 173 W i rtk2go.com 2101 A00__81909_GHB9A BETATEST2 1 0 San_Jose-Calif 13 1005(1),1077(1),1107(1),1117(1) 1 1 1 0 1 0 0 0 0 SNIP USA 37.388 -121.9 1 0 0 1 0 8600 ESPrTk-Base *4C1B
ACK Respond	\$ESP_OK 46 W i 1 ( ID : NTRIP_MASTER ) : Saved Success . *2607
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Write Configure - UART\_CONFIGURE

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'j'	Infor 1	Infor 2	Infor 3	Infor 4	...

**Note:** This configure only work on WEB Configure interface !

Name CFG : UART\_CONFIGURE

Number of field values : 19

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	1	1	-	-	Enable Hardware Control	
PL3	INTEGER	0	1	1	-	-	Enable UART Configure	



PL4	INTEGER	0	2	2	-	-	Enable Encode UART Configure	
PL5	INTEGER	0	255	0	-	-	Key Encrypt K_0	
PL6	INTEGER	0	255	1	-	-	Key Encrypt K_1	
PL7	INTEGER	0	255	2	-	-	Key Encrypt K_2	
PL8	INTEGER	0	255	3	-	-	Key Encrypt K_3	
PL9	INTEGER	0	255	4	-	-	Key Encrypt K_4	
PL10	INTEGER	0	255	5	-	-	Key Encrypt K_5	
PL11	INTEGER	0	255	6	-	-	Key Encrypt K_6	
PL12	INTEGER	0	255	7	-	-	Key Encrypt K_7	
PL13	INTEGER	0	255	8	-	-	Key Encrypt K_8	
PL14	INTEGER	0	255	9	-	-	Key Encrypt K_9	
PL15	INTEGER	0	255	10	-	-	Key Encrypt K_10	
PL16	INTEGER	0	255	11	-	-	Key Encrypt K_11	
PL17	INTEGER	0	255	12	-	-	Key Encrypt K_12	
PL18	INTEGER	0	255	13	-	-	Key Encrypt K_13	
PL19	INTEGER	0	255	14	-	-	Key Encrypt K_14	
PL20	INTEGER	0	255	15	-	-	Key Encrypt K_15	



PL0	PL1	PL2	Enable Hardware Control	Unit
'W'	'j'	0	Disable use Hardware Control in UART Configure mode	
		1	Enable use Hardware Control in UART Configure mode	

PL0	PL1	PL3	Enable UART Configure	Unit
'W'	'j'	0	Disable start UART Configure mode	
		1	Enable start UART Configure mode	

PL0	PL1	PL4	Enable Encode UART Configure	Unit
'W'	'j'	0	Disable encrypt data repond Read/Write configure UART Configure	
		1	Enable encrypt data repond Read/Write configure UART Configure. Use Bitwise Encrypt algorithm.	
		2	Enable encrypt data repond Read/Write configure UART Configure. Use AES256 Encrypt algorithm.	

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'j'	STRING	-	-	1	1	ID Configure : UART_CONFIGURE	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

**Note:** This configure only work on WEB Configure interface !

Message :	
HOST Send	\$ESP_OK 48 W j 1 1 0 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 *6008



ACK Respond	\$ESP_OK 48 W j 1 ( ID : UART_CONFIGURE ) : Saved Success . *3C54
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - BLUETOOTH

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'k'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : BLUETOOTH

Number of field values : 3

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	1	0	-	-	Type Bluetooth	
PL3	PRINT	-	-	BTU-ESPrTk : [ID]	1	100	Bluetooth Classic Name	
PL4	PRINT	-	-	BLE-ESPrTk : [ID]	1	100	Bluetooth BLE Name	

PL0	PL1	PL2	Type Bluetooth	Unit
'W'	'k'	0	Bluetooth Classic - BTU	
		1	Bluetooth Low Energy - BLE	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'k'	STRING	-	-	1	1	ID Configure : BLUETOOTH	
	PL3	INTEGER	0	1	-	-	Status Configure	
							0 Error: Failed to save , please try again	
							1 OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 56 W k 0 BTU-ESPrTk : 81909_GHB9A BLE-ESPrTk : 81909_GHB9A *6632



ACK Respond	\$ESP_OK 43 W k 1 ( ID : BLUETOOTH ) : Saved Success . *6556
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - DISPLAY\_VIEWER

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'I'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : DISPLAY\_VIEWER

Number of field values : 8

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	2	1	-	-	Type Display	
PL3	INTEGER	0	6	6	-	-	Brightness Display	
PL4	INTEGER	0	6	6	-	-	Contrast Display	
PL5	INTEGER	0	1	0	-	-	Flip Display	
PL6	INTEGER	0	1	1	-	-	Use ERROR-LED	
PL7	INTEGER	0	1	0	-	-	Invert ERROR-LED state	
PL8	INTEGER	0	1	1	-	-	Use CONNECTION-LED	
PL9	INTEGER	0	1	0	-	-	Invert CONNECTION-LED state	

PL0	PL1	PL	Type Display	Unit
'W'	'I'	0	NEOPIXEL LED ( 4 LED)	
		1	Oled SSD1306 0.96" (I2C - 128x64)	
		2	Oled SH1106 1.3" (I2C - 128x64)	

PL0	PL1	PL3	Brightness Display	Unit
PL0	PL1	PL4	Contrast Display	
'W'	'I'	0	10	
		1	20	
		2	50	
		3	100	
		4	150	



		5	200	
		6	255	

PL0	PL1	PL5	Flip Display	Unit
'W'	'1'	0	No Flip Display .	
		1	Yes Flip Display. If type display NEOPIXEL LED: Rorate index neopixel 1234 to 4321 If type display OLED Display: Vertical flip screen .	

PL0	PL1	PL6	Use ERROR-LED	Unit
PL0	PL1	PL8	Use CONNECTION-LED	
'W'	'1'	0	Not use	
		1	Use	

PL0	PL1	PL7	Invert ERROR-LED state	Unit
PL0	PL1	PL9	Invert CONNECTION-LED state	
'W'	'1'	0	No Invert	
		1	Yes Invert	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'1'	STRING	-	-	1	1	ID Configure : DISPLAY_VIEWER	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	



## Example

Message :	
HOST Send	\$ESP_OK 20 W 1 1 6 6 0 1 0 1 0 *2509
ACK Respond	\$ESP_OK 48 W 1 1 ( ID : DISPLAY_VIEWER ) : Saved Success . *2044
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Write Configure - EVENT\_LOG

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'm'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : EVENT\_LOG

Number of field values : 5

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	9	3	-	-	Type Size Event_Log File	
PL3	INTEGER	0	1	0	-	-	Enable Record Action	
PL4	INTEGER	0	1	0	-	-	Enable Record Error	
PL5	INTEGER	0	1	0	-	-	Enable Record Action Planing	
PL6	INTEGER	0	1	0	-	-	Enable Record WiFi Scan	



PL0	PL1	PL2	Type Size Event_Log File	Unit
'W'	'm'	0	5 Kbytes	
		1	10 Kbytes	
		2	15 Kbytes	
		3	20 Kbytes	
		4	25 Kbytes	
		5	30 Kbytes	
		6	35 Kbytes	
		7	40 Kbytes	

PL0	PL1	PL3	Enable Record Action	Unit
PL0	PL1	PL4	Enable Record Error	
PL0	PL1	PL5	Enable Record Action Planing	
PL0	PL1	PL6	Enable Record WiFi Scan	
'W'	'm'	0	Enalbe	
		1	Disable	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'm'	STRING	-	-	1	1	ID Configure : EVENT_LOG	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	



## Example

Message :	
HOST Send	\$ESP_OK 14 W m 3 0 0 0 0 *6D76
ACK Respond	\$ESP_OK 43 W m 1 ( ID : EVENT_LOG ) : Saved Success . *624A
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - SD\_CARD

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'o'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : SD\_CARD

Number of field values : 7

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	STRING	-	-	my_record	3	20	File's Name	
PL3	INTEGER	0	9	0	-	-	Format File	
PL4	INTEGER	0	1	0	-	-	Type write	
PL5	INTEGER	10	4000000	500	-	-	MAX_SIZE_FILE (K Byte)	K Byte
PL6	INTEGER	0	100000000	1	-	-	RTK-Rover NMEA Record Cycle	second
PL7	INTEGER	1	65000	2	-	-	RTK-Rover Max NMEA save each Update Cycle	
PL8	BIT	-	-	1100000000000000 0000000000000000 0000	32	32	RTK-Rover Enable type NMEA record	



PL0	PL1	PL3	Format File	Unit
'W'	'o'	0	.log	
		1	.txt	
		2	.nmea	
		3	.nme	
		4	.gps	
		5	.ubx	
		6	data	
		7	.dat	
		8	.bin	
		9	(No type): User type format at the end file's name like (my_record.txt)	

PL0	PL1	PL4	Type write	Unit
'W'	'o'	0	Append to old file	
		1	Create and write on new file	

PL0	PL1	PL8	RTK-Rover Enable type NMEA record	PL0	PL1	PL	RTK-Rover Enable type NMEA record
'W'	'o'	BIT1	NMEA - GGA	'W'	'"	BIT16	NMEA - BWC
		BIT2	NMEA - RMC			BIT17	NMEA - MSK
		BIT3	NMEA - GSA			BIT18	NMEA - MSS
		BIT4	NMEA - GSV			BIT19	NMEA - RMA
		BIT4	NMEA - VTG			BIT20	NMEA - RMB
		BIT5	NMEA - GLL			BIT21	NMEA - RTE
		BIT6	NMEA - ZDA			BIT22	NMEA - TRF
		BIT7	NMEA - GNS			BIT23	NMEA - STN
		BIT8	NMEA - GST			BIT24	NMEA - VBW
		BIT9	NMEA - DTM			BIT25	NMEA - WCV
		BIT10	NMEA - GBS			BIT26	NMEA - WPL
		BIT11	NMEA - GRS			BIT27	NMEA - XTC
		BIT12	NMEA - AAM			BIT28	NMEA - XTE





## Command Write Configure - IMU\_MPU9250

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'p'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : IMU\_MPU9250

Number of field values : 19

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	9	1	-	-	Type Update frequency	
PL3	INTEGER	0	3	3	-	-	Gyroscope Scale Range	
PL4	INTEGER	0	3	1	-	-	Accelerometer Scale Range	
PL5	INTEGER	0	6	0	-	-	Low pass Filter	
PL6	FLOAT	1.00	20.0	4.512	-	-	Shock Kalman Filter	
PL7	BIT	-	-	000000111	9	9	Enable/Disable data output	
PL8	BIT	-	-	00001111	8	8	Enable Apply Extended Kalman filter	
PL9	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - MBx	
PL10	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - MBy	
PL11	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - MBz	
PL12	FLOAT	-1000000000.0	1000000000.0	1	-	-	Matrix Convert - M11	
PL13	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M12	
PL14	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M13	
PL15	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M21	
PL16	FLOAT	-1000000000.0	1000000000.0	1	-	-	Matrix Convert - M22	
PL17	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M23	
PL18	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M31	
PL19	FLOAT	-1000000000.0	1000000000.0	0	-	-	Matrix Convert - M32	
PL20	FLOAT	-1000000000.0	1000000000.0	1	-	-	Matrix Convert - M33	



PL0	PL1	PL2	Type Update frequency	Unit
'W'	'p'	0	2 Hz	
		1	10 Hz	
		2	15 Hz	
		3	20 Hz	
		4	25 Hz	
		5	35 Hz	
		6	50 Hz	
		7	100 Hz	
		8	150 Hz	
		9	200 Hz	

PL0	PL1	PL3	Gyroscope Scale Range	Unit
'W'	'p'	0	250	
		1	500	
		2	1000	
		3	2000	

PL0	PL1	PL4	Accelerometer Scale Range	Unit
'W'	'p'	0	2	
		1	4	
		2	8	
		3	16	

PL0	PL1	PL5	Low pass Filter	Unit
'W'	'p'	0	Not use	
		1	5 Hz	
		2	10 Hz	
		3	20 Hz	
		4	41 Hz	
		5	92 Hz	



		6	184 Hz	
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PL0	PL1	PL7	Enable/Disable data output IM1	Unit
			\$ESPIM1,GX,GY,GZ,MX,MY,MZ,AX,AY,AZ,T,MXc,MYc,MZc,*xx	
'W'	'p'	BIT1	Raw Gyroscope 3 Axis(GX,GY,GZ)	
		BIT2	Raw Magnetometer 3 Axis(MX,MY,MZ)	
		BIT3	Raw Accelerometer 3 Axis(AX,AY,AZ)	
		BIT4	Temperature(T)	
		BIT5	Magnetometer 3 Axis Calibrated(MXc,MYc,MZc)	
			Enable/Disable data output IM2	Unit
			\$ESPIM2,QW,QX,QY,QZ,Yaw,Pitch,Roll,H,FQW,FQX,FQY,FQZ,Fyaw,Fpitch,Froll,FH,*xx	
		BIT6	DMP-Quaternion (QW,QX,QY,QZ)	
		BIT7	DMP-Euler 3 Axis(Yaw,Pitch,Roll)	
		BIT8	Compass Heading : Calibrated + Tilt compensated(H)	
		BIT9	Data Filter (FQW,FQX,FQY,FQZ,Fyaw,Fpitch,Froll,FH)	

PL0	PL1	PL8	Enable Apply Extended Kalman filter	Unit
'W'	'p'	BIT1	Filter QW	
		BIT2	Filter QX	
		BIT3	Filter QY	
		BIT4	Filter QZ	
		BIT5	Filter Yaw	
		BIT6	Filter Pitch	
		BIT7	Filter Roll	
		BIT8	Filter Heading	

## ESPrTk Respond

Payload Index	Type	value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'p'	STRING	-	-	1	1	ID Configure : IMU_MPU9250	
	PL3	INTEGER	0	1	-	-	Status Configure	



							0	Error: Failed to save , please try again	
							1	OK : Saved configure success	
	PL4	STRING	-	-	-	-		Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 61 W p 1 3 1 0 4.512 000000111 00001111 0 0 0 1 0 0 0 1 0 0 0 1 *5E4C
ACK Respond	\$ESP_OK 45 W p 1 ( ID : IMU_MPU9250 ) : Saved Success . *6617
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - GPIO\_PIN\_MAP

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'q'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : GPIO\_PIN\_MAP

Number of field values : 26

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	ID_ESPrTk_Pin map to GPIOx	Unit
PL2	INTEGER	0	25	18	-	-	GPIO 0 ← ID_ESPrTk_Pin	
PL3	INTEGER	0	25	4	-	-	GPIO 1 ← ID_ESPrTk_Pin	
PL4	INTEGER	0	25	21	-	-	GPIO 2 ← ID_ESPrTk_Pin	
PL5	INTEGER	0	25	1	-	-	GPIO 3 ← ID_ESPrTk_Pin	
PL6	INTEGER	0	25	16	-	-	GPIO 4 ← ID_ESPrTk_Pin	
PL7	INTEGER	0	25	10	-	-	GPIO 5 ← ID_ESPrTk_Pin	
PL8	INTEGER	0	25	14	-	-	GPIO 12 ← ID_ESPrTk_Pin	
PL9	INTEGER	0	25	0	-	-	GPIO 13 ← ID_ESPrTk_Pin	
PL10	INTEGER	0	25	17	-	-	GPIO 14 ← ID_ESPrTk_Pin	
PL11	INTEGER	0	25	11	-	-	GPIO 15 ← ID_ESPrTk_Pin	
PL12	INTEGER	0	25	13	-	-	GPIO 16 ← ID_ESPrTk_Pin	
PL13	INTEGER	0	25	7	-	-	GPIO 17 ← ID_ESPrTk_Pin	
PL14	INTEGER	0	25	8	-	-	GPIO 18 ← ID_ESPrTk_Pin	
PL15	INTEGER	0	25	2	-	-	GPIO 19 ← ID_ESPrTk_Pin	
PL16	INTEGER	0	25	22	-	-	GPIO 21 ← ID_ESPrTk_Pin	
PL17	INTEGER	0	25	19	-	-	GPIO 22 ← ID_ESPrTk_Pin	
PL18	INTEGER	0	25	12	-	-	GPIO 23 ← ID_ESPrTk_Pin	
PL19	INTEGER	0	25	9	-	-	GPIO 25 ← ID_ESPrTk_Pin	
PL20	INTEGER	0	25	23	-	-	GPIO 26 ← ID_ESPrTk_Pin	
PL21	INTEGER	0	25	20	-	-	GPIO 27 ← ID_ESPrTk_Pin	
PL22	INTEGER	0	25	15	-	-	GPIO 32 ← ID_ESPrTk_Pin	



PL23	INTEGER	0	25	3	-	-	GPIO 33 ← ID_ESPrTk_Pin	
PL24	INTEGER	0	25	24	-	-	GPIO 34 ← ID_ESPrTk_Pin	
PL25	INTEGER	0	25	6	-	-	GPIO 35 ← ID_ESPrTk_Pin	
PL26	INTEGER	0	25	25	-	-	GPIO 36 ← ID_ESPrTk_Pin	
PL27	INTEGER	0	25	5	-	-	GPIO 39 ← ID_ESPrTk_Pin	

ID_ESPrTk_Pin	Name pin	ID_ESPrTk_Pin	Name pin
0	CWB_Button	13	RX_UART2
1	RX_UART0	14	ERROR_LED
2	MOSI_SD_Card	15	CS_LoRa
3	MOSI_LoRa_Ethe	16	TX_UART2
4	TX_UART0	17	TX_UART3
5	MISO_SD_Card	18	CS_Ethernet__PWR_GSM
6	MISO_LoRa_Ethe	19	SCL_I2C
7	RX_UART1	20	SCL_OLED
8	SCK_SD_Card	21	RST_LoRa_Ethe
9	SCK_LoRa_Ethe	22	SDA_I2C
10	TX_UART1	23	SDA_OLED
11	CONNECT_LED	24	DI0_LoRa
12	CS_SD_Card	25	RX_UART3



## Example

Example 1	JSON - Message Configure
HOST Send	\$ESP_OK 72 W q 18 4 21 1 16 10 14 0 17 11 13 7 8 2 22 19 12 9 23 20 15 3 24 6 25 5 *3F0B
Default from factory	{ "CWB_Button" : "13" ,        "RX_UART0" : "3" ,    "MOSI_SD_Card" : "23" , "MOSI_LoRa_Ethe" : "33" ,    "TX_UART0" : "1" ,    "MISO_SD_Card" : "39" , "MISO_LoRa_Ethe" : "35" ,    "RX_UART1" : "17" ,    "SCK_SD_Card" : "18" , "SCK_LoRa_Ethe" : "25" ,    "TX_UART1" : "5" ,    "CONNECT_LED" : "15" , "CS_SD_Card" : "19" ,        "RX_UART2" : "16" ,    "ERROR_LED" : "12" , "CS_LoRa" : "32" ,            "TX_UART2" : "4" ,    "TX_UART3" : "14" , "CS_Ethernet_PWR_GSM" : "0" , "SCL_I2C" : "22" "SCL_OLED" : "27" , "RST_LoRa_Ethe" : "2" ,      "SDA_I2C" : "21" ,    "SDA_OLED" : "26" , "DI0_LoRa" : "34" ,         "RX_UART3" : "36" }
Example 2	JSON - Message Configure
HOST Send	\$ESP_OK 72 W q 18 4 5 1 10 9 16 12 8 2 17 11 15 6 23 20 21 14 24 3 22 19 7 13 0 25 *3F4F
Example configure of User	{ "CWB_Button" : "36" ,        "RX_UART0" : "3" ,    "MOSI_SD_Card" : "15" , "MOSI_LoRa_Ethe" : "27" ,    "TX_UART0" : "1" ,    "MISO_SD_Card" : "2" , "MISO_LoRa_Ethe" : "19" ,    "RX_UART1" : "34" ,    "SCK_SD_Card" : "14" , "SCK_LoRa_Ethe" : "5" ,      "TX_UART1" : "4" ,    "CONNECT_LED" : "17" , "CS_SD_Card" : "13" ,        "RX_UART2" : "35" ,    "ERROR_LED" : "25" , "CS_LoRa" : "18" ,            "TX_UART2" : "12" ,    "TX_UART3" : "16" , "CS_Ethernet_PWR_GSM" : "0" , "SCL_I2C" : "33" ,    "SCL_OLED" : "22" , "RST_LoRa_Ethe" : "23" ,      "SDA_I2C" : "32" ,    "SDA_OLED" : "21" , "DI0_LoRa" : "26" ,         "RX_UART3" : "39" }
ACK Respond	\$ESP_OK 46 W q 1 ( ID : GPIO_PIN_MAP ) : Saved Success . *3616
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'q'	STRING	-	-	1	1	ID Configure : GPIO_PIN_MAP



	PL3	INTEGER	0	1	-	-	Status Configure		
							0	Error: Failed to save , please try again	
							1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format		



## Command Write Configure - SYSTEM\_Other\_Mode

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'r'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : SYSTEM\_Other\_Mode

Number of field values : 9

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	5	0	-	-	Type CHIP ESP32	
PL3	INTEGER	0	9	9	-	-	Power System Saving	
PL4	INTEGER	0	7	3	-	-	Type speed SPI-SD CARD	
PL5	INTEGER	0	7	3	-	-	Type speed SPI-ETHERNET	
PL6	INTEGER	0	7	3	-	-	Type speed SPI-LORA	
PL7	INTEGER	0	7	3	-	-	Type speed I2C-IMU	
PL8	INTEGER	0	7	3	-	-	Type speed I2C-OLED	
PL9	BIT	-	-	111111111111	12	12	Enable print message types on TX_UART0 port	
PL10	BIT	-	-	11111111111111111111	20	20	Enable warning to users when an error occurs	



PL0	PL1	PL2	Type CHIP ESP32	Unit
'W'	'r'	0	ESP32_D0WD	
		1	ESP32_D0WDQ6	
		2	ESP32_D0WD_V3	
		3	ESP32_D0WDQ6_V3	
		4	ESP32_PICO_D4	
		5	ESP32_PICO_V3	

PL0	PL1	PL3	Power System Saving	Unit
'W'	'r'	0	10% of Max Power	
		1	20% of Max Power	
		2	30% of Max Power	
		3	40% of Max Power	
		4	50% of Max Power	
		5	60% of Max Power	
		6	70% of Max Power	
		7	80% of Max Power	
		8	90% of Max Power	
		9	100% of Max Power	

PL0	PL1	PL4	Type speed SPI-SD CARD	Unit
		PL5	Type speed SPI-ETHERNET	
		PL6	Type speed SPI-LORA	
		PL7	Type speed I2C-IMU	
		PL8	Type speed I2C-OLED	
'W'	'r'	0	(Lowest speed) 25% of Standard Speed	
		1	50% of Standard Speed	
		2	75% of Standard Speed	
		3	100% of Standard Speed	
		4	125% of Standard Speed	
		5	150% of Standard Speed	
		6	175% of Standard Speed	



		7	(Highest speed) 200% of Standard Speed	
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PL0	PL1	PL9	Enable print message types on TX_UART0 port	Unit
'W'	'r'	BIT1	_SYSTEM_ (ESPrTk System)	
		BIT2	_ERROR_ (Error status)	
		BIT3	_INFO_ (Text , Log, Information...)	
		BIT4	_GOIN_ (Go to function status)	
		BIT5	_WFSCAN_ (Wifi Scan Result)	
		BIT6	_BROKER_ (Broker MQTT Status)	
		BIT7	_RVNMEA_ (print NMEA from Rover)	
		BIT8	_CONFIG_ (Configure information detail)	
		BIT9	\$_GGA (Rover print GGA message)	
		BIT10	\$_NMEA_ (Rover print NMEA message)	
		BIT11	\$ESPIM1 (IMU MPU9250 Data type 1)	
		BIT12	\$ESPIM2 (IMU MPU9250 Data type 2)	

PL0	PL1	PL10	Enable warning to users when an error occurs	Unit
'W'	'r'	BIT1	FIRST SETTING	
		BIT2	UART	
		BIT3	INTERNET	
		BIT4	MQTT	
		BIT5	NTRIP	
		BIT6	RADIO_RF_PHY	
		BIT7	RADIO_RF_ROVER	
		BIT8	BLUETOOTH	
		BIT9	SD_CARD	
		BIT10	IMU_MPU	
		BIT11	DISPLAY_VIEWER	
		BIT12	UART_CONFIGURE	
		BIT13	EVENT_LOG	
		BIT14	Other1	
		BIT15	Other2	



		BIT16	Other3	
		BIT17	Other4	
		BIT18	Other5	
		BIT19	Other6	
		BIT20	Other7	

## ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'r'	STRING	-	-	1	1	ID Configure : SYSTEM_Other_Mode	
	PL3	INTEGER	0	1	-	-	Status Configure	
							0 Error: Failed to save , please try again	
							1 OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 52 W r 0 9 3 3 3 3 111111111111 11111111111111111111 *790E
ACK Respond	\$ESP_OK 51 W r 1 ( ID : SYSTEM_Other_Mode ) : Saved Success . *4B63
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...





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PL0	PL1	PL2	Type configure GSM	Unit
'W'	's'	0	Auto Configure	
		1	Custom AT Configure	

PL0	PL1	PL3	View AT TX-RX	Unit
'W'	's'	0	Disable View AT TX-RX	
		1	Enable View AT TX-RX	

PL0	PL1	PL8	Auto restart GSM	Unit
'W'	's'	0	Disable Auto restart GSM	
		1	Enable Auto restart GSM	

PL0	PL1	PL9	Type Max Baudrate	Unit
'W'	's'	0	1200	bps
		1	2400	bps
		2	4800	bps
		3	9600	bps
		4	19200	bps
		5	38400	bps
		6	57600	bps
		7	115200	bps
		8	230400	bps
		9	250000	bps
		10	460800	bps



		11	500000	bps
		12	921600	bps
		13	1000000	bps
		14	2000000	bps

PL0	PL1	PL10	Net Mode	Unit
'W'	's'	0	AUTO	
		1	GSM only	
		2	UMTS only	
		3	LTE only	
		4	LTE_M1 only	
		5	LTE_NB1 only	
		6	EGPRS only	
		7	WCDMA only	
		8	TDS_CDMA only	
		9	EVDO only	
		10	GSM + EGPRS	
		11	GSM + LTE	
		12	GSM + UMTS	
		13	GSM + WCDMA	
		14	GSM + TDSCDMA	
		15	CDMA + EVDO	
		16	GSM + UMTS + LTE	
		17	GSM + WCDMA + LTE	
		18	GSM + EGPRS + LTE	
		19	GSM + TDSCDMA + LTE	
		20	GSM + WCDMA + TDSCDMA	

PL0	PL1	PL11	GSM/2G/3G Band	Unit
'W'	's'	BIT1	Auto	



	BIT2	Any_Value	
	BIT3	GSM_450	
	BIT4	GSM_480	
	BIT5	GSM_750	
	BIT6	GSM_850	
	BIT7	GSM_900	
	BIT8	GSM_1800	
	BIT9	GSM_1900	
	BIT10	GSM_EGSM_900	
	BIT11	GSM_PGSM_900	
	BIT12	GSM_RGSM_900	
	BIT13	GSM_DCS_1800	
	BIT14	GSM_PCS_1900	
	BIT15	WCDMA_800	
	BIT16	WCDMA_850	
	BIT17	WCDMA_VIII_900	
	BIT18	WCDMA_III_1700	
	BIT19	WCDMA_IV_1700	
	BIT20	WCDMA_IX_1700	
	BIT21	WCDMA_PCS_1900	
	BIT22	WCDMA_IMT_2000	
	BIT23	WCDMA_VII_2600	

PL0	PL1	PL12	4G/LTE Band	Unit
'W'	's'	BIT1	Auto	
		BIT2	Any_Value	
		BIT3	Band 0	
		BIT4	Band 1	
		BIT5	Band 2	
		BIT6	Band 3	
		...		
		BIT X	Band (X-3)	
		...		
		BIT66	Band 63	



PL0	PL1	PL13	TDS Band	Unit
'W'	's'	BIT1	Auto	
		BIT2	Any_Value	
		BIT3	A (1900-1920 MHz, 2010-2020 MHz)	
		BIT4	B (1850-1910 MHz, 1930-1990 MHz)	
		BIT5	C (1910-1930 MHz)	
		BIT6	D (2570-2620 MHz)	
		BIT7	E (2300-2400 MHz)	
		BIT8	F (1880-1920 MHz)	



Type	Custom AT Code	Example
[PWR^a]	Retart GSM device by pull-down PWR pin (in <b>a</b> second) and wait until GSM wakeup + ready.	[PWR^2]
[RST]	Retart/Reset GSM device by AT command and wait until GSM ready.	[RST]
[COM^a]	Try scan to communicate with GSM device at baudrate <b>a</b> bps. If failed, auto select baudrate value and try again.	[COM^9600]
[CLR]	Clear all RX buffer UART3.	[CLR]
[DLY^a]	Delay in <b>a</b> Second.	[DLY^1]
[PIN^abcd]	If SIM locked , set PIN SIM is <b>abcd</b> to un-lock SIM.	[PIN^1234]
[CFG]	Auto send AT to Configure Mode / Band /... for GSM device.	[CFG]
[NET^a^b^c]	Auto send AT to Open Network for GSM device. APN String Network: <b>a</b> GPRS Username: <b>b</b> GPRS Password: <b>c</b>	[NET^w3-world^mms^mms]
[TCP^a^b^c]	Connect to Server IP: <b>a</b> ,Port: <b>b</b> . If connect success , wait respond from Server after send string <b>c</b> . ( Auto replace \r \n to 0x0D 0x0A as byte data) ( Just for Dev)	[TCP^google.com^80^GET /search?q=esprtk HTTP/1.1\r\nHost: www.google.com\r\nConnection: close\r\n\r\n]
[a^b^c^d]	Send string <b>a</b> Wait until respond contain <b>d</b> Max time wait : <b>b</b> If not receive, try again, max try : <b>c</b>	[ATE0^5^10^OK]
[a^b^c^d1^d2]	Send string <b>a</b> Wait until respond contain <b>d1</b> or <b>d2</b> Max time wait : <b>b</b> If not receive, try again, max try : <b>c</b>	[AT+CMEE=0^5^10^OK^ok]
...		
[a^b^c^d1^d2^d3^d4^d5^d6 ]	Send string <b>a</b> Wait until respond contain <b>d1</b> or <b>d2</b> or <b>d3</b> (or <b>d4</b> or <b>d5</b> or <b>d6</b> .) Max time wait : <b>b</b> If not receive, try again, max try : <b>c</b>	[AT+CMEE=0^5^10^OK^ok^Ok^Error]





## Command Write Configure - STREAM\_MANAGER

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	't'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : STREAM\_MANAGER

Number of field values : 7

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	1	0	-	-	Enable STREAM_MANAGER	
PL3	INTEGER	0	1	0	-	-	Enable Print status Push-In	
PL4	INTEGER	0	1	0	-	-	Enable Print status Push-In (Full)	
PL5	INTEGER	0	1	0	-	-	Enable Print status Push-Out	
PL6	INTEGER	0	1	0	-	-	Enable Print status Push-Out (Full)	
PL7	INTEGER	0	100000000	0	-	-	Limit Speed Push-Out	Bytes/ Second
PL8	AT_CODE	-	-		0	1500	Custom AT Code	

PL0	PL1	PL2	Enable STREAM_MANAGER	Unit
'W'	't'	0	Disable STREAM_MANAGER	
		1	Enable STREAM_MANAGER	

PL0	PL1	PL3	Print status Push-In	Unit
'W'	't'	0	Disable Print status Push-In	
		1	Enable Print status Push-In	

PL0	PL1	PL4	Print status Push-In (Full)	Unit
'W'	't'	0	Disable Print status Push-In (Full)	
		1	Enable Print status Push-In (Full)	



PL0	PL1	PL5	Print status Push-Out	Unit
'W'	't'	0	Disable Print status Push-Out	
		1	Enable Print status Push-Out	

PL0	PL1	PL6	Print status Push-Out (Full)	Unit
'W'	't'	0	Disable Print status Push-Out (Full)	
		1	Enable Print status Push-Out (Full)	



	Custom AT Code	Example
[ADD <sup>a</sup> <sup>b</sup> ]	Auto to insert RAW data . Cycle <b>a</b> second. RAW in HEX : <b>b</b>	[ADD <sup>1</sup> <sup>D300063F0000000009925CA</sup> ] - Auto add empty RTCM 1008 to stream, cycle 1 second
[T-ID <sup>RMV</sup> ]	If receive message . Remove this message	[R-1007 <sup>RMV</sup> ] - Remove RTCM 1007
[T-ID <sup>ISA</sup> <sup>a</sup> ]	Insert RAW data After <b>T-ID</b> message. RAW in HEX : <b>a</b>	[R-1008 <sup>ISA</sup> <sup>0A0B0C0D</sup> ] - Insert 4 byte 0A0B0C0D after RTCM-1008 message.
[T-ID <sup>ISB</sup> <sup>a</sup> ]	Insert RAW data Before <b>T-ID</b> message. RAW in HEX : <b>a</b>	[N-GPGGA <sup>ISB</sup> <sup>0A0B0C0D</sup> ] - Insert 4 byte 0A0B0C0D before NMEA-\$GPGGA message.
[T-ID <sup>RPL</sup> <sup>a</sup> ]	Replace <b>T-ID</b> message by RAW data . RAW in HEX : <b>a</b>	[R-1074 <sup>RPL</sup> <sup>0A0B0C0D</sup> ] - Replace RTCM-1074 message by 4 byte 0A0B0C0D
[T-ID <sup>RPT</sup> <sup>a</sup> ]	Repeat <b>T-ID</b> message . Max repeat : <b>a</b>	[N-GPRMC <sup>RPT</sup> <sup>3</sup> ] -Repeat NMEA-\$GPRMC message 3 times.
[T-ID <sup>RDC</sup> <sup>a</sup> ]	Count <b>T-ID</b> message . If (Count < <b>a</b> ) : Disable this message , set Count=Count+1. If (Count >= <b>a</b> ) : Enable this message go through stream , reset Count = 0 .	[R-1005 <sup>RDC</sup> <sup>3</sup> ] - Reduce RTCM-1005 message 3 times.

T-ID	Type message	Example
R-i	Type = RTCM , ID Integer = i	R-1007 R-1005
N-i	Type =NMEA, Header String= i	N-GPGGA N-GNRMC
U-i1i2	Type =UBX , Class message HEX= i1, ID message HEX = i2	U-0106 U-0A02
S-i	Type =Skytraq , ID message HEX = i	S-01 S-0E



## ESPrtk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	't'	STRING	-	-	1	1	ID Configure : STREAM_MANAGER	
	PL3	INTEGER	0	1	-	-	Status Configure	
							0 Error: Failed to save , please try again	
							1 OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 17 W t 0 0 0 0 0 0 *444E
HOST Send	\$ESP_OK 49 W t 1 1 0 1 0 0 [ADD^5^0A0B0C0D0E][R-1005^RDC^3]*564E
ACK Respond	\$ESP_OK 48 W t 1 ( ID : STREAM_MANAGER ) : Saved Success . *374A
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - POSITION\_ANTENNA

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'u'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : POSITION\_ANTENNA

Number of field values : 32

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	BIT	-	-	000000000	9	9	Type messages enable	
PL3	INTEGER	0	10000	60	-	-	NMEA GGA repeat cycle	Second
PL4	INTEGER	0	10000	60	-	-	RTCM 1005 repeat cycle	Second
PL5	INTEGER	0	10000	60	-	-	RTCM 1006 repeat cycle	Second
PL6	INTEGER	0	10000	60	-	-	RTCM 1007 repeat cycle	Second
PL7	INTEGER	0	10000	60	-	-	RTCM 1008 repeat cycle	Second
PL8	INTEGER	0	10000	60	-	-	RTCM 1032 repeat cycle	Second
PL9	INTEGER	0	10000	60	-	-	RTCM 1033 repeat cycle	Second
PL10	INTEGER	0	10000	1	-	-	RTCM 1004 repeat cycle	Second
PL11	INTEGER	0	10000	1	-	-	RTCM 1012 repeat cycle	Second
PL12	FLOAT	-90.00	90.00	47.082164	-	-	Rover Latitude	Deg
PL13	FLOAT	-180.0	180.0	2.399216	-	-	Rover Longitude	Deg
PL14	FLOAT	-1000000	1000000	10.000	-	-	Rover Altitude	Meter
PL15	STRING	-	-	GP	2	2	GGA Talker ID	
PL16	FLOAT	-90.00	90.00	47.000000	-	-	Base Latitude	Deg
PL17	FLOAT	-180.0	180.0	2.000000	-	-	Base Longitude	Deg
PL18	FLOAT	-1000000	1000000	10.000	-	-	Base Altitude	Meter
PL19	FLOAT	0.00	6.5535	0	-	-	Base Antenna Height	Meter
PL20	INTEGER	0	3	0	-	-	Quarter Cycle Indicator	
PL21	INTEGER	0	63	0	-	-	ITRF Realization Year	
PL22	INTEGER	0	4095	0	-	-	Reference Station ID	
PL23	INTEGER	0	4095	0	-	-	Physical Reference Station ID	
PL24	INTEGER	0	255	123	-	-	Antenna Setup ID	



PL25	PRINT	-	-	ADVNULLANTENNA	0	31	Antenna Descriptor	
PL26	PRINT	-	-	0.0.0.0	0	31	Antenna Serial Number	
PL27	PRINT	-	-	ESPRTK	0	31	Receiver Type Descriptor	
PL28	PRINT	-	-	3.9.0 _ 4.x.x	0	31	Receiver Firmware Version	
PL29	PRINT	-	-	[ESPrTk's ID]	0	31	Receiver Serial Number	
PL30	BIT	-	-	10000	5	5	GNSS System Indicator and Single Receiver Oscillator Indicator	
PL31	INTEGER	1	32	20	-	-	Max satellite GPS	
PL32	INTEGER	1	27	20	-	-	Max satellite GLONASS	
PL33	INTEGER	1	35	1	-	-	Max satellite SBAS	
PL34	INTEGER	1	96	96	-	-	Max OBS in an Epoch	

PL0	PL1	PL2	Type messages enable	Unit
'W'	's'	BIT1	Enable auto use default NMEA GGA message if GNSS's data not available.	(*)
		BIT2	Enable auto use default RTCM 1005 message if GNSS's data not available.	(*)
		BIT3	Enable auto use default RTCM 1006 message if GNSS's data not available.	(*)
		BIT4	Enable auto use default RTCM 1007 message if GNSS's data not available.	(*)
		BIT5	Enable auto use default RTCM 1008 message if GNSS's data not available.	(*)
		BIT6	Enable auto use default RTCM 1032 message if GNSS's data not available.	(*)
		BIT7	Enable auto use default RTCM 1033 message if GNSS's data not available.	(*)
		BIT8	Enable auto use default RTCM 1004 message if GNSS's data not available.	(*)
		BIT9	Enable auto use default RTCM 1012 message if GNSS's data not available.	(*)

(\*) : BIT = 1 is Enable , BIT = 0 is Disable .

PL0	PL1	PL30	GNSS System Indicator and Single Receiver Oscillator Indicator	Unit
'W'	's'	BIT1	GPS Indicator in use.	(*)
		BIT2	GLONASS Indicator in use.	(*)
		BIT3	GALILEO Indicator in use.	(*)
		BIT4	Reference Indicator in use.	(*)
		BIT5	Single Receiver Oscillator Indicator in use.	(*)

(\*) : BIT = 1 is In Use , BIT = 0 is not In use .



## ESPrTk Respond

Payload Index	Type	value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'u'	STRING	-	-	1	1	ID Configure : POSITION_ANTENNA		
PL3		INTEGER	0	1	-	-	Status Configure		
							0		Error: Failed to save , please try again
							1		OK : Saved configure success
PL4		STRING	-	-	-	-	Describe Status Configure in text string format		

## Example

Message :	
HOST Send	\$ESP_OK 181 W u 000000000 60 60 60 60 60 60 60 60 1 1 47.082164 2.399216 10.000 GP 47.000000 2.000000 10.000 0 0 0 0 123 ADVNULLANTENNA 0.0.0.0 ESPRTK 3.9.0 _ 4.x.x TS9PC_S9SUB 10000 20 20 1 96 *6575
ACK Respond	\$ESP_OK 50 W u 1 ( ID : POSITION_ANTENNA ) : Saved Success . *3613
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

**TIP !** : The table below describes the data fields to be used by the different types of messages when they are enabled.

Name	Standard	GGA	1005	1006	1007	1008	1032	1033	1004	1012
Rover Latitude(degree)	NMEA-0183	●	○	○	○	○	○	○	○	○
Rover Longitude(degree)	NMEA-0183	●	○	○	○	○	○	○	○	○
Rover Altitude(meter)	NMEA-0183	●	○	○	○	○	○	○	○	○
Talker ID \$__GGA	NMEA-0183	●	○	○	○	○	○	○	○	○
Base Latitude (degree)(or auto convert to ECEF)	RTCM-DF026	○	●	●	○	○	●	○	○	○
Base Longitude (degree)(or auto convert to ECEF)	RTCM-DF025	○	●	●	○	○	●	○	○	○
Base Altitude (meter)(or auto convert to ECEF)	RTCM-DF027	○	●	●	○	○	●	○	○	○



Base Antenna Height (meter)	RTCM-DF028	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Quarter Cycle Indicator	RTCM-DF364	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Reserved for ITRF Realization Year	RTCM-DF021	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Reference Station ID	RTCM-DF003	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Physical Reference Station ID (0,4095)	RTCM-DF226	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Antenna Setup ID	RTCM-DF031	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Antenna Descriptor	RTCM-DF030	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Antenna Serial Number	RTCM-DF033	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Receiver Type Descriptor	RTCM-DF228	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Receiver Firmware Version	RTCM-DF230	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Receiver Serial Number	RTCM-DF232	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
GPS Indicator	RTCM-DF022									
GLONASS Indicator	RTCM-DF023									
GALILEO Indicator	RTCM-DF024	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Reference Indicator	RTCM-DF141									
Single Receiver Oscillator Indicator	RTCM-DF142	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Max satellite GPS	ESPrTK	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Max satellite GLONASS	ESPrTK	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Max satellite SBAS	ESPrTK	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Max OBS in an Epoch	ESPrTK	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>

**TIP !** : The table below describes the meanings of the fields defined according to the NMEA0183 and RTCM3.2 message standards.

Field	Data Field Notes
GGA - NMEA 0183	When used in the configuration field of ESPrtk, the input format is the geodetic coordinates (Lat-Long-Alt) used for NMEA-GGA messages.
RTCM3.2-DF025 RTCM3.2-DF026 RTCM3.2-DF027	The antenna reference point X-Y-Z-coordinate is referenced to ITRF epoch as given in DF021. When used in the configuration field of ESPrtk, the input format is geodetic coordinates (Lat-Long-Alt) and will be converted automatically to Cartesian ECEF (XYZ) coordinates when used in RTCM 1005 , 1006,1032 messages.
RTCM3.2-DF028	The Antenna Height field provides the height of the Antenna Reference Point above the marker used in the survey campaign.
RTCM3.2-DF364	The Quarter Cycle Indicator denotes whether different carrier phase signals tracked on the same frequency have a common phase, i.e. whether or not the fractional PhaseRanges of two signals on the same frequency show a quarter cycle difference (see also section 3.1.7 for further explanation).The definition of the indicator relates exclusively to the correction



	<p>status of the quarter cycle, and applies to Messages Types 1001, 1002, 1003, 1004, 1009, 1010, 1011, 1012 . Other possible corrections cannot be indicated by this indicator.</p> <ul style="list-style-type: none"> <li>• 0 - Correction status unspecified</li> <li>• 1 - PhaseRanges in Message Types 1001, 1002, 1003, 1004, 1009, 1010, 1011, 1012 are corrected in such a way that whenever PhaseRanges for different signals on the same frequency are present in these messages, they are guaranteed to be in phase and thus shall show no Quarter-Cycle bias between them (see Table 3.1-5 for details on the adjustments made). Double differences of PhaseRanges tracked with different signals shall show no QuarterCycle differences.</li> <li>• 2 - Phase observations are not corrected. Double differences may show Quarter-Cycle differences for PhaseRanges based on different signals on the same frequency. Processing will require appropriate corrections.</li> <li>• 3 – Reserved</li> </ul>
RTCM3.2-DF021	<p>ITRF Realization Year .          Since this field is reserved, all bits should be set to zero for now. However, since the value is subject to change in future versions, decoding should not rely on a zero value. The ITRF realization year identifies the datum definition used for coordinates in the message.</p>
RTCM3.2-DF003	<p>The Reference Station ID is determined by the service provider. Its primary purpose is to link all message data to their unique source. It is useful in distinguishing between desired and undesired data in cases where more than one service may be using the same data link frequency. It is also useful in accommodating multiple reference stations within a single data link transmission. In reference network applications the Reference Station ID plays an important role, because it is the link between the observation messages of a specific reference station and its auxiliary information contained in other messages for proper operation. Thus the Service Provider should ensure that the Reference Station ID is unique within the whole network, and that ID's should be reassigned only when absolutely necessary. Service Providers may need to coordinate their Reference Station ID assignments with other Service Providers in their region in order to avoid conflicts. This may be especially critical for equipment accessing multiple services, depending on their services and means of information distribution.</p>
RTCM3.2-DF226	<p>The Physical Reference Station ID specifies the station ID of a real reference station, when the data stream itself is based on a nonphysical reference station. Consequently, for the Physical Reference Station ID the same notes apply as for DF003.</p>
RTCM3.2-DF031	<ul style="list-style-type: none"> <li>• 0 - Use standard IGS Model .</li> <li>• 1-255 - Specific Antenna Setup ID# The Antenna Setup ID is a parameter for use by the service provider to indicate the particular reference station-antenna combination. The number should be increased whenever a change occurs at the station that affects the antenna phase center variations. While the Antenna Descriptor and the Antenna Serial Number give an indication of when the installed antenna has been changed, it is envisioned that other changes could occur. For instance the antenna may have been repaired, or the surrounding of the antenna may have been changed and the provider of the service may want to make the user station aware of the change. Depending on the change of the phase center variations due to a setup change, a change in the Antenna Setup ID would mean that the user should check with the service provider to see if the antenna phase center variation</li> </ul>



	in use is still valid. Of course, the provider must make appropriate information available to the users.
RTCM3.2-DF030	Alphanumeric characters. IGS limits the number of characters to 20 at this time, but this DF allows more characters for future extension.
RTCM3.2-DF033	Alphanumeric characters. The Antenna Serial Number is the individual antenna serial number as issued by the manufacturer of the antenna. A possible duplication of the Antenna Serial Number is not possible, because together with the Antenna Descriptor only one antenna with the particular number will be available. In order to avoid confusion the Antenna Serial Number should be omitted when the record is used together with reverse reduction to model type calibration values, because it cannot be allocated to a real physical antenna.
RTCM3.2-DF228	Any text string for Receiver Type Descriptor can be use. Max length = 31 characters.
RTCM3.2-DF230	Receiver Firmware Version
RTCM3.2-DF232	Receiver Serial Number
RTCM3.2-DF022	<ul style="list-style-type: none"> <li>• 0 - No GPS service supported</li> <li>• 1 - GPS service supported</li> </ul>
RTCM3.2-DF023	<ul style="list-style-type: none"> <li>• 0 - No GLONASS service supported</li> <li>• 1 - GLONASS service supported</li> </ul>
RTCM3.2-DF024	<ul style="list-style-type: none"> <li>• 0 - No Galileo service supported</li> <li>• 1 - Galileo service supported</li> </ul>
RTCM3.2-DF141	<p>Reference-Station Indicator .</p> <ul style="list-style-type: none"> <li>• 0 - Real, Physical Reference Station</li> <li>• 1 - Non-Physical or Computed Reference Station</li> </ul> <p>Note: A Non-Physical or Computed Reference Station is typically calculated based on information from a network of reference stations. Different approaches have been established over years. The NonPhysical or Computed Reference Stations are sometimes trademarked and may not be compatible. Examples of these names are “Virtual Reference Stations”, “Pseudo-Reference Stations”, and “Individualized Reference Stations”.</p>
RTCM3.2-DF142	<ul style="list-style-type: none"> <li>• 0 - All raw data observations in messages 1001-1004 and 1009-1012 may be measured at different instants. This indicator should be set to “0” unless all the conditions for “1” are clearly met.</li> <li>• 1 - All raw data observations in messages 1001-1004 and 1009-1012 are measured at the same instant, as described in Section 3.1.4.</li> </ul>
Max satellite GPS	Max satellite GPS for RTCM-1004 generartor, range [1,32]. ( Reducing the value will save the RAM for ESPrtk.)
Max satellite GLONASSS	Max satellite GLONASS for RTCM-1012 generartor, range [1,27]. ( Reducing the value will save the RAM for ESPrtk.)
Max satellite SBAS	Max satellite SBAS, range [1,35]. ( Reducing the value will save the RAM for ESPrtk.)



Max OBS in an Epoch

Max OBS in an Epoch, range [1,96]. ( Reducing the value will save the RAM for ESPrTk.)



## Command Write Configure - WIFI\_TCP\_UDP

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'v'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : WIFI\_TCP\_UDP

Number of field values : 9

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	5	0	-	-	Type Protocol	
PL3	PRINT	-	-	ESPRTK_WF	1	40	WiFi SSID / Hotspot's name	
PL4	PASS_A	-	-	12345678	0	40	WiFi Password	
PL5	STRING	-	-	192.168.4.2	1	40	IP Connect	
PL6	INTEGER	0	65535	4001	-	-	Port Connect	
PL7	STRING	-	-	192.168.4.1	1	40	Local IP	
PL8	INTEGER	0	65535	4000	-	-	Local Port	
PL9	STRING	-	-	192.168.4.0	1	40	Gateway	
PL10	STRING	-	-	255.255.255.0	1	40	Subnet	

PL0	PL1	PL2	Type Protocol	Unit
'W'	'e'	0	TCP Server Access Point	
		1	TCP Server Station	
		2	TCP Client Station	
		3	UDP Server Access Point	
		4	UDP Server Station	
		5	UDP Client Station	



Elements require	TCP Server AP	TCP Server STA	TCP Client STA	UDP Server AP	UDP Server STA	UPD Client STA
WIFI SSID (Name)	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
WiFi Password	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
IP Connect to	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Port Connect to	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Local IP	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Local Port	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Gateway IP	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>
Subnet IP	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input type="radio"/>

Main Action select		Feature support					
		TCP Server AP	TCP Server STA	TCP Client STA	UDP Server AP	UDP Server STA	UPD Client STA
No Main Action							
UART_to_Bluetooth	< ignore ! >	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
UART_Base_to_UART_Rover							
MQTT_Base	Internet via WiFi	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
NTRIP_Base							
MQTT_Rover	Internet via Ethernet/2G/3G/4G	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
NTRIP_Rover							
MQTT_Rover_Repeater	Radio repeater via WiFi	Internet via WiFi / Ethernet / 2G/3G/4G	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
NTRIP_Rover_Repeater							
Radio_Rover_Repeater	Radio repeater via LoRa	Internet via WiFi	<input type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input type="radio"/>	<input checked="" type="radio"/>
		Internet via Ethernet	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
		Internet via 2G/3G/4G	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Radio_Base	Radio Wireless bridge via WiFi		<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
Radio_Rover							
UART_to_RF_Base							
UART_to_RF_Rover	Radio Wireless bridge via LoRa		<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>
Bluetooth_to_RF_Base							
Bluetooth_to_RF_Rover			<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	<input checked="" type="radio"/>	



## ESPrtk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'v'	STRING	-	-	1	1	ID Configure : WIFI_TCP_UDP	
	PL3	INTEGER	0	1	-	-	Status Configure	
							0 Error: Failed to save , please try again	
							1 OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 85 W v 2 ESPRTK_WF 12345678 192.168.1.3 4001 192.168.1.4 4000 192.168.4.1 255.255.255.0 *3635
ACK Respond	\$ESP_OK 46 W v 1 ( ID : WIFI_TCP_UDP ) : Saved Success . *3C06
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - NTRIPCASTER\_Admin

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'w'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : NTRIPCASTER\_Admin

Number of field values : 9

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	STRING	-	-	admin	1	20	Name Login WebAdmin	
PL3	PASS_A	-	-	abc123ABC	1	20	Pass Login WebAdmin	
PL4	STRING	-	-	esprtk@gmail.com	1	60	Admin Email	
PL5	INTEGER	0	65535	80	-	-	WebAdmin Port	
PL6	INTEGER	0	65535	2101	-	-	Caster Port	
PL7	INTEGER	0	254	60	-	-	Cycle Update Parse NMEA	second
PL8	INTEGER	0	254	9	-	-	Basestation timeout data receive	second
PL9	INTEGER	3600	20000000	86400	-	-	Cycle save record limit	second
PL10	INTEGER	0	1	1	-	-	Enable Print Status to TX_UART_0	

PL0	PL1	PL7	Cycle Update Parse NMEA	Unit
'W'	'w'	0	Disable Update Parse NMEA	
		>= 1	Enable Update Parse NMEA	

PL0	PL1	PL8	Basestation timeout data receive	Unit
'W'	'w'	0	Disable Basestation timeout data receive	
		>= 1	Enable Basestation timeout data receive	



PL0	PL1	PL9	Cycle save record limit	Unit
'W'	'w'	0	Disable save record limit	
		1	Enable save record limit	second

PL0	PL1	PL10	Enable Print Status to TX_UART_0	Unit
'W'	'w'	0	Disable Print Status to TX_UART_0	
		1	Enable Print Status to TX_UART_0	

Payload Index	Describe	Detail	Unit
PL2	Name Login WebAdmin	For Admins/Owners of NTRIP CASTER, used to login to Dashboard site to manage user accounts.	
PL3	Pass Login WebAdmin		
PL4	Admin Email	When NTRIP CASTER detected client error or abuse. CASTER will send an error message with the email address of the administrator (admin) via NTRIP Stream , so customers can contact them to resolve the issue.	
PL5	WebAdmin Port	The port that NTRIP CASTER uses to run the Dashboard page. Usually 80. Then , the Dashboard's address will be <a href="http://x.x.x.x/admin">http://x.x.x.x/admin</a> or <a href="http://x.x.x.x:80/admin">http://x.x.x.x:80/admin</a> ( With x.x.x.x is the local IP address of that NTRIP CASTER ) . Setting this value to 0 will not activate the Dashboard and increase the number of sockets by 1 for the NTRIP Client / Server.	
PL6	Caster Port	The port that NTRIP CASTER uses to listen to and respond to connections from the NTRIP Client (Rover / Base). Usually 2101. Then , the Sourcetable Page's address will be <a href="http://x.x.x.x:2101">http://x.x.x.x:2101</a> or <a href="http://x.x.x.x:80">http://x.x.x.x:80</a> ( With x.x.x.x is the local IP address of that NTRIP CASTER )	
PL7	Cycle Update Parse NMEA	NTRIP CASTER will collect the Rover's location via GGA / NMEA message. Setting the	second



		cycle as small will help show the location with a lower delay. Recommended value is above 60s. Setting this value to 0 disables this function.	
PL8	Basestation timeout data receive	NTRIP CASTER acts as a data bridge, it receives RTCM data from NTRIP Base and distributes it to all Rovers. If NTRIP Base stops sending RTCM data after a period of time, NTRIP CASTER will understand the NTRIP Base has lost connection (died or stopped working). The default value is 9 seconds.	second
PL9	Cycle save record limit	All changes, user configuration data, bandwidth counter, etc. will be automatically saved to FLASH periodically after a period of time. The default value is 86400 seconds. ( 1 day ). Setting this value to 0 disables this function.	second
PL10	Enable Print Status to TX_UART_0		

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'w'	STRING	-	-	1	1	ID Configure : NTRIPCASTER_Admin	
	PL3	INTEGER	0	1	-	-	Status Configure	
						0	Error: Failed to save , please try again	
						1	OK : Saved configure success	
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format	

## Example

Message :	
HOST Send	\$ESP_OK 58 W w admin abc123ABC esprtk@gmail.com 80 2101 60 9 86400 1 *675B
ACK Respond	\$ESP_OK 51 W w 1 ( ID : NTRIPCASTER_Admin ) : Saved Success . *7F40
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - NTRIPCASTER\_ACC

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'x'	Infor 1	Infor 2	Infor 3	Infor 4	...

Name CFG : NTRIPCASTER\_ACC

Number of field values : 180

Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL2	STRING	-	-	name_0	1	10	Login Name	
PL3	PASS_A	-	-	pass_0	1	10	Password	
PL4	INTEGER	0	10	10	-	-	Number Rover	
PL5	STRING	-	-	Base_0	1	10	Mountpoint	
PL6	INTEGER	0	1	0	-	-	VRS Support	
PL7	FLOAT	0.000	100000000 0	0	-	-	Limit Highest Speed Bandwidth	bps
PL8	INTEGER	0	10000000	0	-	-	Limit Total Bandwidth (Byte Count)	GByte
PL9	INTEGER	0	200000000 0	0	-	-	Limit time running	second
PL10	FLOAT	0.000	100000000 0	0	-	-	Offset Highest Speed Bandwidth (counter start from this value)	bps
PL11	INTEGER	0	10000000	0	-	-	Offset Total Bandwidth (Byte Count) . (counter start from this value)	GByte
PL12	INTEGER	0	200000000 0	0	-	-	Offset time running (counter start from this value)	second
PL13	INTEGER	0	1	0	-	-	Enable use STR from Client/User	
PL14	PRINT	-	-	Tokyo_JAPAN ;RTCM 3.2;1005(1),10 77(1),1087(1); 3;GPS+GLO;S	0	250	STR String . ( <identifier><format><format- details><carrier><nav- system><network><country><la titude><longitude><nmea><solu	



				NIP;JPN;35.68 ;139.69;0;1;sN TRIP;yes;B;N; 3620;none			tion><generator><compression> <authentication><fee><bitrate>< misc> )	
PL15 to PL27	Configure field from PL15 to PL27 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL28 to PL40	Configure field from PL28 to PL40 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL41 to PL53	Configure field from PL41 to PL53 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL54 to PL66	Configure field from PL54 to PL66 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL67 to PL79	Configure field from PL67 to PL79 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL80 to PL92	Configure field from PL80 to PL92 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL93 to PL105	Configure field from PL93 to PL105 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL93 to PL105	Configure field from PL106 to PL118 (for Account #d) is the same with Configure feild from PL2 to PL14							
PL119 to PL131	Configure field from PL119 to PL131 (for Account #d) is the same with Configure feild from PL2 to PL14							
Payload Index	Type value	Min Value	Max Value	Default Value	Min Length	Max Length	Describe	Unit
PL132	HEX_Up	00000000	FFFFFFFF	00000000	-	-	Ban IP (IP #1 )	
PL133 to PL182	Configure field from PL133 to PL182 (IP #2 → IP #50 ) is the same with Configure feild PL132							

## ESPrTk Respond

Payload	Type value	Min	Max	Min	Max	Describe	Unit
---------	------------	-----	-----	-----	-----	----------	------



Index		Value	Value	Length	Length		
PL2	'x'	STRING	-	-	1	1	ID Configure : NTRIPCASTER_ACC
	PL3	INTEGER	0	1	-	-	Status Configure
							0 Error: Failed to save , please try again
							1 OK : Saved configure success
	PL4	STRING	-	-	-	-	Describe Status Configure in text string format

## Example

Message :	
HOST Send	\$ESP_OK 587 W x name_0 pass_0 10 Base_0 0 0 0 0 0 Tokyo_JAPAN;RTCM 3.2;1005(1),1077(1),1087(1);3;GPS+GLO;SNIP;JPN;35.68;139.69;0;1;sNTRIP;yes;B;N;3620;none  name_1 pass_1 10 Base_1 0 0 0 0 0 REZONVILLE_FRA;RTCM 3.2;1005(1),1077(1),1087(1),1097(1),1127(1);3;GPS+GLO+GAL+BDS;SNIP;FRA;49.10;5.98;0;1;s NTRIP;yes;B;N;7620;none _ 0 _ 0 0 0 0 0 0 0 _ 0 _ 0 0 0 0 0 0 0 _ 0 _ 0 0 0 0 0 0 0 _  0 _ 0 0 0 0 0 0 0 0 _ 0 _ 0 0 0 0 0 0 0 _ 0 _ 0 0 0 0 0 0 0 _ 0 _ 0 0 0 0 0 0 0 _  0 0 0 0 0 0 00000000 *4C0F
ACK Respond	\$ESP_OK 49 W x 1 ( ID : NTRIPCASTER_ACC ) : Saved Success . *7709
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Start UART Configure mode for Read configure data.

### Use ESPrtk command to start UART configure

Use ESPrtk command control	
Step 0	ESPrtk after supplying power.
Step 2	HOST send command : <b>\$ESP_OK 5 O _ *441E</b>
Done	ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 O _ *441E</b>

## Command Read Configure ESPrtk

**Tip :** To use these command , ESPrtk need running at UART Configure mode !

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'R'	ID Command	Infor 1	Infor 2	Infor 3	Infor 4	...

PL0	PL1	Describe Type ID Command	Example
'R'	'a'	CREATE NEW PROFILE	
'R'	'b'	LOGIN_LOGOUT	
'R'	'c'	Read YOUR_PROFILE 's configure data	\$ESP_OK 5 R c *653F
'R'	'd'	Read ACTION_PLANNING 's configure data	\$ESP_OK 5 R d *6238
'R'	'e'	Read INTNERNET 's configure data	\$ESP_OK 5 R e *6339
'R'	'f'	Read RADIO_RTK 's configure data	\$ESP_OK 5 R f *603A
'R'	'g'	Read MQTT_RTK 's configure data	\$ESP_OK 5 R g *613B
'R'	'h'	Read NTRIP_CLIENT 's configure data	\$ESP_OK 5 R h *6E34



'R'	'i'	Read NTRIP_MASTER 's configure data	\$ESP_OK 5 R i  *6F35
'R'	'j'	Read UART_CONFIGURE 's configure data	\$ESP_OK 5 R j  *6C36
'R'	'k'	Read BLUETOOTH 's configure data	\$ESP_OK 5 R k  *6D37
'R'	'l'	Read DISPLAY_VIEWER 's configure data	\$ESP_OK 5 R l  *6A30
'R'	'm'	Read EVENT_LOG 's configure data	\$ESP_OK 5 R m  *6B31
'W'	'n'	Request convert ID Error to text - SIMPLE_DEBUG	\$ESP_OK 7 W n 23 *6E07
'R'	'o'	Read SD_CARD 's configure data	\$ESP_OK 5 R o  *6933
'R'	'p'	Read IMU_MPU9250 's configure data	\$ESP_OK 5 R p  *762C
'R'	'q'	Read GPIO_PIN_MAP 's configure data	\$ESP_OK 5 R q  *772D
'R'	'r'	Read SYSTEM_Other_Mode 's configure data	\$ESP_OK 5 R r  *742E
'R'	's'	Read GSM_CELLULAR 's configure data	\$ESP_OK 5 R s  *752F
'R'	't'	Read STREAM_MANAGER's configure data	\$ESP_OK 5 R t  *7228
'R'	'u'	Read POSITION_ANTENNA's configure data	\$ESP_OK 5 R u  *7329
'R'	'v'	Read WIFI_TCP_UDP's configure data	\$ESP_OK 5 R v  *702A
'R'	'w'	Read NTRIPCASTER_Admin's configure data	\$ESP_OK 5 R w  *712B
'R'	'x'	Read NTRIPCASTER_ACC's configure data	\$ESP_OK 5 R x  *7E24
'R'	'y'	Request ERROR_SYSTEM	\$ESP_OK 5 R y  *7F25
'R'	'z'	Request VERSION_MAC 's configure data	\$ESP_OK 5 R z  *7C26



## Command Read configure - YOUR\_PROFILE

**Note:** This configure only work on WEB Configure interface !

### ESPrTk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R c *653F
ACK Respond	\$ESP_OK 80 R c ESPrTk : IHGG4 def123DEF 0 admin abc123ABC ESPrTk new user Hello member 1 0 *164C
NACK Respond	\$ESP_ER 76 R j NACK : Only support this action on WEB Configure or Command Tester Tool *6F38

## Command Read configure - ACTION\_PLANNING

### ESPrTk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R d *6238
ACK Respond	\$ESP_OK 41 R d 10 1 8 6 6 1 0 0 00000000000000000000 *5B5C
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Read configure - INTERNET

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R e  *6339
ACK Respond	\$ESP_OK 67 R e 0 1 TEWM_B31B6B 884744F797 Tran Trong Toan 12121975 My Router  *1C0E
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - RADIO\_RTK

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R f  *603A
ACK Respond	\$ESP_OK 52 R f abc_LoRa_WiFi_012345 0 0 9 0 433000000 0 9 8 10 *1C06
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Read configure - MQTT\_RTK

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R g *613B
ACK Respond	\$ESP_OK 104 R g m11.cloudmqtt.com 18052 rkdpcppo nvZv101KE_SX 9R082_O68R1 RTCM NMEA FAST_NMEA 1 abc_MQTT_RTK_012345 *3855
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - NTRIP\_CLIENT

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R h *6E34
ACK Respond	\$ESP_OK 31 R h rtk2go.com 2101 no no no 1 *0F7D
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - NTRIP\_MASTER

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.



## Example

Message :	
HOST Send	\$ESP_OK 5 R i  *6F35
ACK Respond	\$ESP_OK 173 R i rtk2go.com 2101 A00_81909_GHB9A BETATEST2 1 0 San_Jose-Calif 13 1005(1),1077(1),1107(1),1117(1) 1 1 1 0 1 0 1 0 0 0 SNIP USA 37.388 -121.9 1 0 0 1 0 8600 ESPrtk-Base *491E
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - UART\_CONFIGURE

**Note:** This configure only work on WEB Configure interface !

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

## Example

Message :	
HOST Send	\$ESP_OK 5 R j  *6C36
ACK Respond	\$ESP_OK 48 R j 1 1 0 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 *6508
NACK Respond	\$ESP_ER 76 R j NACK : Only support this action on WEB Configure or Command Tester Tool *6F38

## Command Read configure - BLUETOOTH

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

## Example

Message :	
HOST Send	\$ESP_OK 5 R k  *6D37



ACK Respond	\$ESP_OK 56 R k 0 BTU-ESPrtk : 81909_GHB9A BLE-ESPrtk : 81909_GHB9A *6332
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - DISPLAY\_VIEWER

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R l *6A30
ACK Respond	\$ESP_OK 20 R l 1 6 6 0 1 0 1 0 *2009
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - EVENT\_LOG

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R m *6B31
ACK Respond	\$ESP_OK 14 R m 3 0 0 0 0 *6876
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Request convert ID Error to text - SIMPLE\_DEBUG

### HOST send request convert ID Error to text

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'W'	'n'	ID_Error	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	255	-	-	ID_ERROR	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	INTEGER	0	255	-	-	ID_ERROR	
PL3	STRING	-	-	-	-	Type of error in string	
PL4	STRING	-	-	-	-	Detail describe error in string.	
PL5	STRING	-	-	-	-	Guess the cause of this error and Suggestions for how to resolve this error.	

## Example

Message :	
HOST Send	\$ESP_OK 7 W n 39 *6506
ACK Respond	\$ESP_OK 130 W n 39 SETTUP No any Actions to do !  ,How_to_fix: Go to Web Configure -> tab Action Planning -> Enable action for ESPrTk  *0C52
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...





## Command Read configure - GPIO\_PIN\_MAP

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R q  *772D
ACK Respond	\$ESP_OK 72 R q 18 4 21 1 16 10 14 0 17 11 13 7 8 2 22 19 12 9 23 20 15 3 24 6 25 5 *3A0B
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - SYSTEM\_Other\_Mode

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R r  *742E
ACK Respond	\$ESP_OK 50 R r 9 3 3 3 3 111111111111 11111111111111111111 *3272
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command read configure - GSM\_CELLULAR

### ESPrtk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.





## Command Read configure - POSITION\_ANTENNA

### ESPrTk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R u  *7329
ACK Respond	\$ESP_OK 181 R u 000000000 60 60 60 60 60 60 60 1 1 47.082164 2.399216 10.000 GP 47.000000 2.000000 10.000 0 0 0 0 123 ADVNULLANTENNA 0.0.0.0 ESPRTK 3.9.0 _ 4.x.x TS9PC_S9SUB 10000 20 20 1 96 *6070
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## Command Read configure - WIFI\_TCP\_UDP

### ESPrTk Respond

The index / range of values / data types is similar to the index / range of values / data types of payloads when configured.

### Example

Message :	
HOST Send	\$ESP_OK 5 R v  *702A
ACK Respond	\$ESP_OK 85 R v 2 ESPRTK_WF 12345678 192.168.1.3 4001 192.168.1.4 4000 192.168.4.1 255.255.255.0 *3330
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...







PL2	PRINT	%d/%d/%d	1/1/20	Date/ Month /Year ESPrTk Version	
PL3	PRINT	%d.%d.%d	3.0.0	ESPrTk Version	
PL4	PRINT	%X02:%X02:%X02:%X02:%X02:%X02	30:AE:A4:28:24:90	6 bytes MAC Address	
PL5	PRINT	%d	1	CHIP Revision	
PL6	PRINT	%d	2	Number of cores of ESP32	

## Example

### Message :

HOST Send	\$ESP_OK 5 R z  *7C26
ACK Respond	\$ESP_OK 41 R z 21/12/19 2.7.9 30:AE:A4:28:24:90 1 2 *3627
NACK Respond	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Start UART Configure mode for Hardware control.

### Use ESPrtk command to start UART configure

Use ESPrtk command control	
Step 0	ESPrtk after supplying power.
Step 2	HOST send command : <b>\$ESP_OK 5 O _ *441E</b>
Done	ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 O _ *441E</b>

## Command Hardware control ESPrtk

**Tip :** To use these command , ESPrtk need running at UART Configure mode !

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	..	...
\$ESP_OK xx	'T'	ID Command	ID Control	Infor 1	Infor 2	...	...

PL0	PL1	Describe Type Command			Numbers of ID Control
'T'	'P'	PL2	<b>Control Enable Type Print on TX_UART0</b>		1
		'0'	P_Control Enable Type Print on TX_UART0		
'T'	'G'	PL2	<b>Control GPIO on ESPrtk</b>		3
		'0'	G_SET_MODE_GPIO		
		'1'	G_WRITE_DIGITAL		
		'2'	G_READ_DIGITAL		



'T'	'U'	<b>PL2</b>	<b>Control UART_1 and UART_2 on ESPrTk</b>	8
		'0'	U_Start_UART	
		'1'	U_Check_UART_Started	
		'2'	U_Send_String	
		'3'	U_Send_Binary	
		'4'	U_Available	
		'5'	U_Read_String	
		'6'	U_Read_Binary	
		'7'	U_Clear_Buffer	
'T'	'I'	<b>PL2</b>	<b>Control WIFI and Ethernet module connect to router</b>	6
		'0'	I_Start_WIFI_and_Connect_to_Router	
		'1'	I_WIFI_Disconnect_to_Router	
		'2'	I_Start_Ethernet_ENC28j60_and_Connect_to_Router	
		'3'	I_Ethernet_ENC28j60_Disconnect_to_Router	
		'4'	I_Start_Ethernet_W5XX_and_Connect_to_Router	
		'5'	I_Ethernet_W5XX_Disconnect_to_Router	
'T'	'T'	<b>PL2</b>	<b>Control TCP Client Task communicate with Server</b>	9
		'0'	T_Connect_to_Server	
		'1'	T_Check_Connected_to_Server	
		'2'	T_Send_String	
		'3'	T_Send_Binary	
		'4'	T_Available	
		'5'	T_Read_String	
		'6'	T_Read_Binary	



		'7'	T_Clear_Buffer	
		'8'	T_Diconnect_to_Server	
'T'	'B'	<b>PL2</b>	<b>Control Bluetooth Classic and Bluetooth BLE on ESPrtk</b>	8
		'0'	B_Start_Bluetooth	
		'1'	B_Check_Client_Connected	
		'2'	B_Send_String	
		'3'	B_Send_Binary	
		'4'	B_Available	
		'5'	B_Read_String	
		'6'	B_Read_Binary	
		'7'	B_Clear_Buffer	
'T'	'O'	<b>PL2</b>	<b>Control OLED Display (SSD1306/SH1106)</b>	12
		'0'	O_Start_OLED	
		'1'	O_Update_and_Display	
		'2'	O_Clear	
		'3'	O_Draw_Dot	
		'4'	O_Draw_Line	
		'5'	O_Draw_Rect	
		'6'	O_Draw_Rect_Corner	
		'7'	O_Draw_Triangle	
		'8'	O_Draw_Circle	
		'9'	O_Draw_Elippse	
		'A'	O_Draw_Character	
		'B'	O_Draw_Number	



'T'	'S'	PL2	Control SD Card	10
		'0'	S_Start_SD_Card	
		'1'	S_Check_Folder_Exist	
		'2'	S_Create_Folder	
		'3'	S_Delete_File	
		'4'	S_Rename_File	
		'5'	S_Check_File_Exist	
		'6'	S_Create_File	
		'7'	S_Get_Size_File	
		'8'	S_Read_Binary_data_File	
		'9'	S_Append_Binary_data_to_File	
'T'	'M'	PL2	Control IMU (MPU9250)	5
		'0'	M_Start_Print_IMU_Data	
		'1'	M_Stop_Print_IMU_Data	
		'2'	M_Start_IMU_Calibrate	
		'3'	M_Stop_IMU_Calibrate	
		'4'	M_Save_Calibrate_Result	
			Disable/Enable type IMU data	
'T'	'V'	PL2	Control Deep Sleep	2
		'0'	V_Enter_Deep_Sleep_mode	
		'1'	V_Exit_Deep_Sleep_mode_and_WakeUp	





## Command Hardware Control – Control Enable Type Print on TX\_UART0

**Tip :** This control command works on UART configure mode , Main Action mode and WEB configure mode via UART0.

### HOST send Control Enable Type Print on TX\_UART0

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'P'	ID Control	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'0'					ID Control : Enable Type Print on TX_UART0	
PL3	BIT	-	-	12	12	BIT Enable Type Print on TX_UART0	

PL0	PL1	PL2	PL3	Enable print message types on TX_UART0 port	Unit
'T'	'P'	'0'	BIT1	_SYSTEM_ (ESPrtk System)	
			BIT2	_ERROR_ (Error status)	
			BIT3	_INFO_ (Text , Log, Information...)	
			BIT4	_GOIN_ (Go to function status)	
			BIT5	_WFSCAN_ (Wifi Scan Result)	
			BIT6	_BROKER_ (Broker MQTT Status)	
			BIT7	_RVNMEA_ (print NMEA from Rover)	
			BIT8	_CONFIG_ (Configure information detail)	
			BIT9	\$_GGA (Rover print GGA message)	
			BIT1 0	\$_NMEA_ (Rover print NMEA message)	
			BIT1 1	\$ESPIM1 (IMU MPU9250 Data type 1)	
			BIT1 2	\$ESPIM2 (IMU MPU9250 Data type 2)	



## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : Enable Type Print on TX_UART0		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: BIT enable PRINT invalid	
						0	-	
						1	OK	
PL4	BIT	-	-	12	12	BIT Enable Type Print on TX_UART0		

## Example

Message :	
HOST Send	\$ESP_OK 19 T P 0 111111111111 *2157
ACK Respond	\$ESP_OK 21 T P 0 1 111111111111 *676E
NACK Respond	\$ESP_ER 40 T P 0 -1 NACK: BIT enable PRINT invalid *1D14
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Hardware Control – Control GPIO on ESPrTk

**Tip :** This control command works on UART configure mode , Main Action mode and WEB configure mode via UART0.

'T'	'G'	<b>PL2</b>	<b>Control GPIO on ESPrTk</b>	
		'0'	G_SET_MODE_GPIO	
		'1'	G_WRITE_DIGITAL	
		'2'	G_READ_DIGITAL	

### HOST send Control G\_SET\_MODE\_GPIO

Not support !

### HOST send Control G\_READ\_DIGITAL

Not support !

### HOST send Control G\_WRITE\_DIGITAL

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'G'	ID Control	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : G_WRITE_DIGITAL	
PL3	BIT	-	-	19	19	BIT control GPIO ESPrTk	
						0   Set GPIO to LOW Level	
						1   Set GPIO to HIGH Level	

PL	PL	PL	PL3	<b>GPIO ESPrTk</b>	PL3	<b>GPIO ESPrTk</b>
0	1	2				





**Tip 1 :** When BIT respond is ‘X’, that mean the GPIO pin was used by other task (such as UART\_1\_2 , LoRa , IMU, Ethernet , SD\_Card, NeoPixel, OLED, ERROR\_LED , CONNECT\_LED ....etc).

For example, if you use the pin map ESPrtk as default configure like this :

Configure	JSON Configure
<b>Default from factory</b>	<pre>{   "CWB_Button" : "13" ,      "RX_UART0" : "3" ,  "MOSI_SD_Card" : "23" ,   "MOSI_LoRa_Ethe" : "33" , "TX_UART0" : "1" ,  "MISO_SD_Card" : "39" ,   "MISO_LoRa_Ethe" : "35" , "RX_UART1" : "17" , "SCK_SD_Card" : "18" ,   "SCK_LoRa_Ethe" : "25" ,  "TX_UART1" : "5" ,  "CONNECT_LED" : "15" ,   "CS_SD_Card" : "19" ,     "RX_UART2" : "16" , "ERROR_LED" : "12" ,   "CS_LoRa" : "32" ,       "TX_UART2" : "4" ,  "TX_UART3" : "14" ,   "CS_Ethernet_PWR_GSM" : "0" , "SCL_I2C" : "22" ,  "SCL_OLED" :   "27" ,   "RST_LoRa_Ethe" : "2" ,   "SDA_I2C" : "21" ,  "SDA_OLED" : "26" ,   "DI0_LoRa" : "34" ,      "RX_UART3" : "36" }</pre>

To use GPIO for Hardware Control , you must release them before.

External deives	To Release	Release
SD_Card	At Write Configure – ACTION_PLANNING (at configure Other Action) → Disable all BIT save data to SD_Card	<b>23 , 39 , 18 , 19</b>
LoRa Ethernet	At Write Configure – RADIO_RTK → Select Type radio link is WIFI to release LoRa	<b>33 , 35 , 25 , 2 , 34 , 0 , 32</b>
	At Write Configure – INTNERNET → Select Type internet is WIFI only to release Ethernet	
Sensor/IMU	At Write Configure – ACTION_PLANNING ( at configure Other Action) → Disable BIT export IMU data	<b>22 , 21</b>
CONNECT_LED	At Write Configure – DISPLAY_VIEWER → Disable use CONNECT_LED	<b>15</b>
ERROR_LED	At Write Configure – DISPLAY_VIEWER → Disable use ERROR_LED	<b>12</b>



Oled	At Write Configure – DISPLAY_VIEWER → Select Type Display is NEOPIXEL	<b>27 , 26</b>
TX_UART12	At Write Configure – ACTION_PLANNING → Select Map TX-UART-RTK to other TX UART port	<b>5 (or 4)</b>
RX_UART12	At Write Configure – ACTION_PLANNING → Select Map RX-UART-RTK to other RX UART port	<b>17 (or 16)</b>

**Tip 2 :** GPIO pins in the release state (idle / not use / free ) can be used for **GPIO control** . However, when users use other control functions such as Ethernet / IMU / SD Card, etc., IO pins will be taken back control for those functions !. (GPIO control will ignore those pins if they are used again.)



## Command Write Configure - Control UART\_1 and UART\_2 on ESPrTk

'T'	'U'	<b>PL2</b>	<b>Control UART_1 and UART_2 on ESPrTk</b>	8
		'0'	U_Start_UART	
		'1'	U_Check_UART_Started	
		'2'	U_Send_String	
		'3'	U_Send_Binary	
		'4'	U_Available	
		'5'	U_Read_String	
		'6'	U_Read_Binary	
		'7'	U_Clear_Buffer	

### HOST send Control U\_Start\_UART

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : U_Check_UART_Started		
	PL3	INTEGER	1	2	-	-	Select UART1 or UART2 for UART_CF	



PL4	INTEGER	2400	1000000	-	-	Baudrate UART_CF	bps
PL5	INTEGER	255	2000	-	-	Buffer size RX of UART_CF	byte

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : U_Check_UART_Started		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	-	
						1	OK	
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 19 T U 0 1 57600 1000 *2051
ACK Respond	\$ESP_OK 61 T U 0 1 Start UART_1 success,Baudrate = 57600,RX_Size = 1000 *4C2E
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control U\_Check\_UART\_Started

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Valu	Max Value	Min Length	Max Length	Describe	Unit
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		e							
PL2	'1'	STRING	-	-	1	1	ID Control : U_Check_UART_Started		

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'1'					ID Control : U_Check_UART_Started		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	UART not started	
						1	UART started	
PL4	STRING	-	-	-	-	Describe status respond control as text		

### Example

Message :	
HOST Send	\$ESP_OK 6 T U 1 *6726
ACK Respond	\$ESP_OK 31 T U 1 1 UART Connected success *4C0F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control U\_Send\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'2'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'2'						ID Control : U_Send_String	
	PL3	STRING	-	-	1	1500	Data send in string format	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'						ID Control : U_Send_String	
	PL3	INTEGER	-1	2	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error : UART_CF was not started .	
							1 Error: Busy TX is sending	
							2 OK: Send String success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :	
HOST Send	\$ESP_OK 29 T U 2 My String out UART\r\n *645B
ACK Respond	\$ESP_OK 33 T U 2 2 UART Send String success *3844
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control U\_Send\_Binary

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'3'	Infor 1	Infor 2	Infor 3	...



Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : U_Send_Binary	
	PL3	HEX	-	-	2	1400	Data send in string format

### ESPrk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : U_Send_Binary	
	PL3	INTEGER	-1	2	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error : UART_CF was not started .
							1 Error: Busy TX is sending
							2 OK: Send Binary success
	PL4	STRING	-	-	-	-	Describe status respond control as text

### Example

Message :	
HOST Send	\$ESP_OK 17 T U 3 A0B0D0E12F *5E6F
ACK Respond	\$ESP_OK 33 T U 3 2 UART Send Binary success *2354
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control U\_Available

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...



\$ESP_OK xx	‘T’	‘U’	‘4’	Infor 1	Infor 2	Infor 3	...
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Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	‘4’	STRING	-	-	1	1	ID Control : U_Available

### ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	‘4’					ID Control : U_Available	
	PL3	INTEGER	-1	1000	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							[0,1000] Size available RX buffer UART

### Example

Message :	
HOST Send	\$ESP_OK 6 T U 4 *6226
ACK Respond	\$ESP_OK 11 T U 4 1000 *295F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control U\_Read\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘U’	‘5’	Infor 1	Infor 2	Infor 3	...



Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : U_Read_String	
	PL3	INTEGER	1	1000	-	-	Size read buffer UART

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : U_Read_String	
	PL3	INTEGER	-1	1000	-	-	Status Control
						-1	NACK: Invalid input /wrong format / out of range ...?
						[0,1000]	Size of string respond
	PL4	STRING	-	-	0	1000	Data read buffer in String format

### Example

Message :	
HOST Send	\$ESP_OK 9 T U 5 12 *1307
ACK Respond	\$ESP_OK 22 T U 5 12 \$GPGGA,06350 *3827
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control U\_Read\_Binary

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'6'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'						ID Control : U_Read_Binary	
	PL3	INTEGER	1	1000	-	-	Size read buffer UART	

### ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'						ID Control : U_Read_Binary	
	PL3	INTEGER	-1	1000	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							[0,1000] Size of string respond	
	PL4	STRING	-	-	-	-	Data read buffer in HEX format	

### Example

Message :	
HOST Send	\$ESP_OK 9 T U 6 12 *1004
ACK Respond	\$ESP_OK 34 T U 6 12 332E3030302C323033342E36 *203B
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control U\_Clear\_Buffer

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'U'	'7'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'7'	STRING	-	-	1	1	ID Control : U_Clear_Buffer	

### ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'7'						ID Control : U_Clear_Buffer	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 -	
							1 Clear Buffer Success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 6 T U 7 *6126
ACK Respond	\$ESP_OK 34 T U 7 1 UART Clear Buffer Success *6931
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - Control WIFI and Ethernet module connect to router

'T'	'I'	<b>PL2</b>	<b>Control WIFI and Ethernet module connect to router</b>	6
		'0'	I_Start_WIFI_and_Connect_to_Router	
		'1'	I_WIFI_Disconnect_to_Router	
		'2'	I_Start_Ethernet_ENC28j60_and_Connect_to_Router	
		'3'	I_Ethernet_ENC28j60_Disconnect_to_Router	
		'4'	I_Start_Ethernet_W5XX_and_Connect_to_Router	
		'5'	I_Ethernet_W5XX_Disconnect_to_Router	

## HOST send Control I\_Start\_WIFI\_and\_Connect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'I'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'	STRING	-	-	1	1	ID Control : I_Start_WIFI_and_Connect_to_Router	

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
---------------	------------	-----------	-----------	------------	------------	----------	------



PL2	'0'						ID Control : I_Start_WIFI_and_Connect_to_Router	
	PL3	INTEGER	-1	2	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: No data SSID-PASS in Profile
							1	WiFi Connecting... please wait in 5 second
							2	WiFi Connected to router

### Example

Message :	
HOST Send	\$ESP_OK 6 T I 0 *7A26
ACK Respond	\$ESP_OK 72 T I 0 1 WiFi Connecting... please wait in 5 second . List:[TEWM_B31B6B] *4C32 >> Error timeout - Wifi cannot connect to router after 10s >> Wifi Connected to TEWM_B31B6B
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

**Tip:** To change SSID-PASS , see UART\_Configure → INTERNET configure.

### HOST send Control I\_WIFI\_Disconnect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'1'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'	STRING	-	-	1	1	ID Control : I_WIFI_Disconnect_to_Router

### ESPrtk Respond

Payload	Type value	Min	Max	Min	Max	Describe	Unit
---------	------------	-----	-----	-----	-----	----------	------



Index		Value	Value	Length	Length	
PL2	'1'					ID Control : I_WIFI_Disconnect_to_Router
	PL3	INTEGER	-1	1	-	-
						Status Control
						-1 NACK: Invalid input /wrong format / out of range ...?
						0 Disconnecting WiFi...Please wait in 3 seconds
						1 WiFi Disconnected success

### Example

Message :	
HOST Send	\$ESP_OK 6 T I 1 *7B26
ACK Respond	\$ESP_OK 26 T I 1 1 WiFi Disconnected *6845
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control I\_Start\_Ethernet\_ENC28j60\_and\_Connect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'I'	'2'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'2'	STRING	-	-	1	1	ID Control : I_Start_Ethernet_ENC28j60_and_Connect_to_Router

### ESPrTk Respond



Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'2'					ID Control : I_Start_Ethernet_ENC28j60_and_Connect_to_Router	
	PL3	INTEGER	-1	2	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error : Not found ENC28J60 on SPI port
							1 Ethernet Connecting... please wait in 10 seconds
							2 Ethernet Connected to Router

### Example

Message :	
HOST Send	\$ESP_OK 6 T I 2 *7826
ACK Respond	\$ESP_OK 46 T I 2 0 Error- Not found Ethernet on SPI port *4962 \$ESP_OK 57 T I 2 1 Ethernet Connecting... please wait in 10 seconds *3C4C \$ESP_OK 27 T I 2 2 Ethernet Connected *376D
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control I\_Ethernet\_ENC28j60\_Disconnect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'I'	'3'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'	STRING	-	-	1	1	ID Control : I_Ethernet_ENC28j60_Disconnect_to_Router



## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : I_Ethernet_ENC28j60_Disconnect_to_Router	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Disconnecting Ethernet ...Please wait in 10 seconds
							1 Ethernet Disconnected to router

## Example

Message :	
HOST Send	\$ESP_OK 6 T I 3 *7926
ACK Respond	\$ESP_OK 60 T I 3 0 Disconnecting Ethernet ...Please wait in 10 seconds *6606 .... \$ESP_OK 30 T I 3 1 Ethernet Disconnected *4D4F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control

### I\_Start\_Ethernet\_W5XX\_and\_Connect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'I'	'4'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'4'	STRING	-	-	1	1	ID Control : I_Start_Ethernet_W5XX_and_Connect_to_Router
-----	-----	--------	---	---	---	---	---

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'					ID Control : I_Start_Ethernet_W5XX_and_Connect_to_Router	
PL3	INTEGER	-1	2	-	-	Status Control	
						-1 NACK: Invalid input /wrong format / out of range ...?	
						0 Error : Not found W5XX module on SPI port	
						1 Ethernet Connecting... please wait in 10 seconds	
						2 Ethernet Connected to Router	

### Example

Message :	
HOST Send	\$ESP_OK 6 T I 4 *7E26
ACK Respond	\$ESP_OK 46 T I 4 0 Error- Not found Ethernet on SPI port *4F62 \$ESPLOG 58 2 INFO SPI Scan Success : Connected to Ethernet over SPI. *5C31 >> Ethernet Connected \$ESP_OK 27 T I 4 2 Ethernet Connected *316B
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control I\_Ethernet\_W5XX\_Disconnect\_to\_Router

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'I'	'5'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'	STRING	-	-	1	1	ID Control : I_Ethernet_W5XX_Disconnect_to_Router	

### ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'						ID Control : I_Ethernet_W5XX_Disconnect_to_Router	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Disconnecting Ethernet ...Please wait in 10 seconds	
							1 Ethernet Disconnected to router	

### Example

Message :	
HOST Send	\$ESP_OK 6 T I 5 *7F26
ACK Respond	\$ESP_OK 60 T I 3 0 Disconnecting Ethernet ...Please wait in 10 seconds *6606 .... \$ESP_OK 30 T I 5 1 Ethernet Disconnected *4B4F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - Control TCP Client Task communicate with Server

'T'	'T'	PL2	Control TCP Client Task communicate with Server	9
		'0'	T_Connect_to_Server	
		'1'	T_Check_Connected_to_Server	
		'2'	T_Send_String	
		'3'	T_Send_Binary	
		'4'	T_Available	
		'5'	T_Read_String	
		'6'	T_Read_Binary	
		'7'	T_Clear_Buffer	
		'8'	T_Diconnect_to_Server	



## HOST send Control T\_Connect\_to\_Server

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : T_Connect_to_Server		
	PL3	STRING	-	-	1	200	TCP IP address of Server	
	PL4	INTEGER	1	65354	-	-	TCP Port number of Server	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : T_Connect_to_Server		
	PL3	INTEGER	-1	2	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error: No WiFi/Ethernet connection	
							1 Error: TCP cannot connect to this IP	
							2 OK : TCP Connected success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :



HOST Send	\$ESP_OK 20 T T 0 google.com 80 *1D52
ACK Respond	\$ESP_OK 50 T T 0 2 TCP Connected , IP=google.com , Port = 80 *307D
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control T\_Check\_Connected\_to\_Server

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'	STRING	-	-	1	1	ID Control : T_Check_Connected_to_Server

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : T_Check_Connected_to_Server	
PL3	INTEGER	-1	1	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?
						0	TCP Client-No connection
						1	TCP Client- Connected
PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :



HOST Send	\$ESP_OK 6 T T 1 *6626
ACK Respond	\$ESP_OK 37 T T 1 1 TCP Client Connected success *074F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control T\_Send\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'2'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : T_Send_String		
	PL3	STRING	-	-	1	1500	Data send in string format	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : T_Send_String		
	PL3	INTEGER	-1	2	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error : Not connect to Server .	
							1 Error: Busy TX is sending	
							2 OK: Send String success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example



Message :	
HOST Send	\$ESP_OK 29 T T 2 GET / HTTP/1.1\r\n\r\n *4470
ACK Respond	\$ESP_OK 39 T T 2 2 TCP Client Send String success *7F08
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control T\_Send\_Binary

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'3'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : T_Send_Binary	
PL3	HEX	-	-	2	1400	Data send in string format	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'3'					ID Control : T_Send_Binary		
PL3	INTEGER	-1	2	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error : Not connect to Server .	
						1	Error: Busy TX is sending	
						2	OK: Send Binary success	
PL4	STRING	-	-	-	-	Describe status respond control as text		



### Example

Message :	
HOST Send	\$ESP_OK 43 T T 3 474554202f20485454502F312F310D0A0D0A *775C
ACK Respond	\$ESP_OK 39 T T 3 2 TCP Client Send Binary success *6418
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control T\_Available

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'4'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'4'	STRING	-	-	1	1	ID Control : T_Available	

### ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'4'					ID Control : T_Available		
	PL3	INTEGER	-1	1000	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?	
						[0,1000]	Size available RX buffer TCP	



### Example

Message :	
HOST Send	\$ESP_OK 6 T T 4 *6326
ACK Respond	\$ESP_OK 11 T T 4 5744 *2B5E
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control T\_Read\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'5'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'5'					ID Control : T_Read_String		
	PL3	INTEGER	1	1000	-	-	Size read buffer TCP	

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'5'					ID Control : T_Read_String		
	PL3	INTEGER	-1	1000	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?	
						[0,1000]	Size of string respond	
	PL4	STRING	-	-	0	1000	Data read buffer in String format	



### Example

Message :	
HOST Send	\$ESP_OK 9 T T 5 60 *1701
ACK Respond	\$ESP_OK 70 T T 5 60 abs: -1 Cache-Control: private, max-age=0 Content-Type: text *123A
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control T\_Read\_Binary

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'6'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'					ID Control : T_Read_Binary	
	PL3	INTEGER	1	1000	-	-	Size read buffer TCP

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'					ID Control : T_Read_Binary	
	PL3	INTEGER	-1	1000	-	-	Status Control
						-1	NACK: Invalid input /wrong format / out of range ...?
						[0,1000]	Size of string respond
	PL4	STRING	-	-	-	-	Data read buffer in HEX format



## Example

Message :	
HOST Send	\$ESP_OK 9 T T 6 60 *1402
ACK Respond	\$ESP_OK 130 T T 6 60  485454502F312E3120323030204F4B0D0A446174653A204D6F6E2C203230204A616E20323032 302031333A30373A313620474D540D0A457870697265 *685F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control T\_Clear\_Buffer

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'7'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'7'	STRING	-	-	1	1	ID Control : T_Clear_Buffer

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'7'					ID Control : T_Clear_Buffer	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 -
							1 Clear Buffer Success
	PL4	STRING	-	-	-	-	Describe status respond control as text



### Example

Message :	
HOST Send	\$ESP_OK 6 T T 7 *6026
ACK Respond	\$ESP_OK 40 T T 7 1 TCP Client Clear Buffer Success *273D
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control T\_Diconnect\_to\_Server

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'T'	'8'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'8'	STRING	-	-	1	1	ID Control : T_Diconnect_to_Server	

### ESPrk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'8'					ID Control : T_Diconnect_to_Server		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1		NACK: Invalid input /wrong format / out of range ...?
						0		-
						1	TCP Disconnected Success	
PL4	STRING	-	-	-	-	Describe status respond control as text		



## Example

Message :	
HOST Send	\$ESP_OK 6 T T 8 *6F26
ACK Respond	\$ESP_OK 25 T T 8 1 TCP Disconnected *2952
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Write Configure - Control Bluetooth Classic and Bluetooth BLE on ESPrtk

'T'	'B'	PL2	Control Bluetooth Classic and Bluetooth BLE on ESPrtk	8
		'0'	B_Start_Bluetooth	
		'1'	B_Check_Client_Connected	
		'2'	B_Send_String	
		'3'	B_Send_Binary	
		'4'	B_Available	
		'5'	B_Read_String	
		'6'	B_Read_Binary	
		'7'	B_Clear_Buffer	

### HOST send Control B\_Start\_Bluetooth

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'0'					ID Control : B_Start_Bluetooth	



	PL3	INTEGER	0	1	-	-	Type Bluetooth		
							0	Start Bluetooth Classic	
							1	Start Bluetooth Low Energy ( BLE )	
	PL4	STRING	-	-	1	100	Name of ESPrtk Bluetooth		

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : B_Start_Bluetooth		
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: Bluetooth start Failed
							1	OK : Bluetooth Started success
	PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :		
HOST Send	Start Bluetooth Classic	\$ESP_OK 22 T B 0 0 my_BLT_device *216B
	Start Bluetooth BLE	\$ESP_OK 22 T B 0 1 my_BLE_device *317A
ACK Respond	\$ESP_OK 62 T B 0 1 Bluetooth Classic Started success,Name: my_BLT_device *2525 \$ESP_OK 58 T B 0 1 Bluetooth BLE Started success,Name: my_BLE_device *320D	
NACK Respond		
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...	

## HOST send Control B\_Check\_Client\_Connected

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'1'	Infor 1	Infor 2	Infor 3	...



Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'	STRING	-	-	1	1	ID Control : B_Check_Client_Connected

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : B_Check_Client_Connected	
PL3	INTEGER	-1	1	-	-	Status Control	
						-1 NACK: Invalid input /wrong format / out of range ...?	
						0 No Bluetooth client connect to ESPrTk	
						1 Has Bluetooth client connected to ESPrTk	
PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :	
HOST Send	\$ESP_OK 6 T B 1 *7026
ACK Respond	\$ESP_OK 32 T B 1 0 Bluetooth-No connection *1B57 \$ESP_OK 36 T B 1 1 Bluetooth Connected success *1804
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control B\_Send\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'2'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'2'						ID Control : B_Send_String	
	PL3	STRING	-	-	1	1500	Data send in string format	

### ESPrtk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'2'						ID Control : B_Send_String	
	PL3	INTEGER	-1	2	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error : No Bluetooth client connect to ESPrkt or Bluetooth was not started yet.	
							1 Error: Busy TX is sending	
							2 OK: Send String success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 38 T B 2 Hello Bluetooth.\r\n I'm ESPrkt *1C44
ACK Respond	\$ESP_OK 38 T B 2 2 Bluetooth Send String success *604D
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control B\_Send\_Binary

<Header> + <Payload_length>	<Payload>					
	PL0	PL1	PL2	PL3	PL4	PL5 ...



\$ESP_OK xx	‘T’	‘B’	‘3’	Infor 1	Infor 2	Infor 3	...
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Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	‘3’					ID Control : B_Send_Binary	
	PL3	HEX	-	-	2	1400	Data send in string format

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	‘3’					ID Control : B_Send_Binary	
	PL3	INTEGER	-1	2	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error : No Bluetooth client connect to ESPrTk or Bluetooth was not started yet.
							1 Error: Busy TX is sending
							2 OK: Send Binary success
	PL4	STRING	-	-	-	-	Describe status respond control as text

### Example

Message :	
HOST Send	\$ESP_OK 67 T B 3 48656c6c6f20426c7565746f6f74682e0D0a49276d2045535072746b0D0a *6749
ACK Respond	\$ESP_OK 38 T B 3 2 Bluetooth Send Binary success *7B5C
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control B\_Available

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'4'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'	STRING	-	-	1	1	ID Control : B_Available

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'					ID Control : B_Available	
	PL3	INTEGER	-1	1000	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							[0,1000] Size available RX buffer Bluetooth

## Example

Message :	
HOST Send	\$ESP_OK 6 T B 4 *7526
ACK Respond	\$ESP_OK 9 T B 4 31 *0413
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control B\_Read\_String

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'5'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : B_Read_String	
	PL3	INTEGER	1	1000	-	-	Size read buffer Bluetooth

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : B_Read_String	
	PL3	INTEGER	-1	1000	-	-	Status Control
						-1	NACK: Invalid input /wrong format / out of range ...?
						[0,1000]	Size of string respond
	PL4	STRING	-	-	0	1000	Data read buffer in String format

## Example

Message :	
HOST Send	\$ESP_OK 10 T B 5 100 *0E3A
ACK Respond	\$ESP_OK 40 T B 5 31 Hi ESPrTk, Im mobile device.  *705B
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control B\_Read\_Binary

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'6'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'					ID Control : B_Read_Binary	
	PL3	INTEGER	1	1000	-	-	Size read buffer RX Bluetooth

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'					ID Control : B_Read_Binary	
	PL3	INTEGER	-1	1000	-	-	Status Control
						-1	NACK: Invalid input /wrong format / out of range ...?
						[0,1000]	Size of string respond
	PL4	STRING	-	-	-	-	Data read buffer in HEX format

## Example

Message :	
HOST Send	\$ESP_OK 10 T B 6 100 *0D3A
ACK Respond	\$ESP_OK 72 T B 6 31  48692045535072746B2C20496D206D6F62696C65206465766963652E200D0A *3D0C
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control B\_Clear\_Buffer

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'B'	'7'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'7'	STRING	-	-	1	1	ID Control : B_Clear_Buffer	

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'7'					ID Control : B_Clear_Buffer		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	-	
						1	Clear Buffer Success	
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 6 T B 7 *7626
ACK Respond	\$ESP_OK 39 T B 7 1 Bluetooth Clear Buffer Success *3767
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...





## Command Hardware Control – Control OLED Display (SSD1306/SH1106)

### HOST send Control OLED Display (SSD1306/SH1106)

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘O’	ID Control	Infor 1	Infor 2	Infor 3	...

‘T’	‘O’	PL2	Control OLED Display (SSD1306/SH1106)	12
	‘0’		O_Start_OLED	
	‘1’		O_Update_and_Display	
	‘2’		O_Clear_Display	
	‘3’		O_Draw_Dot	
	‘4’		O_Draw_Line	
	‘5’		O_Draw_Rect	
	‘6’		O_Draw_Rect_Corner	
	‘7’		O_Draw_Triangle	
	‘8’		O_Draw_Circle	
	‘9’		O_Draw_Elippse	
	‘A’		O_Draw_Character	
	‘B’		O_Draw_Number	

### HOST send Control O\_Start\_OLED

<Header> +	<Payload>
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<Payload_length>	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : O_Start_OLED		
PL3	INTEGER	0	1	-	-	Type OLED Display		
						0		OLED SH1106 128x64
						1		OLED SSD1306 128x64
PL4	INTEGER	1	255	-	-	Brightness		
PL5	INTEGER	1	255	-	-	Contrast		
PL6	INTEGER	0	1	-	-	Vertical Flip Screen		
						0		No
						1		Yes
PL7	INTEGER	0	1	-	-	Flag Auto Update Display without using \$ESP_OK 6 T O 1 *7D26 command (O_Update_and_Display)		
						0		No
						1		Yes

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'					ID Control : O_Start_OLED		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1		NACK: Invalid input /wrong format / out of range ...?
						0		Error : not found OLED Display on I2C port
						1		OK : Started OLED success



PL4	STRING	-	-	-	-	Describe status respond control as text	
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### Example

Message :	
HOST Send	\$ESP_OK 20 T O 0 1 250 250 0 0 *0509
ACK Respond	\$ESP_OK 101 T O 0 1 Start OLED Success, Type: SSD1306,Brightness = 250,Contrast = 250, Flip = 0 ,Auto Update = 0 *223C
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control O\_Update\_and\_Display

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'1'	STRING	-	-	1	1	ID Control : O_Update_and_Display	

### ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'1'					ID Control : O_Update_and_Display		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1		NACK: Invalid input /wrong format / out of range ...?
						0		Error: OLED Display was not started yet.
						1		OK: (OLED-Updated Success) Done
PL4	STRING	-	-	-	-	Describe status respond control as text		



### Example

Message :	
HOST Send	\$ESP_OK 6 T O 1 *7D26
ACK Respond	\$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control O\_Clear\_Display

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'2'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : O_Clear_Display		
	PL3	INTEGER	0	127	-	-	X Clear	
	PL4	INTEGER	0	63	-	-	Y Clear	
	PL5	INTEGER	0	128	-	-	Width Clear	pixel
	PL6	INTEGER	0	64	-	-	Height Clear	pixel
	PL7	INTEGER	0	1	-	-	Color clear	
						0	BLACK	
						1	WHITE	

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'2'						ID Control : O_Clear_Display	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: OLED Display was not started yet.
							1	OK: OLED-Clear) Done
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 19 T O 2 0 0 128 64 0 *3509 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 26 T O 2 1 (OLED-Clear) Done *0A5C \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control O\_Draw\_Dot

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'3'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'3'						ID Control : O_Draw_Dot	
	PL3	INTEGER	-32768	32767	-	-	X	
	PL4	INTEGER	-32768	32767	-	-	Y	
	PL5	INTEGER	0	1	-	-	Color Display	
						0	BLACK	



							1	WHITE	
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## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'3'					ID Control : O_Draw_Dot		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error: OLED Display was not started yet.	
						1	OK: Draw Dot done	
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 14 T O 3 64 32 1 *0271 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 29 T O 3 1 (OLED-Draw Dot) Done *0233 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control O\_Draw\_Line

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'4'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'						ID Control : O_Draw_Line	
	PL3	INTEGER	-32768	32767	-	-	XA	
	PL4	INTEGER	-32768	32767	-	-	YA	
	PL5	INTEGER	-32768	32767	-	-	XB	
	PL6	INTEGER	-32768	32767	-	-	YB	
	PL7	INTEGER	0	1	-	-	Color Display	
							0 BLACK	
							1 WHITE	

### ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'						ID Control : O_Draw_Line	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error: OLED Display was not started yet.	
							1 OK: Draw Line Done	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 18 T O 4 5 5 32 20 1 *0976 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 30 T O 4 1 (OLED-Draw Line) Done *7C77 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	



Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...
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## HOST send Control O\_Draw\_Rect

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'5'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'5'					ID Control : O_Draw_Rect		
	PL3	INTEGER	-32768	32767	-	-	X	
	PL4	INTEGER	-32768	32767	-	-	Y	
	PL5	INTEGER	-32768	32767	-	-	Width Rect	pixel
	PL6	INTEGER	-32768	32767	-	-	Height Rect	pixel
	PL7	INTEGER	0	1	-	-	Color Display	
						0	BLACK	
						1	WHITE	
	PL8	INTEGER	0	1	-	-	Fill object draw	
						0	No	
						1	Yes	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'5'					ID Control : O_Draw_Rect		
	PL3	INTEGER	-1	1	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error: OLED Display was not started yet.	
						1	OK: Draw Rectangle Done	



PL4	STRING	-	-	-	-	Describe status respond control as text	
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### Example

Message :	
HOST Send	\$ESP_OK 22 T O 5 50 20 40 20 1 0 *4F75 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 35 T O 5 1 (OLED-Draw Rectangle) Done *1745 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control O\_Draw\_Rect\_Corner

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'6'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'6'					ID Control : O_Draw_Rect_Corner	
PL3	INTEGER	-32768	32767	-	-	X	
PL4	INTEGER	-32768	32767	-	-	Y	
PL5	INTEGER	-32768	32767	-	-	Width Rectangle Corner	pixel
PL6	INTEGER	-32768	32767	-	-	Height Rectangle Corner	pixel
PL7	INTEGER	-32768	32767	-	-	Radius Corner	
PL8	INTEGER	0	1	-	-	Color Display	
						0	BLACK
						1	WHITE
PL9	INTEGER	0	1	-	-	Fill object draw	



							0	No	
							1	Yes	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'6'					ID Control : O_Draw_Rect_Corner		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error: OLED Display was not started yet.	
						1	OK: Draw Rectangle Corner Done	
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 24 T O 6 12 20 40 20 5 1 0 *050B \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 42 T O 6 1 (OLED-Draw Rectangle Corner) Done *1354 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control O\_Draw\_Triangle

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'7'	Infor 1	Infor 2	Infor 3	...



Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'7'					ID Control : O_Draw_Triangle		
PL3	INTEGER	-32768	32767	-	-	XA		
PL4	INTEGER	-32768	32767	-	-	YA		
PL5	INTEGER	-32768	32767	-	-	XB		
PL6	INTEGER	-32768	32767	-	-	YB		
PL7	INTEGER	-32768	32767	-	-	XC		
PL8	INTEGER	-32768	32767	-	-	YC		
PL9	INTEGER	0	1	-	-	Color Display		
						0		BLACK
						1		WHITE
PL10	INTEGER	0	1	-	-	Fill object draw		
						0		No
						1		Yes

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'7'					ID Control : O_Draw_Triangle		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1		NACK: Invalid input /wrong format / out of range ...?
						0		Error: OLED Display was not started yet.
						1		OK: Draw Triangle Done
PL4	STRING	-	-	-	-	Describe status respond control as text		

### Example

Message :	
HOST Send	\$ESP_OK 28 T O 7 10 10 40 10 25 30 1 0 *470F



	\$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 34 T O 7 1 (OLED-Draw Triangle) Done *7B6A \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control O\_Draw\_Circle

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'8'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'8'					ID Control : O_Draw_Circle		
PL3	INTEGER	-32768	32767	-	-	X Center circle		
PL4	INTEGER	-32768	32767	-	-	Y Center circle		
PL5	INTEGER	-32768	32767	-	-	Circle radius	pixel	
PL6	INTEGER	0	1	-	-	Color Display		
						0		BLACK
						1		WHITE
PL	INTEGER	0	1	-	-	Fill object draw		
						0		No
						1		Yes

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'8'						ID Control : O_Draw_Circle	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: OLED Display was not started yet.
							1	OK: Draw Circle Done
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 19 T O 8 64 32 20 1 0 *360A \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 32 T O 8 1 (OLED-Draw Circle) Done *6E08 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control O\_Draw\_Elipse

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'9'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'9'						ID Control : O_Draw_Elipse	
	PL3	INTEGER	-32768	32767	-	-	X Elipse's Center	
	PL4	INTEGER	-32768	32767	-	-	Y Elipse's Center	
	PL5	INTEGER	-32768	32767	-	-	Width Radius	pixel
	PL6	INTEGER	-32768	32767	-	-	Height Radius	pixel



	PL7	INTEGER	0	1	-	-	Color Display		
							0	BLACK	
							1	WHITE	
	PL8	INTEGER	0	1	-	-	Fill object draw		
							0	No	
							1	Yes	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'9'					ID Control : O_Draw_Elippse		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1		NACK: Invalid input /wrong format / out of range ...?
						0		Error: OLED Display was not started yet.
						1		OK: Draw Done
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 22 T O 9 64 32 40 20 1 0 *4770 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 33 T O 9 1 (OLED-Draw Elippse) Done *0A33 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control O\_Draw\_Character

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'A'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit		
PL2	'A'					ID Control : O_Draw_Character			
	PL3	INTEGER	-32768	32767	-	-	X String		
	PL4	INTEGER	-32768	32767	-	-	Y String		
	PL5	INTEGER	0	1	-	-	Color Display		
							0	BLACK	
							1	WHITE	
	PL6	STRING	-	-	1	1000	Data draw as text string format		

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit		
PL2	'A'					ID Control : O_Draw_Character			
	PL3	INTEGER	-1	1	-	-	Status Control		
							-1	NACK: Invalid input /wrong format / out of range ...?	
							0	Error: OLED Display was not started yet.	
							1	OK: Draw Char Done	
	PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :



HOST Send	\$ESP_OK 59 T O A 80 2 1 Hello\nESPrtk\nOLED\nTest\nDraw\nString\nDone *5478 \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 30 T O A 1 (OLED-Draw Char) Done *1F77 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control O\_Draw\_Number

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'O'	'B'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'B'					ID Control : O_Draw_Number		
PL3	INTEGER	-32768	32767	-	-	X		
PL4	INTEGER	-32768	32767	-	-	Y		
PL5	INTEGER	0	2	-	-	Font text draw number string		
						0	ASCII_5x7	
						1	CASIO_12x16	
PL6	INTEGER	0	1	-	-	Color Display		
						0	BLACK	
						1	WHITE	
PL7	STRING	-	-	-	-	Data draw as text number format		

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'B'						ID Control : O_Draw_Number	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: OLED Display was not started yet.
							1	OK: Draw Done
PL4	STRING	-	-	-	-	Describe status respond control as text		

### Example

Message :	
HOST Send	\$ESP_OK 18 T O B 5 2 0 1 123 *7B38 \$ESP_OK 20 T O B 5 12 1 1 -2.3 *7244 \$ESP_OK 19 T O B 5 32 2 1 0.3 *566E \$ESP_OK 6 T O 1 *7D26 ( need add this command to update display if Flag Auto Update Display is turn off )
ACK Respond	\$ESP_OK 32 T O B 1 (OLED-Draw Number) Done *0513 \$ESP_OK 27 T O 1 1 (OLED-Update) Done *6010
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Hardware Control – SD Card

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	ID Control	Infor 1	Infor 2	Infor 3	...

'T'	'S'	PL2	Control SD Card	10
		'0'	S_Start_SD_Card	
		'1'	S_Check_Folder_Exist	
		'2'	S_Create_Folder	
		'3'	S_Delete_File	
		'4'	S_Rename_File	
		'5'	S_Check_File_Exist	
		'6'	S_Create_File	
		'7'	S_Get_Size_File	
		'8'	S_Read_Binary_data_File	
		'9'	S_Append_Binary_data_to_File	

## HOST send Control S\_Start\_SD\_Card

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'0'	Infor 1	Infor 2	Infor 3	...



Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'0'	STRING	-	-	1	1	ID Control : S_Start_SD_Card	

### ESPrTk Respond

Payload Index		Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'0'						ID Control : S_Start_SD_Card	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error : Card Mount Failed / Not found SD Card on SPI port	
							1 OK : Start SD Card success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 6 T S 0 *6026
ACK Respond	\$ESP_OK 67 T S 0 1 Start SD Card Success , Card type:SD , Card size: 1802 MB  *485A
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control S\_Check\_Folder\_Exist

<Header> +	<Payload>
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<Payload_length>	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : S_Check_Folder_Exist	
	PL3	STRING	-	-	1	1500	Path Folder

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : S_Check_Folder_Exist	
	PL3	INTEGER	-1	1	-	-	Status Control
						-1	NACK: Invalid input /wrong format / out of range ...?
						0	OK: Not exist (Not found this folder)
						1	OK: Existed
	PL4	STRING	-	-	-	-	Describe status respond control as text

### Example

Message :	
HOST Send	\$ESP_OK 15 T S 1 /my_test *5D08
ACK Respond	\$ESP_OK 16 T S 1 1 Existed *3318
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control S\_Create\_Folder



<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'2'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : S_Create_Folder		
	PL3	STRING	-	-	3	1500	Path of folder	

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : S_Create_Folder		
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1 NACK: Invalid input /wrong format / out of range ...?	
							0 Error : Create Folder failed	
							1 OK: Create Folder Success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 15 T S 2 /my_test *5E0B
ACK Respond	\$ESP_OK 30 T S 2 1 Create Folder Success *3708
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control S\_Delete\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'3'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : S_Delete_File	
	PL3	STRING	-	-	3	1500	Path of file

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : S_Delete_File	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error : Error: Delete File failed
							1 OK : Delete File Success
	PL4	STRING	-	-	-	-	Describe status respond control as text

## Example

Message :	
HOST Send	\$ESP_OK 21 T S 3 /my_test/i.txt *4877
ACK Respond	\$ESP_OK 28 T S 3 1 Delete File Success *327F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send Control S\_Rename\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'4'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'4'					ID Control : S_Rename_File		
	PL3	STRING	-	-	2	1500	Path file A	
	PL4	STRING	-	-	2	1500	Path file B	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'4'					ID Control : S_Rename_File		
	PL3	INTEGER	-1	1	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error : Rename failed	
						1	OK : File renamed success	
	PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :



HOST Send	Rename file i.txt to j.txt \$ESP_OK 36 T S 4 my_test/i.txt/my_test/j.txt *546A
ACK Respond	\$ESP_OK 29 T S 4 1 File renamed success *594F
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control S\_Check\_File\_Exist

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'5'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : S_Check_File_Exist	
	PL3	STRING	-	-	1	1500	Path of file

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'5'					ID Control : S_Check_File_Exist	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 Error : File path invalid or file not exist
							0 Error : Not exist - File not found
							1 OK: File Existed
	PL4	STRING	-	-	-	-	Describe status respond control as text

## Example



Message :	
HOST Send	\$ESP_OK 21 T S 5 /my_test/i.txt *4E71
ACK Respond	\$ESP_OK 16 T S 5 1 Existed *3718
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control S\_Create\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'6'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'6'					ID Control : S_Create_File		
	PL3	STRING	-	-	1	1500	Path of file create	

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'6'					ID Control : S_Create_File		
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: Create File failed
							1	OK: Create File Success
	PL4	STRING	-	-	-	-		Describe status respond control as text



### Example

Message :	
HOST Send	\$ESP_OK 21 T S 6 my_test/i.txt *4D72
ACK Respond	\$ESP_OK 28 T S 6 1 Create File Success *2A6C
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control S\_Get\_Size\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'7'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'7'					ID Control : S_Get_Size_File	
	PL3	STRING	-	-	1	1500	Path of

### ESPrk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'7'					ID Control : S_Get_Size_File		
	PL3	INTEGER	-1	1	-	-	Status Control	
					-1		NACK: Invalid input /wrong format / out of range ...?	
					0		Error : Failed open file for read size	
					1		OK	
	PL4	INTEGER	0	10000000000	-	-	Size of file	byte



## Example

Message :	
HOST Send	\$ESP_OK 21 T S 7 /my_test/i.txt *4C73
ACK Respond	\$ESP_OK 12 T S 7 1 241 *5442
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Control S\_Read\_Binary\_data\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'S'	'8'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'8'					ID Control : S_Read_Binary_data_File		
	PL3	STRING	-	-	1	1500	Path of file	
	PL4	INTEGER	0	10000000000	-	-	Offset index start read file	
	PL5	INTEGER	1	1000	-	-	Size read	byte

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value			Describe	Unit	
PL2	'8'					ID Control : S_Read_Binary_data_File		
	PL3	INTEGER	-1	1000	-	-	Status Control	
						-1	NACK: Invalid input /wrong format / out of range ...?	



						[0,1000]	Size of data read respond	
	PL4	STRING	-	-	-	-	Data read in HEX format	

### Example

Message :	
HOST Send	\$ESP_OK 27 T S 8 /my_test/i.txt 0 500 *404A
ACK Respond	\$ESP_OK 493 T S 8 241  45535072746B2056657273696F6E3A20322E372E39202E0D0A45535072746B2049443A2038313 930395F4748423941202E0D0A5265636F726420696E20616374696F6E2061733A2055415254204 36F6E666967757265202D3E2048617264577761726520436F6E74726F6C202D3E2053442043617 264202E0D0A436F6E7461637420537570706F72743A20687474703A2F2F65737072746B2E776F 726470726573732E636F6D202C20456D61696C203A65737072746B40676D61696C2E636F6D20 2C20544D3A207068756E6774686169736F6E393640676D61696C2E636F6D202E0D0A48656C6 C6F2045535072746B0D0A *5835
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

### HOST send Control S\_Append\_Binary\_data\_to\_File

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘S’	‘9’	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	‘9’					ID Control : S_Append_Binary_data_to_File		
	PL3	STRING	-	-	1	1500	Path of file	
	PL4	HEX	-	-	1	1400	Append data to file in HEX format	

### ESPrtk Respond

Payload	Type value	Min	Max	Min	Max	Describe	Unit
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Index		Value	Value	Length	Length		
PL2	'9'					ID Control : S_Append_Binary_data_to_File	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error : Failed open file for append data
							1 OK : Append Data success
	PL4	STRING	-	-	-	-	Describe status respond control as text

### Example

Message :	
HOST Send	\$ESP_OK 50 T S 9 /my_test/i.txt 48656C6C6F2045535072746B0D0A *3040
ACK Respond	\$ESP_OK 33 T S 9 1 File Append Data success *1568
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Hardware Control – IMU (MPU9250)

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘M’	ID Control	Infor 1	Infor 2	Infor 3	...

‘T’	‘M’	PL2	Control IMU (MPU9250)	5
		‘0’	M_Start_Print_IMU_Data	
		‘1’	M_Stop_Print_IMU_Data	
		‘2’	M_Start_IMU_Calibrate	
		‘3’	M_Stop_IMU_Calibrate	
		‘4’	M_Save_Calibrate_Result	
			Disable/Enable type print IMU	

### HOST send M\_Start\_Print\_IMU\_Data

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘M’	‘0’	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'0'						ID Control :M_Start_Print_IMU_Data	
	PL3	INTEGER	0	9	-	-	Type frequency update IMU	
							0	2 Hz
							1	10 Hz
							2	15 Hz
							3	20 Hz
							4	25 Hz
							5	35 Hz
							6	50 Hz
							7	100 Hz
							8	150 Hz
							9	200 Hz

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'0'						ID Control : M_Start_Print_IMU_Data	
	PL3	INTEGER	-1	1	-	-	Status Control	
							-1	NACK: Invalid input /wrong format / out of range ...?
							0	Error: Not found data configure for MPU9250 in Profile
							1	OK: Is starting connect to IMU and print IMU data
	PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
HOST Send	\$ESP_OK 8 T M 0 1 *3D5A
ACK Respond	..... \$ESP_OK 64 T M 0 1 Is starting print IMU data , Type Frequency update = 1  *1C0E .....



	\$ESPIM1 81 82.32 199.63 172.13 -2.40 -7.20 -50.41 0.54 -0.52 -0.57 29.17 -2.40 -7.20 -50.41 *186D \$ESPIM2 82 0.35 -0.25 -0.88 0.20 136.90 -141.23 -31.31 21.44     139.56 -141.49 -30.51 22.45 *750C \$ESPIM1 84 178.90 116.04 202.62 17.55 -21.91 -30.16 0.57 -0.76 -0.12 29.16 17.55 -21.91 -30.16  *2071 \$ESPIM2 82 0.57 -0.51 -0.57 0.30 79.64 -100.98 -20.24 334.15     83.66 -106.79 -20.59 315.65 *7D05 \$ESPIM1 82 117.38 127.38 185.91 37.51 -10.50 -8.85 -0.09 -0.79 0.14 29.16 37.51 -10.50 -8.85  *2211 \$ESPIM2 77 0.66 -0.60 -0.20 0.40 51.81 -78.48 12.85 316.72     52.77 -79.97 6.36 316.71 *4774 .....
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send M\_Stop\_Print\_IMU\_Data

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'M'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'	STRING	-	-	1	1	ID Control : M_Stop_Print_IMU_Data

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : M_Stop_Print_IMU_Data	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 Error:
							1 OK: Stopped Print IMU data



PL4	STRING	-	-	-	-	Describe status respond control as text	
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### Example

Message :	
HOST Send	\$ESP_OK 6 T M 1 *7F26
ACK Respond	\$ESP_OK 31 T M 1 1 Stopped Print IMU data *031B
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send Disable/Enable type print IMU

Please see “Control Enable Type Print on TX\_UART0” → PL3 → BIT11 and BIT12.

Example:

```

$ESP_OK|19|T|P|0|000000000000|*2157 -> Disable Print ALL output UART_0
$ESP_OK|19|T|P|0|11111111100|*2156 -> Disable Print IMU 1 + IMU2
$ESP_OK|19|T|P|0|11111111110|*2057 -> Disable Print IMU 1 , Enable Print IMU2
$ESP_OK|19|T|P|0|11111111101|*2056 -> Enable Print IMU1 , Disable Print IMU 2
$ESP_OK|19|T|P|0|11111111111|*2157 -> Enable Print ALL output UART_0
  
```

## HOST send M\_Start\_IMU\_Calibrate

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	‘T’	‘M’	‘2’	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
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PL2	'2'	STRING	-	-	1	1	ID Control : M_Start_IMU_Calibrate	
-----	-----	--------	---	---	---	---	------------------------------------	--

### ESPrk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'2'					ID Control : M_Start_IMU_Calibrate		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	<b>Error:</b> Not found data configure for MPU9250 in Profile	
						1	OK: Is starting connect to IMU and print IMU data	
						2	<b>Error</b> : Low memory - Fail to malloc new buffer !	
PL4	STRING	-	-	-	-	Describe status respond control as text		

### Example

#### Message :

HOST Send	\$ESP_OK 6 T M 2 *7C26
ACK Respond	\$ESP_OK 30 T M 2 1 Started IMU Calibrate *2F54
Data Respond	\$ESPLOG 59 2 INFO CAL Please rotate the sensor to the different angle *6224 \$ESPLOG 59 2 INFO CAL Please rotate the sensor to the different angle *6224 \$ESPLOG 74 2 INFO CAL Surface scan (0.00 %),Input [-4.2010503,4.0510130,-69.0172577] *6C01 \$ESPLOG 74 2 INFO CAL Surface scan (0.01 %),Input [-4.2010503,4.0510130,-69.0172577] *6D01 \$ESPLOG 74 2 INFO CAL Surface scan (0.02 %),Input [-9.7524385,5.1012754,-67.9669952] *6E07 \$ESPLOG 75 2 INFO CAL Surface scan (0.03 %),Input [-17.5543880,5.8514628,-67.9669952] *5C76 \$ESPLOG 75 2 INFO CAL Surface scan (0.04 %),Input [-24.4561138,5.8514628,-62.7156792] *5276 \$ESPLOG 75 2 INFO CAL Surface scan (0.05 %),Input [-31.9579887,6.7516880,-58.0645180] *527A ..... .....
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## HOST send M\_Stop\_IMU\_Calibrate

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'M'	'3'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'3'	STRING	-	-	1	1	ID Control : M_Stop_IMU_Calibrate	

## ESPrtk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'3'					ID Control : M_Stop_IMU_Calibrate	
PL3	INTEGER	-1	1	-	-	Status Control	
						-1 NACK: Invalid input /wrong format / out of range ...?	
						0 Is calculating ... , please wait.	
						1 <b>OK</b> : Stopped IMU Calibrate. ( Success )	
						2 <b>Error</b> : Incomplete samples (We need more samples to be able to calibrate!	
						3 <b>Error</b> : Incomplete samples ( We need more samples on the X and Y axes by rotating the sensor around the Z axis!)	
						4 <b>Error</b> : Fail to calculating , please try again !	
PL4	STRING	-	-	-	-	Describe status respond control as text	

## Example

Message :



HOST Send	\$ESP_OK 6 T M 3 *7D26
ACK Respond	<p>\$ESP_OK 41 T M 3 0 Is calculating ... , please wait *0214</p> <p>.... (Calibrate progress )...</p> <p>.... (Noise filter progress )...</p> <p>.... (Printout data calibrated progress )...</p> <p>.... (Printout Bias+Rotations matrices )...</p> <p>\$ESP_OK 30 T M 3 1 Stopped IMU Calibrate *2656</p>
Data Respond	<p>\$ESP_OK 41 T M 3 0 Is calculating ... , please wait *0214</p> <p>.....</p> <p>.....</p> <p>\$ESPLOG 27 2 INFO CAL Calibrating:1 % *396B</p> <p>\$ESPLOG 27 2 INFO CAL Calibrating:2 % *3A6B</p> <p>\$ESPLOG 27 2 INFO CAL Calibrating:3 % *3B6B</p> <p>.....</p> <p>\$ESPLOG 28 2 INFO CAL Calibrating:90 % *0E23</p> <p>\$ESPLOG 28 2 INFO CAL Calibrating:95 % *0B23</p> <p>\$ESPLOG 29 2 INFO CAL Calibrating:100 % *3755</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>\$ESPLOG 28 2 INFO CAL Noise filter:0 % *0B2F</p> <p>\$ESPLOG 28 2 INFO CAL Noise filter:3 % *082F</p> <p>\$ESPLOG 28 2 INFO CAL Noise filter:6 % *0D2F</p> <p>.....</p> <p>\$ESPLOG 29 2 INFO CAL Noise filter:90 % *3355</p> <p>\$ESPLOG 29 2 INFO CAL Noise filter:93 % *3055</p> <p>\$ESPLOG 29 2 INFO CAL Noise filter:96 % *3555</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>\$ESPLOG 69 2 INFO CAL Count (1/617),Output [-24.6396484,26.2568359,-19.2402344] *112C</p> <p>\$ESPLOG 69 2 INFO CAL Count (2/617),Output [-24.6396484,26.2568359,-19.2402344] *122F</p> <p>\$ESPLOG 69 2 INFO CAL Count (3/617),Output [-22.3652344,25.3867188,-21.1152344] *102C</p> <p>.....</p> <p>\$ESPLOG 70 2 INFO CAL Count (615/617),Output [12.0615234,22.5830078,-25.9902344] *3D36</p> <p>\$ESPLOG 70 2 INFO CAL Count (616/617),Output [14.1621094,25.6347656,-25.7070312] *323C</p> <p>\$ESPLOG 70 2 INFO CAL Count (617/617),Output [12.6474609,24.3251953,-24.7656250] *3E3D</p> <p>.....</p> <p>.....</p> <p>.....</p> <p>\$ESPLOG 205 2 INFO CAL Success ! Bias 1x3 [ -11.4422918 , -23.6864032 , -40.1461467 ] ,Rotation 3x3 [ 1.0044592 , -0.0014763 , -0.0122153 , -0.0014784 , 0.9697963 , -0.0028070 , -0.0122177 , -</p>



	0.0028135 , 1.0257844 ]  *1007 ..... ..... ..... \$ESP_OK 30 T M 3 1 Stopped IMU Calibrate *2656
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send M\_Save\_Calibrate\_Result

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'M'	'4'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'	STRING	-	-	1	1	ID Control : M_Save_Calibrate_Result

## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'4'					ID Control : M_Save_Calibrate_Result	
	PL3	INTEGER	-1	1	-	-	Status Control
							-1 NACK: Invalid input /wrong format / out of range ...?
							0 <b>Error:</b>
							1 OK: Updated Calibrate Result
	PL4	STRING	-	-	-	-	Describe status respond control as text



### Example

**Message :**

HOST Send	\$ESP_OK 6 T M 4 *7A26
ACK Respond	\$ESP_OK 33 T M 4 1 Updated Calibrate Result *4650
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## Command Hardware Control – Deep Sleep

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'V'	ID Control	Infor 1	Infor 2	Infor 3	...

'T'	'V'	PL2	Control Deep Sleep	2
		'0'	V_Enter_Deep_Sleep_mode	
		'1'	V_Exit_Deep_Sleep_mode_and_WakeUp	

### HOST send V\_Enter\_Deep\_Sleep\_mode

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'V'	'0'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'	STRING	-	-	1	1	ID Control : V_Enter_Deep_Sleep_mode
PL3		STRING	0	1	1	0	Only ESPrtk (ESP32) enter Deep Sleep mode .
						1	ESPrtk (ESP32) and all other modules connect to ESPrtk will enter Deep Sleep mode .



## ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit	
PL2	'1'					ID Control : V_Enter_Deep_Sleep_mode		
PL3	INTEGER	-1	1	-	-	Status Control		
						-1	NACK: Invalid input /wrong format / out of range ...?	
						0	Error:	
						1	OK: Enter Deep Sleep mode success	
PL4	STRING	-	-	-	-	Describe status respond control as text		

## Example

Message :	
HOST Send	\$ESP_OK 8 T V 0 1 *265A
ACK Respond	\$ESP_OK 38 T V 0 1 Enter Deep Sleep mode success *3A40
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...

## HOST send V\_Exit\_Deep\_Sleep\_mode\_and\_WakeUp

<Header> + <Payload_length>	<Payload>						
	PL0	PL1	PL2	PL3	PL4	PL5	...
\$ESP_OK xx	'T'	'V'	'1'	Infor 1	Infor 2	Infor 3	...

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
---------------	------------	-----------	-----------	------------	------------	----------	------



PL2	'1'	STRING	-	-	1	1	ID Control : V_Exit_Deep_Sleep_mode_and_WakeUp
-----	-----	--------	---	---	---	---	---

### ESPrTk Respond

Payload Index	Type value	Min Value	Max Value	Min Length	Max Length	Describe	Unit
PL2	'1'					ID Control : V_Exit_Deep_Sleep_mode_and_WakeUp	
PL3	INTEGER	-1	1	-	-	Status Control	
						-1 NACK: Invalid input /wrong format / out of range ...?	
						0 - Timeout : Not see confirm message from HOST	
						1 OK: Exit Deep Sleep mode and WakeUp success	
PL4	STRING	-	-	-	-	Describe status respond control as text	

### Example

Message :	
#1 HOST Send	\$ESP_OK 6 T V 1 *6426
#1 ACK Respond	Please send \$ESP_OK 6 T V 1 *6426 again to confirm wake up !
#2 HOST Send again to confirm wake up	\$ESP_OK 6 T V 1 *6426
#2 ACK Respond	\$ESP_OK 49 T V 0 1 Exit Deep Sleep mode and wake up success *026C
NACK Respond	
Other NACK	\$ESP_ER ... or \$ESS_ER ... or \$AES_ER ...



## WEB Configure mode

Besides using UART\_Configure to configure ESPrtk.

Users can perform ESPrtk configuration through a WEB interface (UI) with a web browser running on a computer or mobile device.

### Start WEB Configure mode.

There are two ways to start WEB Configure mode on ESPrtk.

- Use ESPrtk command control
- Use the CWB button

### Use ESPrtk command to start WEB configure

Use ESPrtk command control	
Step 0	ESPrtk after supplying power.
Step 2	HOST send command : <b>\$ESP_OK 5 N _  *451F</b>
Done	ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0: <b>\$ESP_OK 5 N _  *451F</b>

### Use the CWB button to start WEB configure

Method 1: Use a combination of RESTART and CWB buttons.	
Step 0	ESPrtk after supplying power.
Step 1	Press and hold the CWB button. ( set GPIO to Low level)
Step 2	Press the RESET button ( then release)
Done	Continue to hold CWB in 0.5 second -> ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously . ESPrtk respond on TX_UART0 : <b>\$ESP_OK 5 N _  *451F</b>
Method 2: Use only the CWB button	
Step 0	ESPrtk after supplying power.
Done	Press and hold the CWB button ( set GPIO to Low level) for 3 seconds -> ESPrtk will start go to WEB Configure mode. The CONNECT_LED blink fast.
Success	The CONNECT_LED will light continuously .



ESPrtk respond on TX\_UART0: **\$ESP\_OK|5|N|\_|\*451F**

**TIP :**

After ESPrtk enters WEB Configure mode successfully, pressing the CWB button will not work in this mode.

When using the CWB button to launch WEB Configure, both ways you need to hold it down, so if pressing and holding the button makes it difficult for you, you may need to use a switch (parallel connection with the CWB button).

## Access WEB UI and use

Now ESPrtk will start the WiFi hotspot (**AccessPoint**) named: **ESPrtk : xxxxx**. With xxxxx is the ID of ESPrtk device. (ESPrtk\_ID).

When the boot process is complete, the connected CONNECT\_LED will light continuously.

You can now connect to the WiFi hotspot , because the station is public (open) so you can connect without a password.

After connecting, open any browser on your device, and access **<http://192.168.4.1/profile>** to enter **Profile** page.

At the profile page, click on the “Login/Logout” tab, enter your username and password and then click “Login”.

On ESPrtk 3.0.0 , the default username/password is **admin** and **abc123ABC**

If ESPrtk does not have an account yet, click on “**Create new profile**” with your username/password chosen by user.

	Tab	Access address
1	Homepage	<a href="http://192.168.4.1">http://192.168.4.1</a>
2	Ublox Tab	<a href="http://192.168.4.1/ublox">http://192.168.4.1/ublox</a>
3	Navspark Tab	<a href="http://192.168.4.1/navspark">http://192.168.4.1/navspark</a>
4	GNSS Viewer Tab	<a href="http://192.168.4.1/gnssviewer">http://192.168.4.1/gnssviewer</a>
5	Profile Tab	<a href="http://192.168.4.1/profile">http://192.168.4.1/profile</a>
6	About Tab	<a href="http://192.168.4.1/about">http://192.168.4.1/about</a>
7	System Tab	<a href="http://192.168.4.1/system">http://192.168.4.1/system</a>

## Homepage

### Introduce

WEB Configure homepage.

Click on the middle of the screen to go to the Profile configuration page.



## Ublox Tab

### Introduce

This function allows users to configure Ublox module in the same way as Ublox Center software. Just connect the UART1 port (ESPrtk) to the UART-Configure (Ublox module), select the appropriate baudrate and start the configuration.

This function uses the latest Ublox Center API and protocol and supports configuration on all of Ublox’s latest product lines such as F9P-M8P-LEA -NEO.

### Hardware connect

Type	ESPrtk pin name	ZED-F9P	M8P – LEA -NEO	Other Ublox modules
UART	TX_UART1	RX_UART_1	RX_UART_1	RX UART-config
UART	RX_UART1	TX_UART_1	TX_UART_1	TX UART-config
UART	TX_UART2	RX_UART_2		RX UART-config
UART	RX_UART2	TX_UART_2		TX UART-config

### Support function

Communicate	Support
UART1 / UART2 Switch + Multi baudrate + Auto scan baudrate Ublox device	●
Automatically detect errors of input data.	●

	Ublox Configure function	Support
0	ANT (Antenna Settings)	●
1	BATCH (Batch mode output)	●
2	CFG (Configuration)	●
3	DAT (Datum)	●
4	DGNNS (Differential GNSS configure)	●
5	DOSC (Disciplined Oscillator)	●
6	EKF (EKF Settings)	○
7	ESFGWT (Gyro + Wheeltick)	○
8	ESRC (External Source Config)	●



9	<b>FXN (Fix Now Mode)</b>	○
10	<b>GEOFENCE (Geofence Config)</b>	●
11	<b>GNSS (GNSS Config)</b>	●
12	<b>HNR (High Nav Rate)</b>	●
13	<b>INF (Inf Message)</b>	●
14	<b>ITFM (Jamming/Interference Monitor)</b>	●
15	<b>LOGFIL (Log Settings)</b>	●
16	<b>MSG (Messages)</b>	●
17	<b>NAV5 (Navigation 5)</b>	●
18	<b>NAVX5 (Navigation Expert 5)</b>	●
19	<b>NMEA (NMEA Protocol)</b>	●
20	<b>ODO (Odometer/Low-Speed COG filter)</b>	●
21	<b>PM (Power Management)</b>	○
22	<b>PM2 (Extended Power Management)</b>	●
23	<b>PMS (Power Management Setup)</b>	●
24	<b>PRT (Ports)</b>	●
25	<b>PWR (Power)</b>	●
26	<b>RATE (Rates)</b>	●
27	<b>RINV (Remote Inventory)</b>	●
28	<b>RST (Reset)</b>	●
29	<b>RXM (Receiver Manager)</b>	●
30	<b>SBAS (SBAS Settings)</b>	●
31	<b>SLAS (SLAS Settings)</b>	●
32	<b>SMGR (Sync Manager Config)</b>	●
33	<b>TMODE (Time Mode)</b>	○
34	<b>TMODE2 (Time Mode2)</b>	●
35	<b>TMODE3 (Time Mode 3)</b>	●
36	<b>TP (Timepulse)</b>	●
37	<b>TP5 (Timepulse 5)</b>	●
38	<b>TXSLOT (Tx Time Slots)</b>	●
39	<b>USB (Universal Serial Bus)</b>	●
40	<b>VALDEL (New Configuration)</b>	○
41	<b>VALGET (New Configuration)</b>	○
42	<b>VALSET (New Configuration)</b>	○



43	ESPrtk - Hex configure Ublox tool	●
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## To use

Connect UART port as table above.

- 1- First, start connecting to the module with a baudrate.
- 2-Use "Autoscan Baudrate" to scan if dont know baudrate.
- 3-Select configure function , select yourconfigure item , press SEND configure .

### TIP :

- Wait a moment after changing the baudrate.
- Do not click too quickly (after configure, you need wait a moment).
- Items marked with '\*' are not supported yet.
- Scroll the Configure tab to see the full component.

## ESPrtk - Hex configure Ublox tool

This function allows users to configure Ublox modules with Hex code.

(These codes are the PAYLOAD part in the communication frame to configure Ublox's module, can find the communication frame at the configuration documents).

ESPrtk also supports syntax errors filter , error alerts, data dumps, auto-sending ...

The input field has the format:

Input field format
<b>&lt;Configuration Name&gt; – &lt;Hex code&gt; &lt;Enter&gt;</b>

For example:

CFG-MSG – 06 01 08 00 0A 06 00 00 00 00 00 00
CFG-MSG – 06 01 08 00 0A 07 00 00 00 00 00 00
CFG-MSG – 06 01 08 00 0A 21 00 00 00 00 00 00

Check input:



- Configuration name and Hex code are separated by dashes: ‘-‘.
- Each hex value must be separated by a space.
- The configuration commands must be separated by new lines (enter).
- A Byte Hex must contain at least 1 characters (and no more than 2 characters).
- Irrespective of uppercase and lowercase letters.

For example, all four ways below are valid and have the same output:

- Hex 1 = 01 02 0F 07 00 0D
- Hex 2 = 1 2 F 7 0 D
- Hex 3 = 1 2 f 7 0 d
- Hex 4 = 01 2 f 07 0 d

All of the four Hex codes above have a unique output:

- Hex = 01 02 0F 07 00 0D

## Navspark Tab

### Introduce

### Hardware connect

Type	ESPrtk pin name	NS-HP-BD NS-HP-GL NS-HP-GN  PX1120R	PX1122R	NS-HP-xx	Other Navspark modules
UART	TX_UART1	RX_UART_1	RX_UART_1	RX_UART_1	RX UART-config
UART	RX_UART1	TX_UART_1	TX_UART_1	TX_UART_1	TX UART-config
UART	TX_UART2	RX_UART_2	RX_UART_2	RX_UART_2	RX UART-config
UART	RX_UART2	TX_UART_2		TX_UART_2	TX UART-config



## Support function

Communicate	Support
UART1 / UART2 Switch + Multi baudrate + Auto scan baudrate Navspark device	●
Automatically detect errors of input data.	●

	Binary - Configure function	Support	Binary - Query function	Support
0	Configure Serial Port	●	Query Software Version	●
1	Configure Message Type	●	Query CRC Checksum Version	●
2	Configure Pinning Parameters	●	Query SHA1 String	○
3	Configure NMEA Message Interval	●	Query NMEA Message Interval	●
4	Configure Binary Message Interval	●	(blank)	
5	Configure Position Update Rate	●	Query Position Update Rate	●
6	Configure Position Pinning	●	Query Position Pining	●
7	Configure Power Mode	●	Query Power Mode	●
8	Configure DOP Mask	●	Query DOP Mask	●
9	Configure Elevation and CNR Mask	●	Query Elevation and CNR Mask	●
10	(blank)	●	Query GLONASS K-Number, Slot, CNR	○
11	Configure NMEA Talker ID	●	Query NMEA Talker ID	●
12	Configure NMEA Output Comport	○		
	Venus 8 - Configure function	Support	Venus 8 - Query function	Support
0	Configure SBAS	●	Query SBAS	●
1	Configure SBAS Advance	○	Query SBAS Advance	○
2	Configure SAEE	●	Query SAEE	●
3	Configure QZSS	●	Query QZSS	●
4	Configure DGPS	○	(blank)	
5	Configure Interference Detect Control	●	Query Interference Detect Control	●
6	Configure Parameter Search Engine Number	●	Query Parameter Search Engine Number	●
7	Configure Position Fix Navigation	●	Query Position Fix Navigation	●



	Mask		Mask	
8	Configure Navigation Mode	●	Query Navigation Mode	●
9	Configure GNSS Constellation Type	●	Query GNSS Constellation Type	●
10	Configure GPS/UTC Leap Seconds	●	Query GPS Time	●
11	Configure Parameter Search Engine Sleep Criteria	○	Query Parameter Search Engine Sleep Criteria	○
12	Configure Datum Index	●	Query Datum Index	●
13	Configure Kernel Very Low Speed		Query Kernel Very Low Speed	○
14	Configure PSTI Interval	●	Query PSTI 004 Interval	●
15	Configure PSTI Interval	●	Query PSTI 007 Interval	●
16	Configure PSTI Interval	●	Query PSTI 020 Interval	●
17	Configure PSTI Interval	●	Query PSTI 030 Interval	●
18	Configure PSTI Interval	●	Query PSTI 032 Interval	●
19	Configure PSTI Interval	●	Query PSTI 033 Interval	●
20	Configure PSTI Interval	●	Query PSTI 060 Interval	●
21	Configure PSTI Interval	●	Query PSTI 063 Interval	●
22	Configure PSTI Interval	●	Query PSTI 065 Interval	●
23	Configure PSTI Interval	●	Query PSTI 067 Interval	●
24	Configure PSTI Interval	●	Query PSTI 068 Interval	●
35	Configure PSTI Interval	●	Query PSTI 070 Interval	●
36	Configure Custom PSTI from 000 to 255 Interval	●	Query Custom PSTI Interval	○
	<b>Phoenix - Configure function</b>	<b>Support</b>	<b>Phoenix - Query function</b>	<b>Support</b>
0	Config Phoenix Tag	○	Query Phoenix Extended ID	○
1	Configure Custom NMEA string Interval	●	Query Custom NMEA String Interval	○
2	Configure NMEA string Interval	●	Query GGA NMEA String Interval	●
3	Configure GNS NMEA String Interval	●	Query GNS NMEA String Interval	●
4	Configure GSA NMEA String Interval	●	Query GSA NMEA String Interval	●
5	Configure GSV NMEA String Interval	●	Query GSV NMEA String Interval	●
6	Configure GLL NMEA String	●	Query GLL NMEA String	●



	<b>Interval</b>		<b>Interval</b>	
7	<b>Configure RMC NMEA String Interval</b>	●	<b>Query RMC NMEA String Interval</b>	●
8	<b>Configure VTG NMEA String Interval</b>	●	<b>Query VTG NMEA String Interval</b>	●
9	<b>Configure ZDA NMEA String Interval</b>	●	<b>Query ZDA NMEA String Interval</b>	●
10	<b>Configure DTM NMEA String Interval</b>	●	<b>Query DTM NMEA String Interval</b>	●
11	<b>Configure GBS NMEA String Interval</b>	●	<b>Query GBS NMEA String Interval</b>	●
12	<b>Configure GRS NMEA String Interval</b>	●	<b>Query GRS NMEA String Interval</b>	●
13	<b>Configure GST NMEA String Interval</b>	●	<b>Query GST NMEA String Interval</b>	●
14	<b>Configure THS NMEA String Interval</b>	●	<b>Query THS NMEA String Interval</b>	●
15	<b>Configure HDT NMEA String Interval</b>	●	<b>Query HDT NMEA String Interval</b>	●
<b>RAW - Configure function</b>		<b>Support</b>	<b>RAW - Query function</b>	<b>Support</b>
0	<b>Configure Base Station</b>	●	<b>Query Base Position</b>	○
1	<b>Configure Binary Measurement Data Out</b>	●	<b>Query Binary Measurement Data Out</b>	●
2	<b>Configure RTCM Measurement Data Out</b>	●	<b>Query RTCM Measurement Data Out</b>	●
<b>RTK - Configure function</b>		<b>Support</b>	<b>RTK-Query function</b>	<b>Support</b>
0	<b>Configure RTK Reference Static Started Position</b>	●	<b>Query RTK Mode</b>	●
1	<b>Configure RTK Mode</b>	●	<b>Query RTK And Operational Function</b>	●
2	<b>Configure RTK Mode And Operational Function</b>	●	<b>Query RTK Mode And Operational Function</b>	●
3	<b>Configure RTK Slave Serial Port Baud Rate</b>	●	<b>Query RTK Slave Serial Port Baud Rate</b>	●
4	<b>Configure Precisely Kinematic Base Serial Port Baud Rate</b>	●	<b>Query RTK Precisely Kinematic Base Serial Port Baud Rate</b>	●
5	<b>Configure RTK GLONASS Carrier-Phase Inter-Frequency Bias</b>	○		
<b>1PPS Timing- Configure function</b>		<b>Support</b>	<b>1PPS Timing - Query function</b>	<b>Support</b>



0	Configure 1PPS Timing	●	Query 1PPS Timing	●
1	Configure 1PPS Cable Delay	●	Query Cable Delay	●
2	Configure 1PPS Pulse Width	●	Query 1PPS Pulse Width	●
3	Configure 1PPS Output Mode	●	Query 1PPS Output Mode	●
4	Configure 1PPS Frequency Output	●	Query 1PPS Frequency Output	●
<b>Ephemeris - Configure function</b>		<b>Support</b>	<b>Ephemeris - Query function</b>	<b>Support</b>
0	Configure GPS Ephemeris	○	Query GPS Ephemeris	○
1	Configure GLONASS Ephemeris	○	Query GLONASS Ephemeris	○
2	Configure Beidou Ephemeris	○	Query Beidou Ephemeris	○
3	Configure GPS Almanac	○	Query GPS Almanac	○
4	Configure GLONASS Almanac	○	Query GLONASS Almanac	○
5	Configure Beidou Almanac	○	Query Beidou Almanac	○
6	Configure GLONASS Time Corrections	○	Query GLONASS Time Corrections	○
<b>Pro Configure - Configure function</b>		<b>Support</b>	<b>Pro Configure - Query function</b>	<b>Support</b>
0	Hex Payload Configure	●		

## To use

Connect UART port as table above.

- 1- First, start connecting to the module with a baudrate.
- 2-Use "Autoscan Baudrate" to scan if dont know baudrate.
- - To check the response from module Navspark, you can send "Query Software Version".
- 3-Select configure function , select your configure item , press SEND configure .

### TIP :

- Wait a moment after changing the baudrate.
- Do not click too quickly (after configure, you need wait a moment).
- Items marked with '\*' are not supported yet.
- Scroll the Configure tab to see the full component.
- When you see the error [Module respond NACK (just not accept, please choose another option)], it means that the connection is successful and correct baudrate, but the configure value is invalid, you need to check the valid values of that module.



## ESPrTk - Hex configure Navspark tool

This function allows users to configure Navspark modules with Hex code.

(These codes are the PAYLOAD part in the communication frame to configure Navspark's module, can find the communication frame at the configuration documents).

ESPrTk also supports syntax errors filter , error alerts, data dumps, auto-sending ...

The input field has the format:

Input field format
<Configuration Name> - <Hex code> <Enter>

For example:

[NMEA_Message_Interval] - 08 01 01 01 01 01 01 00 00
[NMEA_Message_Interval] - 08 01 01 01 01 01 01 00 00

Check input:

- Configuration name and Hex code are separated by dashes: '-'.
- Each hex value must be separated by a space.
- The configuration commands must be separated by new lines (enter).
- A Byte Hex must contain at least 1 characters (and no more than 2 characters).
- Irrespective of uppercase and lowercase letters.

For example, all four ways below are valid and have the same output:

- Hex 1 = 01 02 0F 07 00 0D
- Hex 2 = 1 2 F 7 0 D
- Hex 3 = 1 2 f 7 0 d
- Hex 4 = 01 2 f 07 0 d

All of the four Hex codes above have a unique output:

- Hex = 01 02 0F 07 00 0D



## GNSS Viewer Tab

### Introduce

### Hardware connect

Type	ESPrTk IO name	IMU -MPU9250	Ublox module	Navspark module	Other GNSS modules
I <sup>2</sup> C	SCL_I2C	SCL I <sup>2</sup> C	-	-	-
I <sup>2</sup> C	SDA_I2C	SDA I <sup>2</sup> C	-	-	-
UART	TX_UART1	-	RX_UART_1	RX_UART_1	RX UART
UART	RX_UART1	-	TX_UART_1	TX_UART_1	TX UART – NMEA/RTCM Output
UART	TX_UART2	-	RX_UART_2	RX_UART_2	RX UART
UART	RX_UART2	-	TX_UART_2	TX_UART_2	TX UART – NMEA/RTCM Output

### Support function

Hardware communicate	Support
UART1 / UART2 Switch + Multi baudrate	●

	GNSS Viewer tool	IMU Viewer tool
1	Information Table	3D Model Xbox view+ Bias
2	GPS Sattelite View	3D Model F117 view+ Bias
3	BEIDOU Sattelite Signal View	Euler Angle graph view
4	GLONASS Sattelite View	Gyroscope graph view
5	GPS Sattelite Sky View	Accelerometer graph view
6	BEIDOU Sattelite Sky View	Euler Angle chart view
7	GLONASS Sattelite Sky View	Gyroscope chart view
8	Position Viewer Tool	Accelerometer chart view

### To use

Connect the RX-UART1 port to the TX output of the GNSS device.

- 1- First, Select connection baudrate and screen update frequency then press connect.



- Wait in 5 second until NMEA/RTCM information show/draw on page.

**TIP :**

If the input is NMEA, the following messages will be parse: RMC-GLL-GGA – GSA-ZDA-VTG-GSV.  
 If the input is RTCM, ESPrtk 3.0.0 currently can only detect RTCM 3.x and show at “Message Type Parse “ box but does not really resolve it because it is not fully supported yet.

## Profile Tab

### Introduce

### Hardware connect

Type	ESPrtk IO name	IMU -MPU9250	SD Card
I <sup>2</sup> C	SCL_I2C	SCL I <sup>2</sup> C	-
I <sup>2</sup> C	SDA_I2C	SDA I <sup>2</sup> C	-
SPI	MOSI_SD_Card	-	MOSI
SPI	MISO_SD_Card	-	MISO
SPI	SCK_SD_Card	-	SPI Clock
SPI	CS_SD_Card	-	Chip Select

### Support function

Communicate	Support
Automatically detect errors of input data.	●

	Function tab	UI Write configure for	UI Auto Read configure	Other UI Tools
0	Create new profile			
1	Login / Logout			
2	Your profile	YOUR_PROFILE	●	
3	Action Planning	ACTION_PLANNING	●	
4	Internet - RTK Online	INTERNET	●	
5	Radio - RTK OFFline	RADIO_RTK	●	
6	MQTT RTK	MQTT_RTK	●	



7	<b>NTRIP Client</b>	<b>NTRIP_CLIENT</b>	●	<b>Mountpoint Table Insert</b>
8	<b>NTRIP Master</b>	<b>NTRIP_MASTER</b>	●	
9	<b>UART Configure</b>	<b>UART_CONFIGURE</b>	●	<b>Command Tester Tool</b>
10	<b>Bluetooth</b>	<b>BLUETOOTH</b>	●	
11	<b>Display viewer</b>	<b>DISPLAY_VIEWER</b>	●	
12	<b>Log File-Events</b>	<b>EVENT_LOG</b>	●	<b>Event log Decoder</b>
13	<b>Simple Debug</b>	<b>SIMPLE_DEBUG</b>	●	<b>Convert ID_Error to Text</b>
14	<b>SD Card Logger</b>	<b>SD_CARD</b>	●	
15	<b>IMU-MPU9250</b>	<b>IMU_MPU9250</b>	●	<b>Calibration IMU Helper</b>
16	<b>GSM 2G-3G-4G-LTE</b>	<b>GSM_CELLULAR</b>	●	<b>GSM - ATCode Edit + Decoder</b>
17	<b>Stream Manager Remove+Insert+Add</b>	<b>STREAM_MANAGER</b>	●	<b>STREAM - AT Code Edit + Decoder</b>
18	<b>Position+Antenna</b>	<b>POSITION_ANTENNA</b>	●	

### **NTRIP Client - Mountpoint Table Insert tool.**

This function automatically updates and provides a mountpoint list with basic information of Basestation in the form of resolved data tables. Users only need to select from the list, the mountpoint name will be filled automatically. The function will also automatically detect and suggest entering additional information such as Password, position, ... if that NTRIP service requires.

The sourcetable data storage size on ESPrTk is up to 200 Kbytes. ( If the data is too large, some data of the end will be remove ).

### **UART Configure – Command Tester tool.**

One of the special features available on version 3.0.0.

This function simulates a virtual UART port and an INUPUT / OUTPUT window similar to the Serial Terminal software running on a PC.



This function is used to practice or configure ESPrtk directly using the ESPrtk command (those used in UART Configure).

Users can also use this function to read all configuration information or configure all in one click.

The support:

- Automatically detect message frame errors and propose corrections.
- Automatic separation, sending and counting of successful message frames.
- Supports all **Command Read Configure ESPrtk** . ( see detail ID Commands above)
- Support all **Command Write Configure ESPrtk**. ( see detail ID Commands above)
- Support encryption framework \$ ESS\_xx and \$ AES\_xx (BITWISE and AES256).
- Supports some basic control commands.

PL0	Type Command	WEB Configure Mode Support ?- Command Tester Tool
'N'	Start WEB Configure mode	●
'O'	Start UART Configure mode	●
'X'	Start Main Action mode	●
'P'	PING to ESPrtk	●
'Q'	Quit UART Configure mode and jump to Main Action mode	○
'R'	Read data configure on ESPrtk	●
'W'	Write configure to ESPrtk	●
'E'	Export configure as example	●
'T'	Hardware control	○
'T'	Hardware control (Control type PRINT output on TX_UART0 )	●
'T'	Hardware control (Control GPIO ESPrtk )	●
'R'	Request ERROR_SYSTEM	●



## **Log File-Events - Event log Decoder tool.**

The best way to see the status of ESPrtk is to collect TX-UART0 output data, the purpose of this is to find the error and fix it.

However, this requires a continuous connection from ESPrtk to the terminal display device, and will make it difficult for users without the necessary tools, or distance obstacles.

Event Log will overcome that disadvantage.

When the Eventlog is activated, during operation, data about the operation, error status, .. will be recorded in a file named Event\_Log.bin and stored forever until the user delete it.

During operation, users can stop the program whenever they feel that collecting data for the Event\_Log file is enough, then they can check the Event\_Log file to see what happened on ESPrtk, (or how ESPrtk works until now).

Users can also download this file to store or share with everyone.

The Event\_Log file will be limited by the maximum allowable size.

Users can select data collection targets. For debugging should activate all.

If Event\_Log is enabled, it starts to record the status from the time ESPrtk is restarted (power on or press the Reset button) until the user turns off the power (or press the Reset button).

Now, in ESPrtk, there exists an Event\_Log.bin file, users can open Webconfigure, go back to the Event Log tab and click on the READ File button to extract the file, need to wait for a while (60s longest) for a series of Information will be displayed below.

The user can then download this file or need to delete the file by clicking Clear File to allow a new recording process at the next operation.

### **Note:**

Activating Event\_Log will cause memory resources on ESPrtk to be used (depending on the maximum size allowed from 5Kbyte to 50Kbyte).

The process of extracting Event\_Log.bin file sometimes takes a lot of time because of the large size.

The Event\_Log.bin file will not contain sensitive installation information in the Profile such as passwords, IDs, host servers, ...

The file Event\_Log.bin is not encrypted protected, it is just a zip file, it is open source and can be read normally from the mapping table to extract it. Its data is the result of the active log collection process on ESPrtk and is not involved in ESPrtk's operational configuration.

You can share this file with everyone.

## **Simple Debug - Convert ID \_Error to Text tool.**

When you collect the ID of the error on ESPrtk (ID number or color seen on Neopixel), you can decode it using this simple tool to see what error has occurred.

After logging in, open the Simple Debug tab, enter the error ID or select the neopixel strip color in order (1-2-3-4).

Press "See error", the page will print an error in the form of text and suggest how to fix it.



This is just the simplest debug tool, sometimes it will help you when you can't contact anyone to get help.

### IMU-MPU9250 - Calibration IMU Helper tool.

This tool allows users to collect raw and calibrated magnetometer data of the IMU sensor to assess the quality of the raw or calibrated magnetometer using the conversion matrix.

To use this function, connect the MPU9250 sensor to the I2C port of ESPrTk.

The support:

- Export raw and calibrated data simultaneously on all 3 X-Y-Z axes.
- Support to configure the output data format according to the purpose of the user.
- Display points and interact with 3D graphics.
- Support compressing data file into .txt or .svc file for download.
- Automatic stop by preset size limit.

## About Tab

### Introduce

### Support function

<b>Other UI Tools</b>
<b>Request ESPrTk information</b>

## System Tab

### Introduce

### Support function

<b>Function tab</b>	<b>UI Write configure for</b>	<b>UI Auto Read</b>	<b>Other UI Tools</b>
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			configure	
0	ESPrtk Custom Pin Map	GPIO_PIN_MAP	•	Input GPIO pin map as JSON string
1	Setting system	SYSTEM_Other_Mode	•	

### Input GPIO pin map as JSON string tool.

This is a special feature and it is hidden when accessed in the Web Config.

To be able to access this page, after the login Profile, type [192.168.4.1/system](http://192.168.4.1/system) to enter System page.

This page showing with a black background interface , users can drag and drop ESP32 pins into the frame corresponding to ESPrtk. Click “Save” button to save the configuration.

Or user can enter the JSON string into the text field and click “Save as JSON” to save the configuration.

After that, ESPrtk will check the logic, if there is no error, it will print “Config GPIO save success” in the Submit status box.

At the same time, it export a JSON string, clicks “Copy output” to save it in Clipboard as text and paste it anywhere.

Configure data will store in FLash in ESP32 .

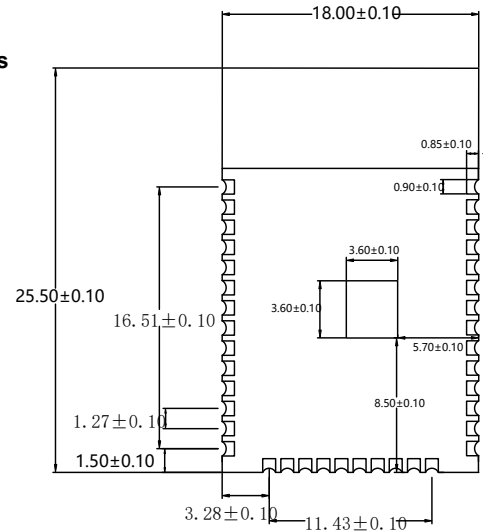
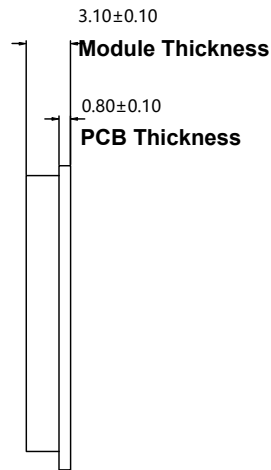
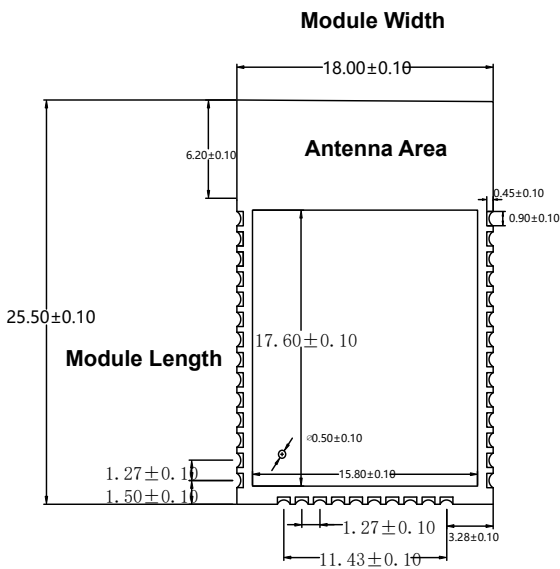
After restarting , GPIO configuration information will be printed on the Serial port (TX\_UART0 baud 230400) and load this configure to all function before main program start.



# Physical Dimensions

## ESP32-WROOM-32D DIMENSIONS

Unit: mm



Top View

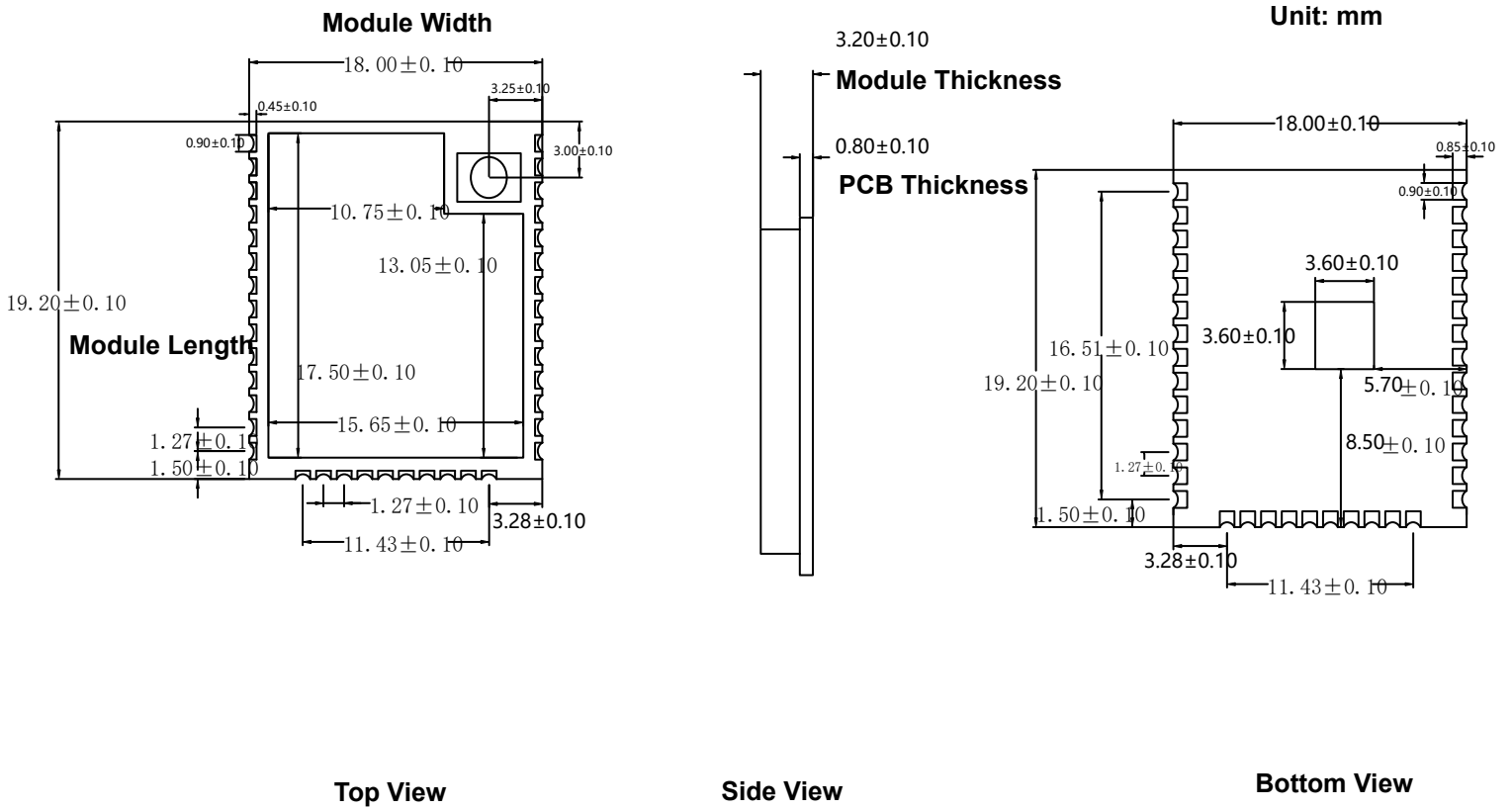
Side View

Bottom View

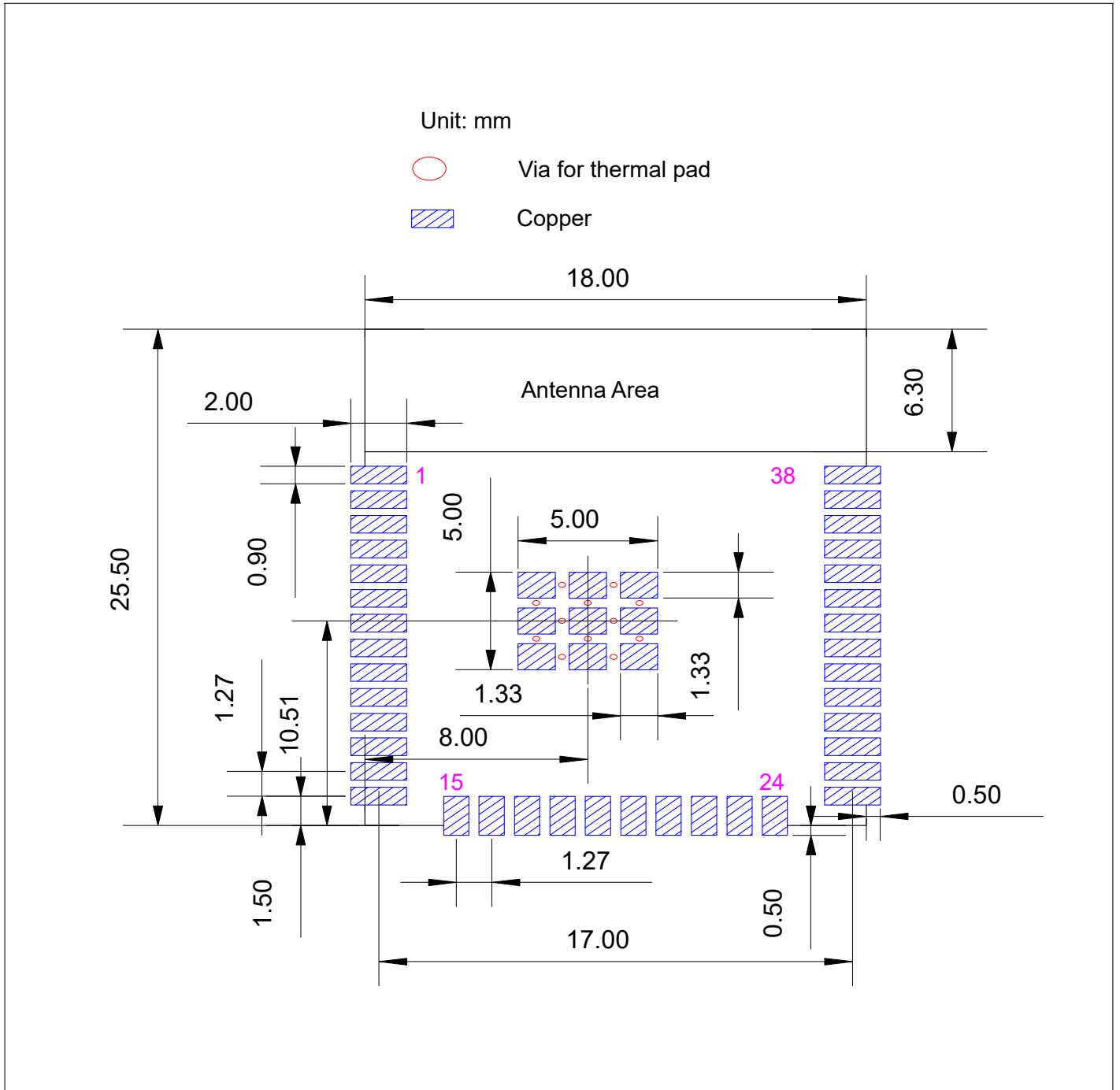
Physical Dimensions of ESP32-WROOM-32D/E



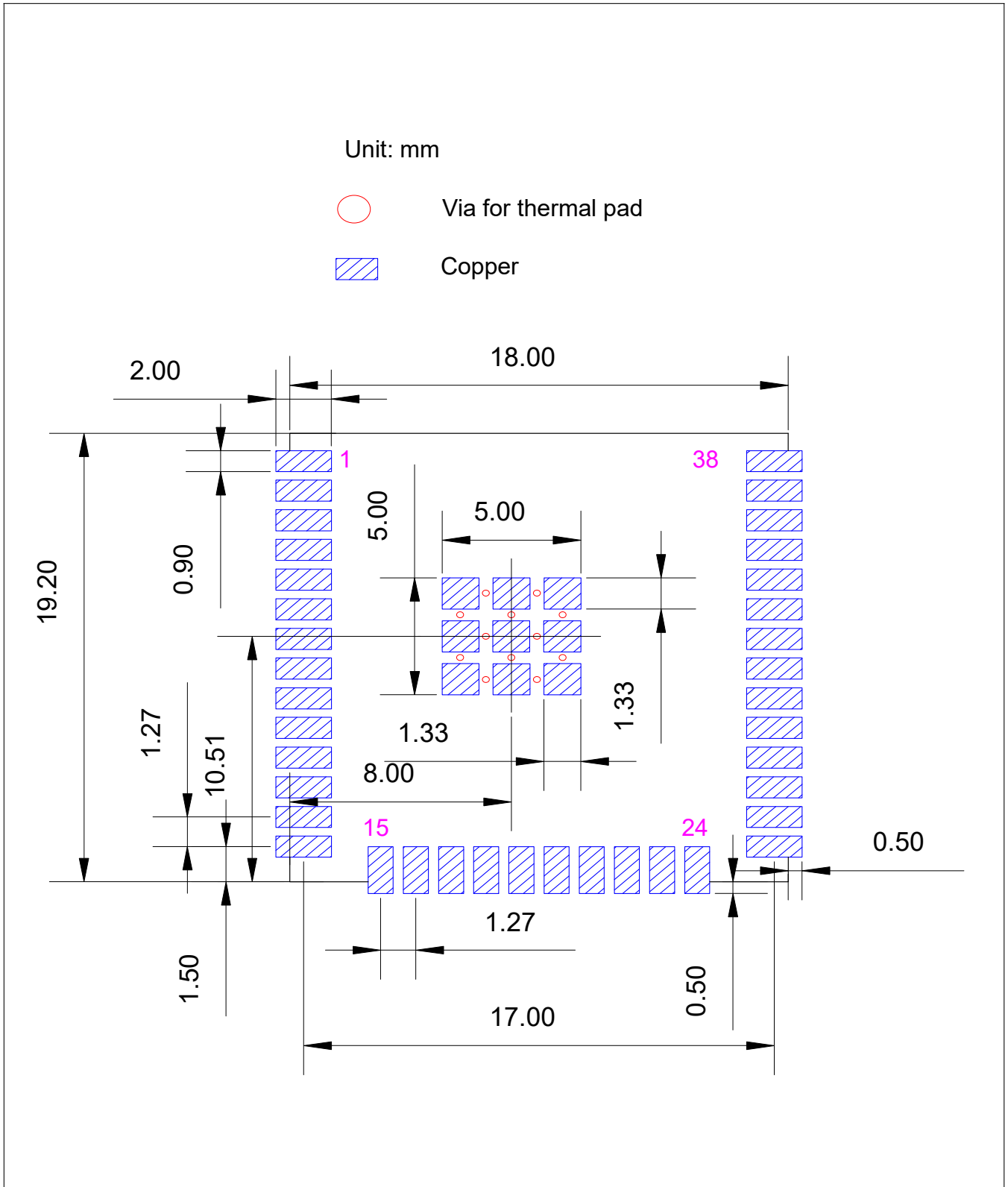
### ESP32-WROOM-32U DIMENSIONS



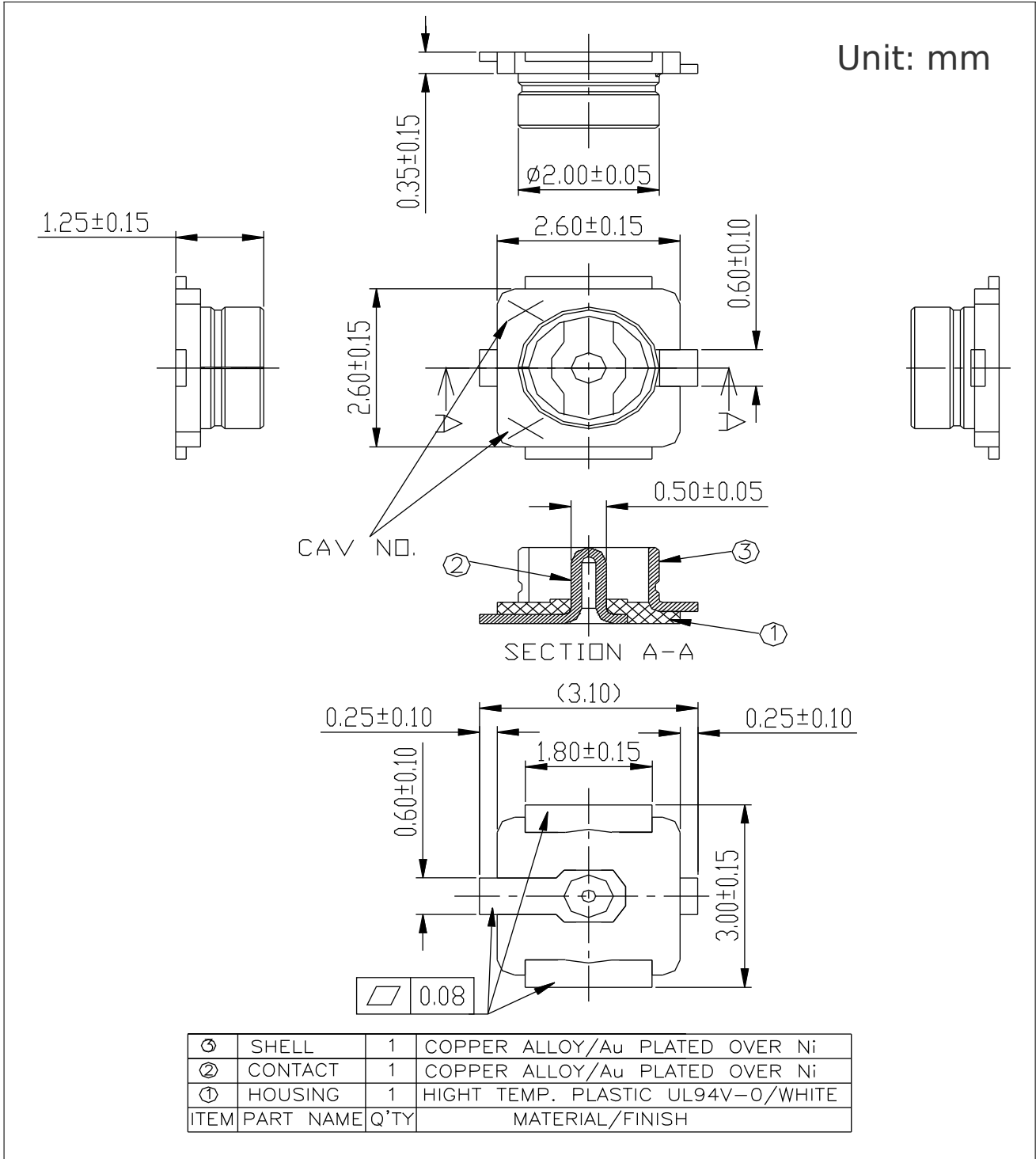
Physical Dimensions of ESP32-WROOM-32U/UE



Recommended PCB Land Pattern of ESP32-WROOM-32D/E



Recommended PCB Land Pattern of ESP32-WROOM-32U/UE



ESP32-WROOM-32U/UE U.FL Dimensions